# MAS.S61 Wireless & Mobile Sensing

Lecture 2: Fundamentals of Wireless Sensing & Localization

<u>Lecturers</u>
Fadel Adib (<u>fadel@mit.edu</u>)



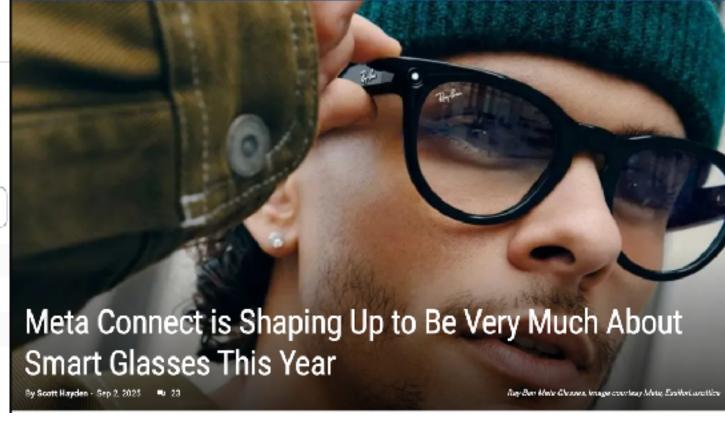
World ∨ Business ∨ Markets ∨ Sustainability ∨ More ∨

#### US FDA clears Apple Watch hypertension feature

By Reuters

September 13, 2025 1:32 AM EDT · Updated September 13, 2025





a new pair of smart glasses with a display, codenamed 'Hypernova' wrist-worn electromyography (EMG) based controller for input

#### Wireless & Mobile Sensing

sensing the physical world & transmitting data wirelessly

sensing via the wireless signals or mobile devices

This lecture

#### Objectives of Today's Lecture

## Learn the fundamentals, applications, and implications of wireless localization and sensing

- 1. What are the unifying principles of wireless positioning & wireless sensing?
- 2. How do systems like GPS, WiFi positioning, seeing through walls work?
- 3. How do state-of-the-art positioning systems work?
- 4. What are the industry opportunities and societal implications of wireless positioning and sensing (today and in the near+far future)?

#### What is Wireless Positioning (aka Localization)?

The process of obtaining a human or object's location using wireless signals

#### **Applications:**

- Navigation: both outdoors (GPS) and indoors (e.g., inside museum)
- Location based services: Tagging, Reminder, Ads
- Virtual Reality and Motion Capture
- Gestures, writing in the air
- Behavioral Analytics (Health, activities, etc.)
- Locating misplaced items (keys)
- Security (e.g., only want to give WiFi access to customers inside a
  - store)
- Delivery drones







#### What are the different ways of obtaining location?

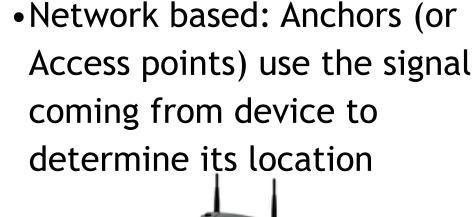
- Radio signals: GPS, Cellular, Bluetooth, WiFi
- Ultrasound signals: similar to those used in NEST
- Inertial
- Cameras, Vision, LIDAR

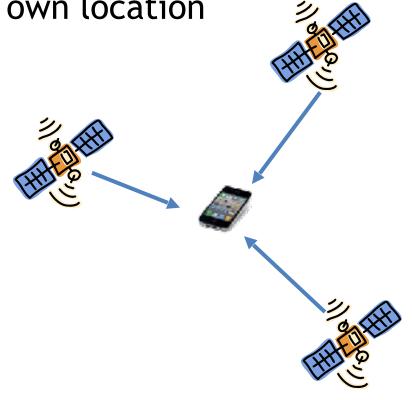
Focus of this lecture

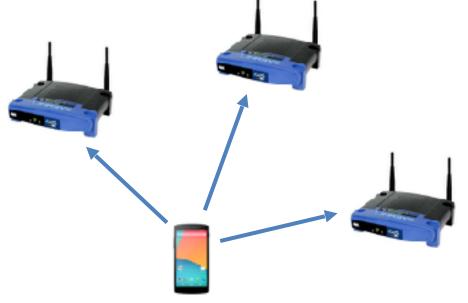
We will discuss the localization techniques in increasing order of sophistication

#### Who performs the localization process?

Device based: A device uses incoming signal from one or more "anchors" to determine its own location







• Example: GPS

Example: Radar

#### 1) Identity-based Localization

Idea: Use the identity and known location of anchor nodes

#### Example:

- Wardriving -- been used to improve the accuracy of GPS
- WiFi indoor localization

Localize by mapping to one of those locations.

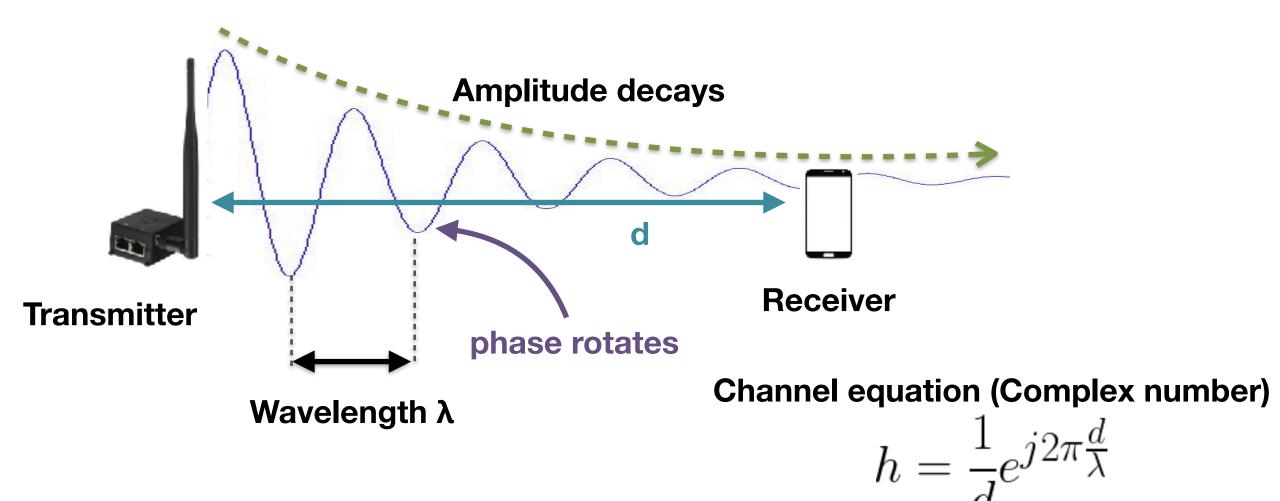
Pros? Cons?

<u>Idea:</u> Higher power -> closer; lower power-> further

In fact, we can extract more information about exact distance from measured power. Need to understand more about wireless signals

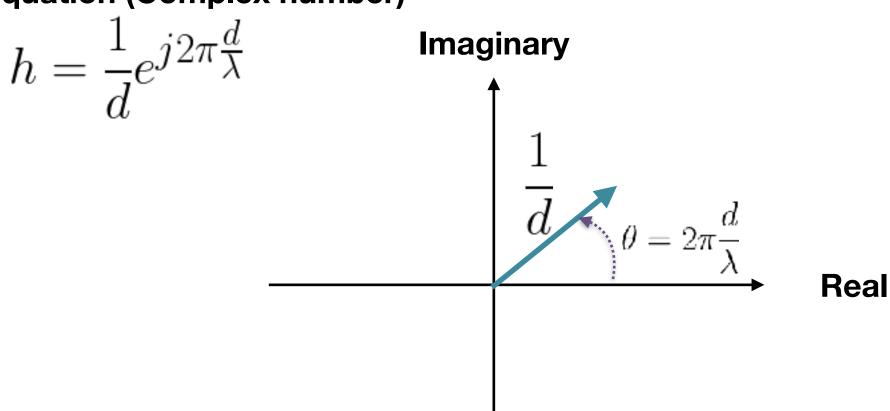
## Wireless Signals are Waves

#### Wireless Signals are Waves



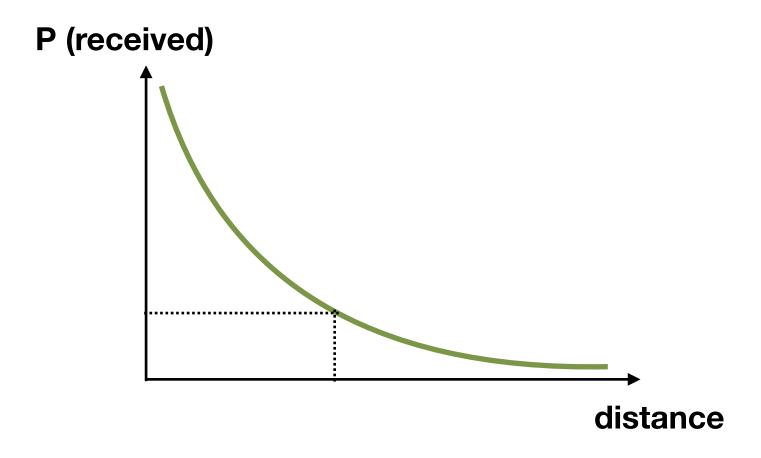
#### Wireless Signals are Waves

#### **Channel equation (Complex number)**

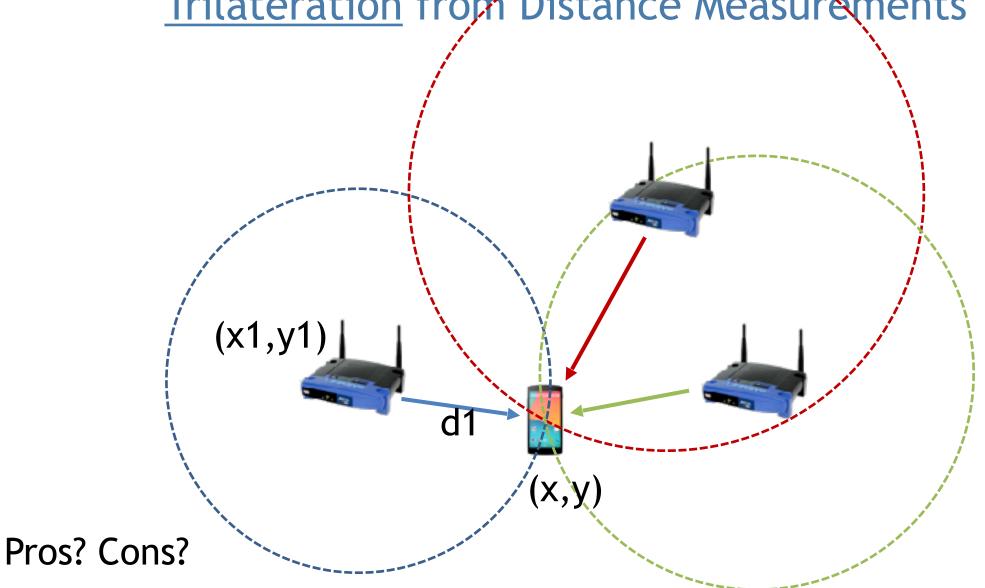


From power to distance

Power is proportional to 1/d<sup>2</sup>

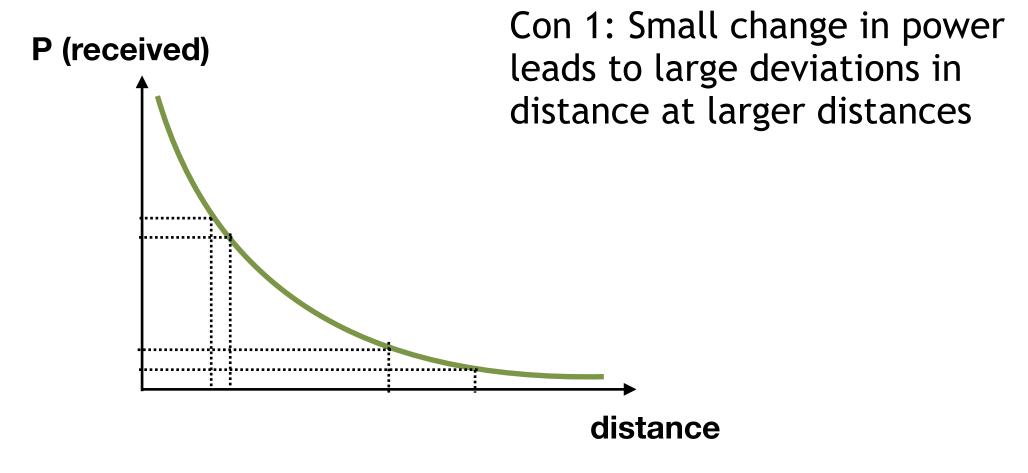


<u>Trilateration</u> from Distance Measurements



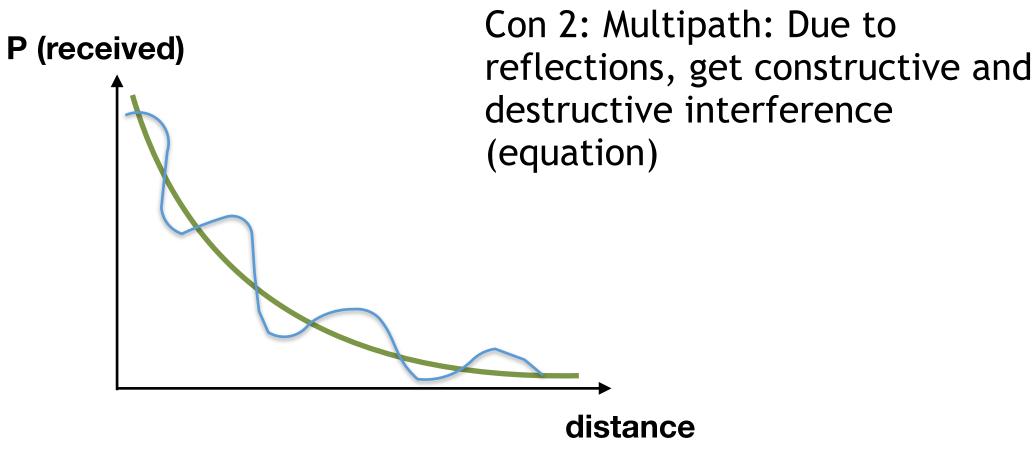
From power to distance

Power is proportional to 1/d<sup>2</sup>



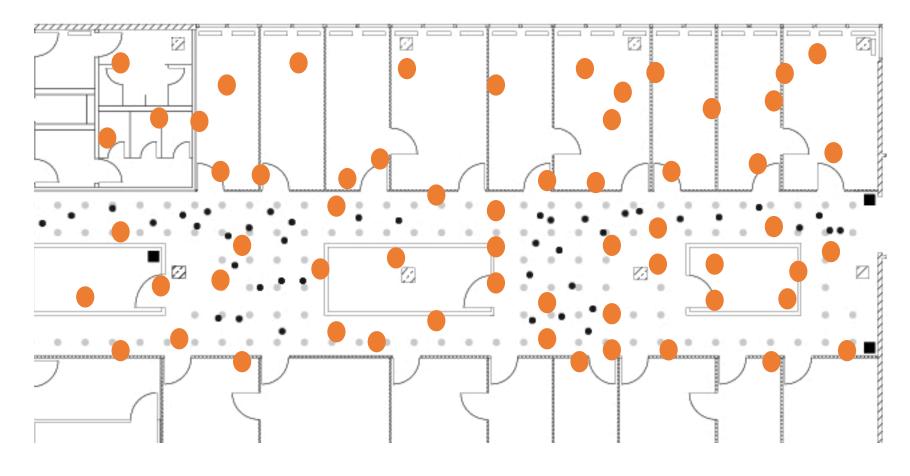
From power to distance

Power is proportional to 1/d<sup>2</sup>



**Solution:** Fingerprinting

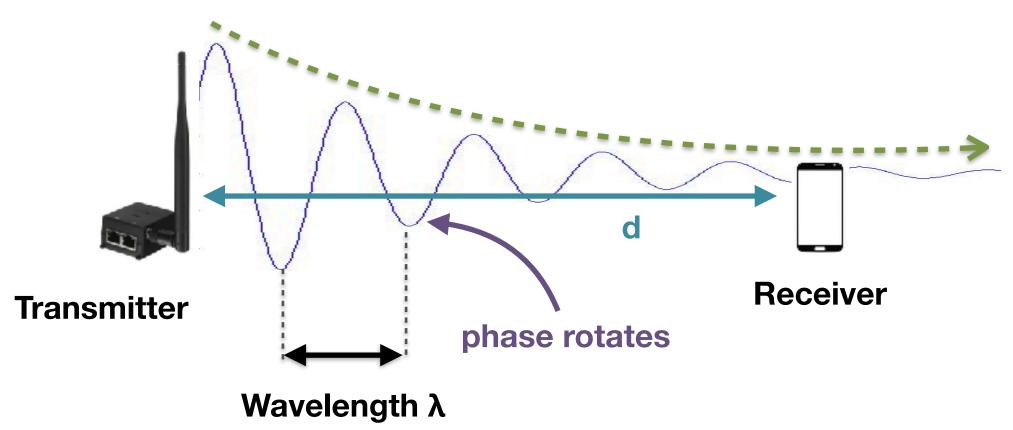
i.e., measuring device records signal strength fingerprints at each location



Pros? Cons?

## 3) Use the Signal "Phase"

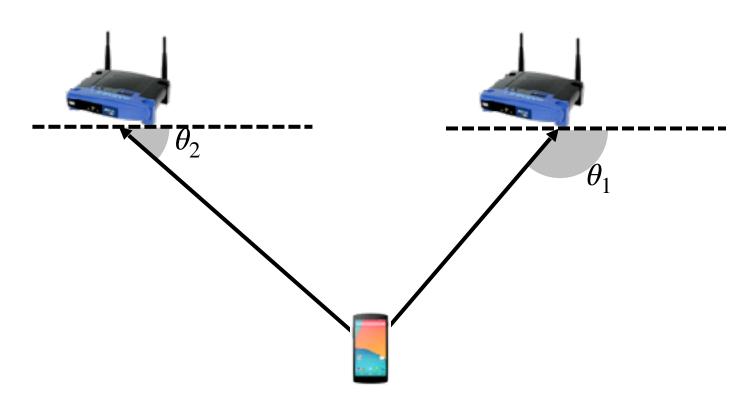
Phase 
$$\phi=2\pi \frac{d}{\lambda}$$



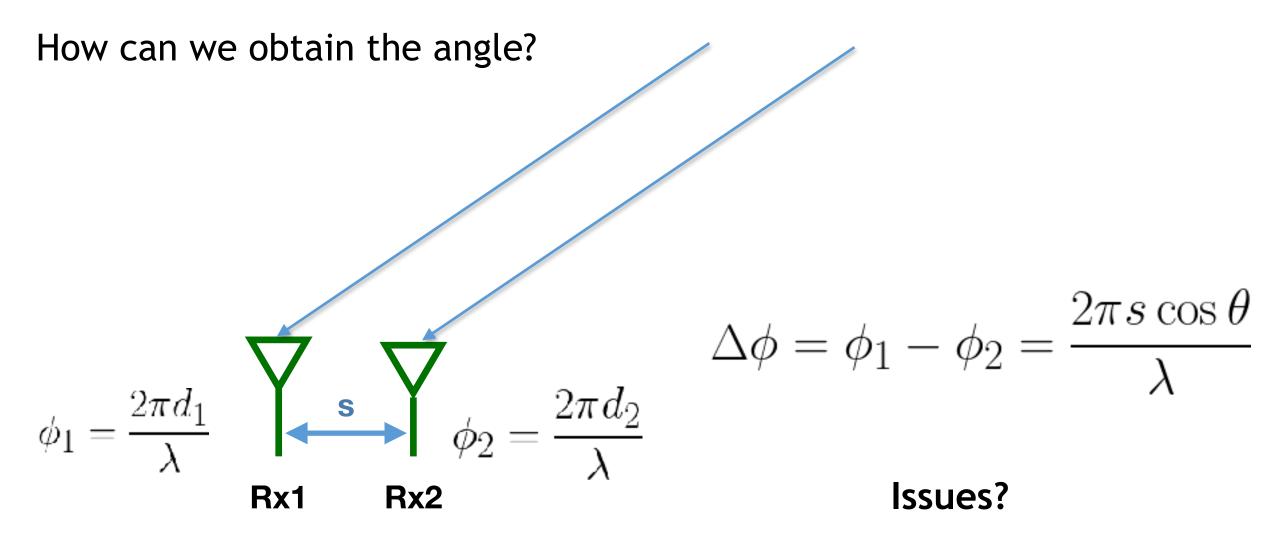
Pros? Cons?

Triangulation from Angular Measurements

Measure Angle of Arrival (AoA) from device to each AP



Triangulation from Angular Measurements

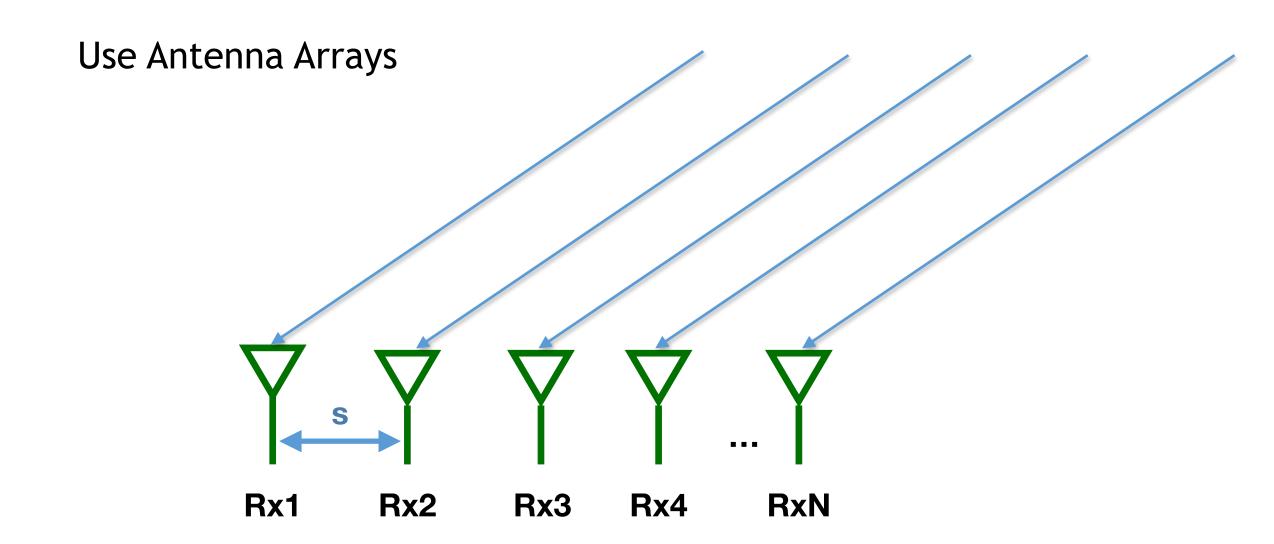


Triangulation from Angular Measurements

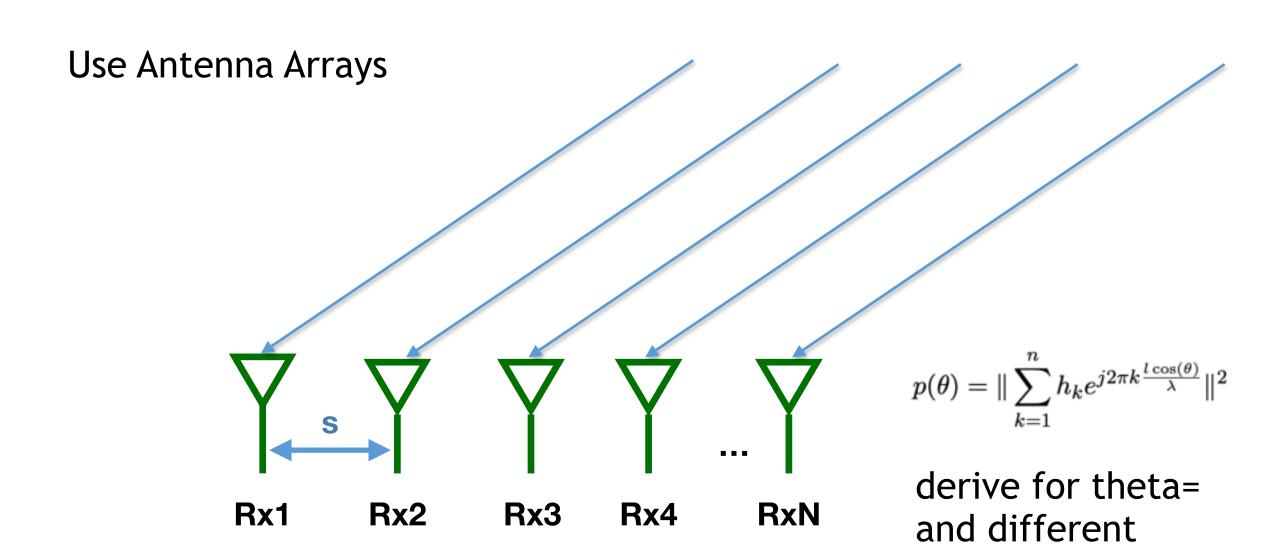
#### Issues

- Multipath
- Nonuniform resolution
- Half-circle vision

Triangulation from Angular Measurements



Triangulation from Angular Measurements



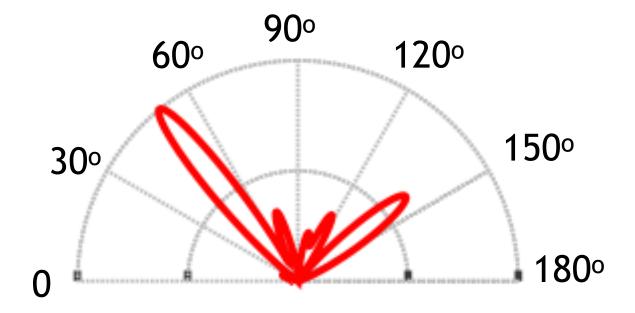
#### Triangulation from Angular Measurements

#### **Use Antenna Arrays**

$$\begin{split} p(\theta) &= \| \sum_{k=1}^{n} h_{k} e^{j2\pi k \frac{l \cos(\theta)}{\lambda}} \|^{2} \\ &= \| \sum_{k=1}^{n} \frac{1}{d_{k}} e^{\Phi_{k}} e^{j2\pi k \frac{l \cos(\theta)}{\lambda}} \|^{2} \\ &= \| \sum_{k=1}^{n} \frac{1}{d_{k}} e^{-2\pi j \frac{d_{1} + (k-1)l \cos(\theta^{*})}{\lambda}} e^{j2\pi k \frac{l \cos(\theta)}{\lambda}} \|^{2} \\ &= \| \sum_{k=1}^{n} \frac{1}{d_{k}} e^{-2\pi j \frac{d_{1} - l \cos(\theta^{*})}{\lambda}} e^{j2\pi k \frac{l}{\lambda} (\cos(\theta) - \cos(\theta^{*}))} \|^{2} \\ &\approx \| \frac{1}{d_{1}} e^{-2\pi j \frac{d_{1} - l \cos(\theta^{*})}{\lambda}} \sum_{k=1}^{n} e^{j2\pi k \frac{l}{\lambda} (\cos(\theta) - \cos(\theta^{*}))} \|^{2} \text{ (approximating } \frac{1}{d_{k}} \text{ by } \frac{1}{d_{1}}) \end{split}$$

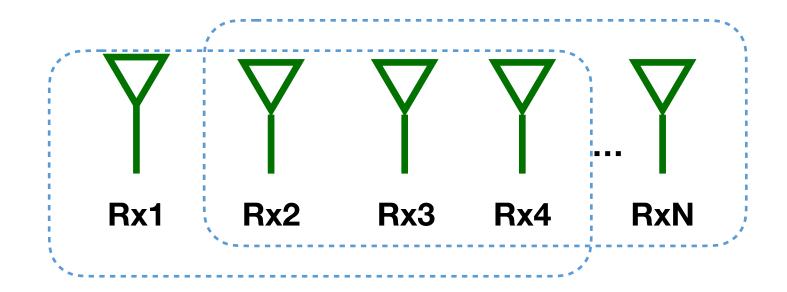
Triangulation from Angular Measurements

Use Antenna Arrays



How do we know which direction corresponds to the direct path?

## ArrayTrack (NSDI'14) deals with Multipath



## 5) Measure the Time-of-Flight (ToF)

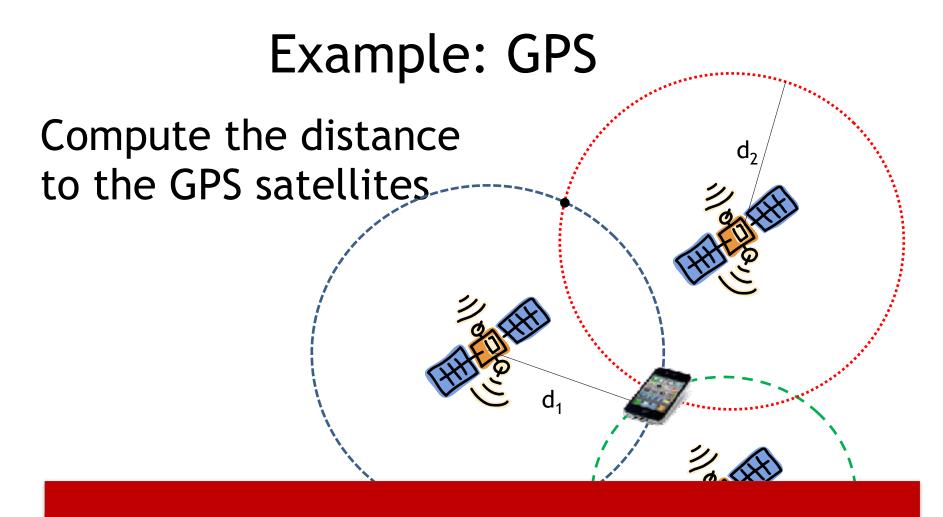


Distance = Time of flight x speed of travel

Can use trilateration (intersection circles/spheres)

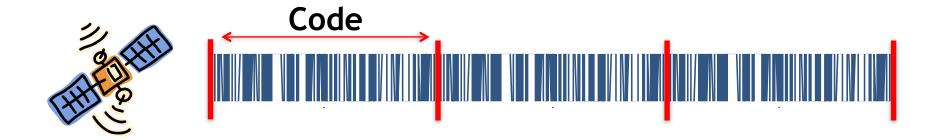
How do we know when the signal was transmitted?

**Transmitter** 



distance = propagation delay x speed of light

#### How to Compute the Propagation Delay?



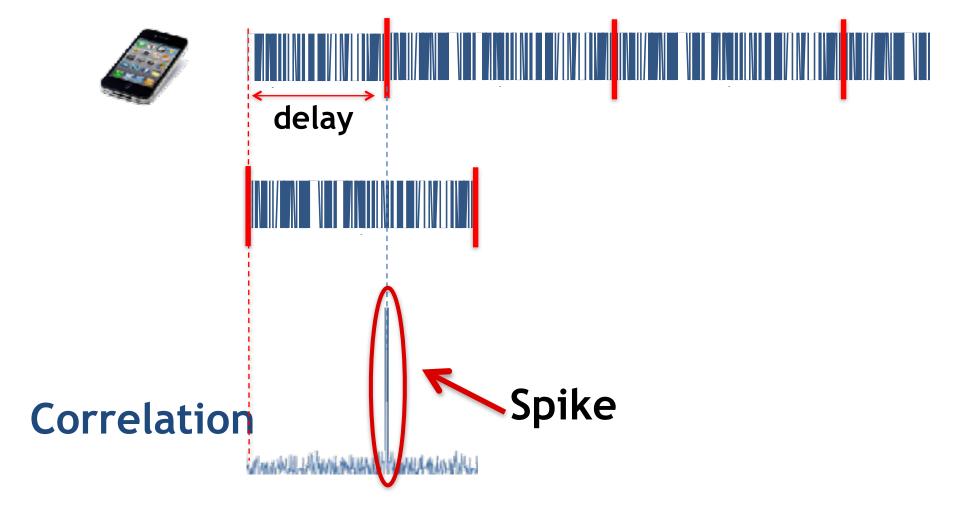
Each satellite has its own code

#### How to Compute the Propagation Delay?



Code arrives shifted by propagation delay

#### How to Compute the Propagation Delay?



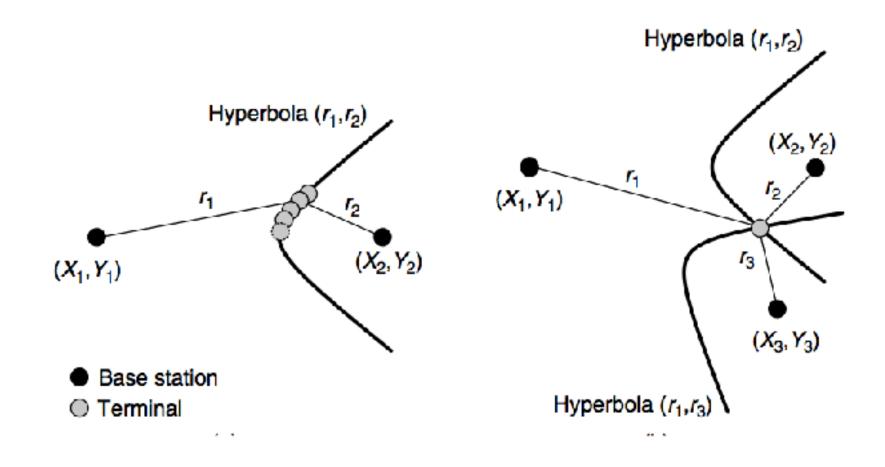
Spike determines the delay use it to compute distance and localize

#### **GPS Data Packet**

- Almanac & ephemeris data
  - Satellite location, clock, orbital parameters, etc.
  - Bitrate?
    - 50 bits/second
  - Takes about 12.5 minutes to download

- How do today's systems use it?
  - A-GPS (Assisted GPS)
  - WiFi APs are mapped war-driving

#### 6) Time-difference-of-arrival (TDoA)



#### State-of-the-Art Techniques?

- Sophisticated Combinations of these techniques, e.g.,:
- Combine AoA with time-of-flight
- Use circular antennas and combine with inertial sensing
- Perform synthetic aperture radar and DTW
- Synthesize measurements from multiple frequencies
- ...

#### **Next Class: Wireless Communications**

#### Required

- The Wireless Channel (Chapter) summary required
- Underwater-to-Air Communications review required