## EQUIVARIANT RECOGNITION PRINCIPLE

MIT/Harvard Babytop Seminar, Spring 2025 Tuesday, April 29th, 2025 LiveT<sub>F</sub>X by Howard Beck

Abstract. Speaker: Branko Juran (Copenhagen)

**Disclaimer**: Do not take these notes too seriously, sometimes half-truths are told in exchange for better exposition, and there may be errors in my liveT<sub>E</sub>Xing

## 1. INTRODUCTION

X based space, we can attach homotopy groups  $\pi_n(X)$ , and it is a group when  $n \ge 1$  and is further abelian when  $n \ge 2$ . The group structure comes from a structure  $\Omega^n X = \text{Map}_*(S^n, X)$ . This space is called an  $\mathbb{E}_n$ -algebra.

There is a category  $Disk_n$  of *n*-dimensional disks and framed embeddings, with disjoint unions.

**DEFINITION 1.1.** An  $\mathbb{E}_n$ -algebra is:

$$\operatorname{Alg}_{\mathbb{E}_n}(\mathcal{C}) = \operatorname{Fun}^{\otimes}(\operatorname{Disk}_n, \mathcal{C})$$

⊲

⊲

where C is a symmetric monoidal  $\otimes$ -category.

The recognition principle says that the  $E_n$ -algebra structure retains the deloopings.

We can ask whether all  $E_n$ -algebras in spaces are *n*-th loop spaces. Not all are - in fact, the only obstruction is that we need  $\pi_0$  to be a group, instead of just a monoid.

**DEFINITION 1.2.** An E<sub>n</sub>-algebra in spaces A is called group-like if  $\pi_0(A)$  is a group.

**THEOREM 1.3** (Recognition Principle, May-Segal). There is an equivalence of categories:

 $(\text{Spaces}_*)_{>n} \xrightarrow{\sim} \text{Alg}_{\text{E}_n}^{\text{gp}}(\text{Spaces})$ 

of *n*-th connected based spaces and group-like  $E_n$ -algebras in spaces.

## 2. Equivariant Setting

Let *G* be a finite group.

In equivariant homotopy theory, we have loop spaces indexed not by integers but by representations. Thus, we also fix a finite-dimensional real *G*-representation.

We have the *V*-fold loop space of a *G*-space  $X \in \text{Spaces}^G$ :

$$\Omega^V X = \operatorname{Map}_*(S^V, X)$$

where  $S^V$  is the representation sphere of V - its one-point compactification.  $\pi_0$  of this is the V-th homotopy group.

To make an analogous theory, we will need G-symmetric monoidal G-categories.

We want to construct *G*-spaces.

Idea: we want to model topological spaces with an action of *G*.

Here is an attempt: Spaces<sup>BG</sup>. This is called Borel-equivariant, but is not good enough – we cannot take arbitrary fixed points.

**DEFINITION 2.1.** Let the **orbit category**  $\mathcal{O}_G$  be the category of finite transitive *G*-sets. In other words, these are *G*/*H* for some subgroups  $H \subset G$ . *G*-spaces are given by:

Spaces<sup>G</sup> = Fun
$$(\mathcal{O}_{G}^{op}, S)$$

where we send G/H to  $X^H$ .

**DEFINITION 2.2.** A *G*-category is  $\mathcal{O}_G^{\text{op}} \to \text{Cat.}$ 

**Example 2.3.**  $G/H \mapsto \text{Spaces}^H$ 

**EXAMPLE 2.4.** For V a G-representation, we can take  $\text{Disk}_V^H$  to be the category of H-disks framed in  $\text{Res}_H^G V$  and embeddings.

For example, you can take the free embedding of two disjoint disks (with the  $C_2$  action) into the disk with a  $C_2$  action via the sign representation.

For a symmetric monoidal structures, we need norms

**DEFINITION 2.5.** For a commutative monoid  $X \in \mathsf{CMon}(\mathsf{Top})$  with a *G*-action, we get a map:

$$M^e \to M^G$$
$$m \mapsto \sum_{g \in G} g \cdot m$$

This should be part of the definition.

**RECALL 2.6.** The category of symmetric monoidal categories:

$$Cat^{\otimes} = CMon(Cat) = Fun^{II}(Span(FinSet), Cat)$$

Span(FinSet) has objects finite sets and morphisms  $S \leftarrow T \rightarrow S'$ . Because this is product preserving:

$$\langle 1 \rangle \mapsto \mathcal{C} \\ \langle n \rangle \mapsto \mathcal{C}^n$$

We have a special morphism  $\langle 2 \rangle = \langle 2 \rangle \rightarrow \langle 1 \rangle$ . The map  $C^2 \rightarrow C$  is multiplication.

**DEFINITION 2.7.** A *G*-symmetric monoidal *G*-category is this but with *G*-sets:

 $\operatorname{Fun}^{\prod}(\operatorname{Span}(\operatorname{Fin}\operatorname{Set}_G),\operatorname{Cat})$ 

*G/H* goes to some category  $C^H$ , and these can be chosen freely. The rest are built from products (disjoint unions).

There is the span  $G/e = G/e \rightarrow G/G$  that gives you:

$$\mathcal{C}^e \xrightarrow{\mathsf{Nm}^G_e} \mathcal{C}^G$$

This is called a **norm map** and is just part of the data.

We can also compose spans like this:



We get that:

$$\operatorname{Res}_{e}^{G}\operatorname{Nm}_{e}^{G}(x) \simeq \bigotimes_{g \in G} gx$$

 $(in C^e)$ 

**∇** 

⊲

⊲

⊲

**EXAMPLE 2.8** (Spaces). The *G*-category with  $\underline{Spaces}^H = Spaces^H$  has a *G*-symmetric monoidal structure for  $K \subset H \subset G$ :

$$Nm_K^H$$
: Spaces<sup>K</sup>  $\rightarrow$  Spaces<sup>H</sup>  
 $X \mapsto Map^K(H, X)$ 

**EXAMPLE 2.9.** We take  $Disk_V$  with norms.

$$\mathsf{Disk}_V^K \to \mathsf{Disk}_V^H$$
$$D \mapsto H \underset{V}{\times} D$$

This is a topological induction, not a representation-theoretic one. Note that *D* is a manifold  $\triangleleft$  **DEFINITION 2.10.** An  $\mathbb{E}_V$ -algebra in *C* (a *G*-symmetric monoidal *G*- $\infty$ -category) is a *G*-symmetric monoidal *G*-functor (preserves all this data) from Disk<sub>V</sub>:

 $\mathsf{Disk}_V \to \mathcal{C}$ 

**EXAMPLE 2.11.**  $\Omega^V X \in \operatorname{Alg}_{\mathbb{E}_V}(\operatorname{Spaces})$ 

For example, take  $G = C_2$  and  $V = \text{sgn. For } X \in \text{Spaces}^{C_2}$ ,  $\Omega^{\text{sgn}} X$  is an  $\mathbb{E}_{\text{sgn}}$ -algebra.

• On underlying:

$$(\Omega^{\text{sgn}}X)^e = \Omega(X^e)$$

is an  $\mathbb{E}_1$ -algebra.

• On *C*<sub>2</sub>-fixed points:

$$(\Omega^{\operatorname{sgn}}X)^{C_2} = \operatorname{Map}_*^{C_2}(S^{\operatorname{sgn}}, X)$$

This is not an  $\mathbb{E}_1$ -algebra, as sgn has no valid pinch map. However, in  $\text{Disk}_{\text{sgn}}^{C_2}$ , we have an object D(sgn) with the  $C_2$  swap action which gets sent to  $\Omega^{\text{sgn}}X$ . We also have  $C_2 \times D(\mathbb{R})$ , which has two disks with the swap action between them.  $D(\mathbb{R})$  gets sent to non-equivariant loops:  $\Omega X^e \times \Omega X^e$  with the  $C_2$ -swap. There is also the disjoint union  $D(\text{sgn}) \coprod \left(C_2 \times D(\mathbb{R})\right)$  which gets sent to the product  $\Omega X^e \times \Omega X^e \times \Omega^{\text{sgn}}X$ . There is an embedding of this into D(sgn). You sent the fixed point to the fixed point, and free orbits to free orbits. We thus get a map  $\Omega X^e \times \Omega X^e \times \Omega^{\text{sgn}}X \to \Omega^{\text{sgn}}X$ . If we take  $C_2$ -fixed points, we get

 $\Omega X^e \times (\Omega^{\operatorname{sgn}} X)^{C_2} \to (\Omega^{\operatorname{sgn}} X)^{C_2} = \operatorname{Map}_{*}^{C_2}(S^{\operatorname{sgn}}, X)$ 

This is the structure the sign loop spaces have - it is a module over  $\Omega X^e$ .

**DEFINITION 2.12.** An  $\mathbb{E}_V$ -algebra in *G*-spaces is called **grouplike** if  $\pi_0(A^H)$  is a group for all  $H \subset G$  such that dim  $V^H \ge 1$  (whenever it makes sense).

**Тнеогем 2.13.** 

$$\operatorname{Alg}_{\mathbb{E}_{V}}^{\operatorname{gp}}(\operatorname{Spaces}) \simeq (\operatorname{Spaces}_{*}^{G})_{>V}$$

*If*  $\mathbb{R} \subset V$ *, this is proven by Guillou-May, Hausach, Rouke-Sanderson.* 

Why  $\mathbb{E}_V$ -algebras?

- V-fold loop spaces
- G-manifolds
- Equivariant factorization homology
- "real" homotopy theory cares about  $G = C_2$  and sgn, such as  $KU_{\mathbb{R}}$ ,  $MU_{\mathbb{R}}$ , and friends.

**PROOF.** Reduce to, for  $X \in \text{Spaces}^G_*$ :

$$\operatorname{Free}_{\mathbb{R}_V}^{\operatorname{gp}} X \simeq \Omega^V \Sigma^V X$$

The hard part is the group-like part - without it, it is much easier.

Non-equivariantly, we have group-completion  $(-)^{gp} \simeq \Omega B(-)$  of a monoid.

⊲

⊲

⊲