# Analyzing Vulnerability of Electricity Distribution Networks to DER disruptions

Devendra Shelar Saurabh Amin

Massachusetts Institute of Technology

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D. Shelar, S. Amin

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## Outline



2 Vulnerability analysis under DER disruptions

- 3 Solution Approach
- 4 Computational Results

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# Vulnerability analysis & control of distribution networks

#### Questions

- How to assess vulnerability of electricity networks to disruptions of Distributed Energy Resources (DERs)?
- What is the optimal attacker interdiction plan?

#### Approach

Attacker-defender model; Network interdiction formulation; Characterization of worst-case attacks; Defender strategies

#### Results

- Interdiction model captures threats to DERs / smart inverters;
- Structural results on worst case attacks that maximize weighted sum of cost due to loss of voltage regulation and cost of load control;
- Efficient (greedy) technique for solving interdiction problems with nonlinear power flow constraints;

# Main idea: Model of DER disruptions

# Vulnerability: Control Center and Substation communications



- Hack control center-substation communications
- Introduce incorrect set-points and disrupt DERs
- Create supply-demand mismatch
- Cause voltage bounds violations

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• Induce cascading failures

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#### 1 Motivation and Focus

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## Network interdiction

#### Network interdiction problem

- Perfect information leader-follower game;
- Attacker moves first and defender moves next.

#### Problem statement:

- Determine attacker's interdiction plan (compromise DERs) to maximize the sum of loss of voltage regulation (LOVR), and load shedding (LL),
- Under defender choices:
  - Non-compromised DERs provide active and reactive power (VAR);
  - Demand at consumption nodes may be partly satisfied;
  - Small LOVR acceptable.

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### Related work

#### Control of distribution systems

- Steven Low, Javad Lavaei, et al.: Convex optimal power flow (on tree networks)
- Konstantin Turitsyn e. al., Ian A. Hiskens. et. al.: Distributed optimal VAR control balancing voltage regulation and line losses

#### Resilience and security of networked systems

- Ross Baldick, Kevin Wood: Interdiction for transmission networks
- Daniel Bienstock, et al.: Cascading failures with linear power flow
- Rakesh Bobba, Robin Berthier: AMI security, false-data injection

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## Network model

#### Tree networks

- $\mathcal{G} = (\mathcal{N}, \mathcal{E})$  tree network of nodes and edges
- $\nu_i = |V_i|^2$  square of voltage magnitude at node *i*
- $\ell_{ij} = |I_{ij}|^2$  square of current magnitude from node *i* to *j*
- $z_{ij} = r_{ij} + \mathbf{j}x_{ij}$  impedance on line (i, j)
- $P_{ij}, Q_{ij}$  real and reactive power from node *i* to node *j*
- $S_{ij} = P_{ij} + \mathbf{j}Q_{ij}$  complex power flowing on line  $(i,j) \in \mathcal{E}$



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### Power flow and operational constraints

- Generated power:  $sg_i = pg_i + jqg_i$
- Consumed power:  $sc_i = pc_i + jqc_i$
- Power flow

$$\begin{split} P_{ij} &= \sum_{k:j \to k} P_{jk} + pc_j - pg_j + r_{ij}\ell_{ij} \\ Q_{ij} &= \sum_{k:j \to k} Q_{jk} + qc_j - qg_j + x_{ij}\ell_{ij} \\ \nu_j &= \nu_i - 2(r_{ij}P_{ij} + x_{ij}Q_{ij}) + (r_{ij}^2 + x_{ij}^2)\ell_{ij} \\ \ell_{ij} &= \frac{P_{ij}^2 + Q_{ij}^2}{\nu_i} \end{split}$$

Voltage limits

$$\underline{\nu}_i \leq \nu_i \leq \overline{\nu}_i$$

Maximum injected power

$$-\sqrt{\overline{sg}_i^2 - (pg_i)^2} \le qg_i \le \sqrt{\overline{sg}_i^2 - (pg_i)^2}$$

## Attacker model

Attacker strategy:  $\psi = (\delta, \widetilde{pg}^a, \widetilde{qg}^a)$ 

- $\delta$  is a vector, with elements  $\delta_i = 1$  if DER *i* is compromised and zero otherwise;
- $\widetilde{pg}^a$ : Active power set-points induced by the attacker;
- $\widetilde{qg}^a$  : Reactive power set-points induced by the attacker.
- Satisfy resource constraint  $\sum_{i=1}^{n} \delta_i \leq M$

M: attacker's budget.



Power injected by each DER constrained by:

$$-\sqrt{\overline{sg}_{i}^{2}-(\widetilde{\rho}\widetilde{g}_{i}^{a})^{2}} \leq \widetilde{qg}_{i}^{a} \leq \sqrt{\overline{sg}_{i}^{2}-(\widetilde{\rho}\widetilde{g}_{i}^{a})^{2}}$$

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## Attacker's impact with no defender response

- Scenario: Attacker introduces incorrect set-points sg<sup>a</sup> that lead voltage below (or above) the permitted thresholds.
- DER Interconnection guidelines would mandate disconnections of other non-compromised DERs.
- This could cause disconnection of DERs or load-shedding which, if uncontrolled, may result in failures in other DNs.

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## Defender model

Defender response:  $\phi = (\gamma, \widetilde{pg}^d, \widetilde{qg}^d)$ 

- $\gamma \in [0, 1]$  the portion of controlled loads;
- $\widetilde{pg}^d$ : New active power set-points set by defender;
- $\widetilde{qg}^d$ : New reactive power set-points set by the defender.



$$pc_i = \gamma_i pc_i^{\mathrm{d}}, \quad qc_i = \gamma_i qc_i^{\mathrm{d}}$$

Power injected by each DER constrained by:

$$-\sqrt{\overline{sg}_{i}^{2}-(\widetilde{pg}_{i}^{d})^{2}}\leq \widetilde{qg}_{i}^{d}\leq \sqrt{\overline{sg}_{i}^{2}-(\widetilde{pg}_{i}^{d})^{2}}$$

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Final PV output  $pg_i = \delta_i \widetilde{pg}_i^a + (1 - \delta_i) \widetilde{pg}_i^d$   $qg_i = \delta_i \widetilde{qg}_i^a + (1 - \delta_i) \widetilde{qg}_i^d$ How to choose the defender response (set-points)?

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#### Losses

• Loss of voltage regulation

$$\mathcal{L}_{\mathsf{LOVR}} \equiv \max_{i \in \mathcal{N}_0} W_i (\underline{\nu}_i - \nu_i)_+$$

• Cost incurred due to load control

$$\mathcal{L}_{\mathsf{VOLL}} \equiv \sum_{i \in \mathcal{N}_0} C_i (1 - \gamma_i)$$

Composite loss function

$$\mathcal{L}(\psi, \phi) = \mathcal{L}_{\mathsf{LOVR}} + \mathcal{L}_{\mathsf{VOLL}}$$

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## Problem statement

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Find attacker's interdiction plan to maximize composite loss  $L(\psi, \phi)$ , given that defender optimally responds

$$\begin{split} \max_{\psi} & \min_{\phi} \left( \max_{i \in \mathcal{N}_0} W_i (\underline{\nu}_i - \nu_i)_+ + \sum_{i \in \mathcal{N}_0} C_i (1 - \gamma_i) \right) \\ \text{s.t. Power flow, DER constraints and resource contraints} \\ \phi &= (\gamma, \widetilde{pg}^d, \widetilde{qg}^d) \\ \psi &= (\delta, \widetilde{pg}^a, \widetilde{qg}^a) \\ \delta \in \{0, 1\}^N, \gamma \in \prod_{i \in \mathcal{N}_0} [\underline{\gamma}_i, 1] \end{split}$$

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This bilevel-problem is hard!

- Outer problem: mixed-integer attack variables
- Inner problem: nonlinear in control variables

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## Bilevel Network Interdiction Problem

$$\begin{array}{rcl} [\mathsf{ADLP1}] & z_1^* & = & \min_{\mathbf{x} \in X} z_1(\mathbf{x}), \text{where} \\ & z_1(\mathbf{x}) & \equiv & \max_{\mathbf{y}} & \mathbf{c}^T \mathbf{y} \\ & & \text{s.t.} & A \mathbf{y} \leq b \\ & & 0 \leq \mathbf{y} \leq U(\mathbf{1} - \mathbf{x}). \\ [\mathsf{ADLP2}] & z_2^* & = & \min_{\mathbf{x} \in X} z_2(\mathbf{x}), \text{where} \\ & z_2(\mathbf{x}) & \equiv & \max_{\mathbf{y}} & (\mathbf{c}^T - \mathbf{x}^T \overline{R}) \mathbf{y} \\ & & \text{s.t.} & A \mathbf{y} \leq b \\ & & 0 \leq \mathbf{y} \leq U(\mathbf{1} - \mathbf{x}) \end{array}$$

where  $\overline{R} = \text{diag}(\overline{\mathbf{r}})$ ,  $\overline{\mathbf{r}} = (\overline{\mathbf{r}}_1 \dots \overline{\mathbf{r}}_n)^T$  and  $\overline{\mathbf{r}}_k$  is an upper bound to the optimal dual variable for the constraint  $y_k \leq u_k(1 - x_k)$ .

• Can be solved using Bender's decomposition

## Simple case

For a fixed defender choice and ignoring loss of freq. regulation:

$$\max_{\boldsymbol{\delta}} \left( \max_{i \in \mathcal{N}_0} W_i (\underline{\nu}_i - \nu_i)_+ \right)$$

s.t. Power flow, DER constraints, and resource contraints

Results for this simple case also extend to the case when R/X ratio is homogeneous and defender responds with only DER control.

## Precedence description



In the above figure

- $j \prec_i k$ : Node j is before node k with respect to node i
- $e =_i k$ : Node e is at the same level as node k with respect to node i
- $b \prec k$ : Node b is before node k because of b is ancestor of k

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## Optimal interdiction plan

#### Theorem

For a tree network, given nodes i (pivot),  $j, k \in \mathcal{N}_0$ :

- If DGs at j, k are homogenous and j is before k w.r.t. i, then DG disruption at k will have larger effect on ν<sub>i</sub> at i (relative to disruption at node j);
- If DGs at j, k are homogenous and j is at the same level as k w.r.t. i, then DG disruptions at j and k will have the same effect on ν<sub>i</sub> at i;

Let 
$$\nu_i^{old} / \nu_i^{new}$$
 be  $|V_i|^2$  before/after the attack  

$$\Delta(\nu_i) = \nu_i^{old} - \nu_i^{new}$$

$$\Delta_j(\nu_i) < \Delta_k(\nu_i)$$

$$\Delta_e(\nu_i) \approx \Delta_k(\nu_i)$$

$$j \prec_i k$$

$$e = i k$$

$$b \prec k$$

$$p = -i - k$$

## Computing optimal attack: fixed defender choices

- 1: **procedure** OptimalAttackForFixedResponse
- 2: for  $i \in \mathcal{N}_0$  do
- 3: for  $j \in \mathcal{N}_0$  do
- 4: Compute  $\Delta_j(\nu_i)$
- 5: end for
- 6: Sort *j*s in decreasing order of  $\Delta_j(\nu_i)$  values
- 7: Compute  $J_i^*$  by picking *j*s corresponding to top  $M \Delta_j(\nu_i)$  values.
- 8: end for

9: 
$$k := W_i \arg\min_{i \in \mathcal{N}_0} \nu_i - \Delta_{J_i^*}(\nu_i)$$

- 10: **return**  $J^* := J_k^*$  (Pick  $J_i^*$  which violates voltage constraint the most)
- 11: end procedure
  - $\mathcal{O}(n^2 \log n)$

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## Greedy algorithm for optimal attack: defender response



## IEEE 37-node network



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## Secure network designs: which DERs to secure?



Consider a DN with balanced tree topology, homogeneous R/X ratio, and homogenous nodes. In an optimally secure design:

- If any node is secure, all its child nodes must also be secure;
- There exists at most one intermediate level (depth) that contains both vulnerable and secure nodes;
- In this intermediate level, the secure nodes are "uniformly distributed".

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# Results: VOLL vs $|\delta|, \quad \gamma = 0.5$



# Results: LOVR vs $|\delta|, \quad \gamma = 0.5$



## Results: Homogeneous Network





Figure :  $\nu$  vs Distance from Substation

Figure : Reactive Power vs Real Power Output of PVs

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## Results: Homogeneous vs Heterogeneous Network



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Figure :  $\nu$  vs Distance from Substation

Figure : Reactive Power vs Real Power Output of PVs

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## Main insights

- Results using greedy algorithm compare very well with results from (more computationally intensive) brute force and Bender's cut;
- Optimal attack plans with defender response (using both DER control and load control) show downstream preference;
- When cost of load control is high (resp. low), defender permits (resp. does not permit) increase in cost due to LOVR;
- For small # of compromised DERs, load control is preferred over LOVR;
- Beyond a certain attack intensity, load control is not effective and attacker starts targeting upstream nodes (and their voltage bounds).

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