Moment-Sum-Of-Squares based Semidefinite Programming for Chance Constrained Optimization

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Chance Optimization



> Success: a set defined in terms of design parameters and probabilistic uncertainties.

Chance Optimization

- $x \in \mathbb{R}^n$: Design parameters
- $\omega \in \mathbb{R}^m$: Uncertain parameters with given probability distributions $\mathrm{pr}(\omega)$
- $p_i(x,\omega), i=1,...,n_p$: Polynomials
- $g_i(x), i=1,...,n_g$: Polynomials

Chance Optimization

$$\begin{array}{ll} \underset{x \in \mathbb{R}^{n}}{\text{maximize}} & \text{Probability}_{\mathrm{pr}(\omega)}(\ p_{i}(x,\omega) \geq 0, \ i=1,...,n_{p} \) \\ \text{subject to} & g_{i}(x) \geq 0, \ i=1,...,n_{g} \end{array}$$

Example: Portfolio Selection Problem

- Assets with uncertain rate of return $\omega_i \sim pr_i(\omega)$, i = 1, ..., 4
- x_i invested money in asset i
- Success = Achive a return higher than " r^* " Return = { $\omega_1 x_1 + \omega_2 x_2 + \omega_3 x_3 + \omega_4 x_4 \ge r^*$ }
- Total investment: $x_1 + x_2 + x_3 + x_4 \le x^*$



Chance Optimization

maximize x_1, x_2, x_3, x_4 Probability $(\omega_1 x_1 + \omega_2 x_2 + \omega_3 x_3 + \omega_4 x_4 \ge r^*)$ subject to $x_1 + x_2 + x_3 + x_4 \le x^*$

Chance Constrained Optimization:



Chance Constrained Optimization:



Chance Constrained Optimization

 $\begin{array}{ll} \underset{x \in \mathbb{R}^{n}}{\text{minimize}} & p(x) & \text{Success Set} & \text{Acceptable risk level} \\ \text{subject to} & \text{Probability}_{\mathrm{pr}(\omega)}(g_{i}(x,\omega) \geq 0, \ i = 1, ..., n_{g} \) \geq 1 - \Delta \end{array}$

Chance (Constrained) Optimization

> These problems are, in general, **nonconvex** and **computationally hard**.

• e.g., Probability<sub>pr(
$$\omega$$
)</sub>($g(x, \omega) \ge 0$) = $\int_{g(x, \omega) \ge 0} \operatorname{pr}(\omega) d\omega$

Multivariate integral

In general, It does not have any analytical solution

- > Existing Methods For Chance (Constrained) Optimization:
 - Sampling based Approaches
 - Particular Classes of Constraints and Uncertainties

e.g., Linear Chance Constraints with Gaussian Uncertainties

Chance (Constrained) Optimization

- In this presentation, we develop an approach to address a general class of Chance (Constrained) Optimizations.
- > We look for **convex relaxations** in the form of **Semidefinite Programs**.
- > To obtain convex relaxations, we leverage on:
 - Theory of Measure and Moments
 - Theory of Sum-Of-Squares Polynomials
 - Duality of Conic Programs
- Ashkan Jasour, "Convex Approximation of Chance Constrained Problems: Application in Systems and Control", School of Electrical Engineering and Computer Science, The Pennsylvania State University, 2016.
- Ashkan Jasour, Necdet S. Aybat, and Constantino Lagoa, "Semidefinite Programming For Chance Constrained Optimization Over Semialgebraic Sets", SIAM Journal on Optimization, 25(3), 1411–1440, 2015.

Ashkan Jasour, "Risk Aware and Robust Nonlinear Planning", Course Notes for MIT 16.S498, rarnop.mit.edu, 2019.
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Chance (Constrained) Optimization



Assumptions:

- All function and constraints are polynomial functions.
- Sets are Compact (Archimedean¹).

To satisfy Archimedean, we can add the (redundant) polynomial $M - ||x||^2$ where $M \ge 0$ such that the set $\{x: M - ||x||^2 \ge 0\}$ contains the set.

1: For more information: rarnop.mit.edu, 2019 Lecture 3, pages 58-59

Measure and Moment based Chance Optimization - Overview



Step 1: Infinite-dimensional LP

- We treat deign variables *x* as random variables.
- Instead of looking for "x", we look for its probability distribution (probability measure).

Step 2: Infinite-dimensional SDP

Instead of looking for measures, we look for the moment sequence (i.e. E[x^α], α = 0, ..., ∞) of the measures.

Step 3: Finite SDP

Truncate matrices of SDP of Step 2 (truncated moments)

Step 4: We extract the solution of the original chance optimization by looking at the moments.

Infinite LP

in measure space

Infinite SDP

in moment space

Finite moment SDP

Measure and Moment based Chance Constrained Optimization - Overview

$$\begin{array}{ll} \underset{x \in \mathbb{R}^n}{\text{minimize}} & p(x) \\ \text{subject to} & \text{Probability}_{\mathrm{pr}(\omega)}(g_i(x,\omega) \ge 0, \ i = 1, ..., n_g) \ge 1 - \Delta \end{array}$$

- We look at the **dual optimization** of **moment SDP** of the **chance optimization**.
- We obtain Sum-Of-Squares optimization whose solution, (e.g., $p_{cc}(x)$) approximates the **feasible** set of chance constrained optimization.

$$\chi_{cc} = \{x : \text{Probability}_{pr(\omega)}(g_i(x,\omega) \ge 0, i = 1, ..., n_g) \ge 1 - \Delta\} = \{x : p_{cc}(x) \ge 1 - \Delta\}$$

We obtain inner and outer approximation of the chance constrained set.



Measure and Moment based Chance Optimization

Reformulate Chance Optimization problem in terms of measures

$$\begin{aligned} \mathbf{P}^* = & \underset{x \in \mathbb{R}^n}{\text{maximize}} \quad \text{Probability}_{\mathrm{pr}(\omega)}(\ p_i(x, \omega) \geq 0, \ i = 1, ..., n_p \) \\ & \text{subject to} \quad g_i(x) \geq 0, \ i = 1, ..., n_g \end{aligned}$$

- We treat deign variables *x* as random variables.
- Instead of looking for "x", we look for its probability measure.
- Two sets of probability measures:
 - Unknown Probability measure of Design parameters: $x \sim \mu_x$
 - Given Probability measure of uncertain parameters: $\omega \sim \mu_{\omega}$
- \succ We obtain the equivalent optimization in terms of μ_x and μ_{ω} .

Reformulate Chance Optimization problem in terms of measures

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Given Success Set in (x, ω) Space:

Given Feasible Set:

• $\mathcal{K} = \{(x,\omega) \in \mathbb{R}^n \times \mathbb{R}^m : p_i(x,\omega) \ge 0, \ i = 1, ..., n_p \}$ $\chi = \{x \in \mathbb{R}^n : g_i(x) \ge 0, \ i = 1, ..., n_g\}$

Reformulate Chance Optimization problem in terms of measures

$$\mathbf{P}^* = \underset{x \in \mathbb{R}^n}{\text{maximize}} \quad \text{Probability}_{\text{pr}(\omega)}(p_i(x, \omega) \ge 0, \ i = 1, ..., n_p)$$

subject to $g_i(x) \ge 0, \ i = 1, ..., n_g$

•
$$\mathcal{K} = \{(x,\omega) \in \mathbb{R}^n \times \mathbb{R}^m : p_i(x,\omega) \ge 0, \ i = 1, ..., n_p \}$$
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V Infinite dimensional Linear Program in Measures

$$\mathbf{P}^*_\mu := ext{maximize}_{\mu_x,\mu} \int d\mu, ext{ }$$
 (volume of measure μ)

s.t. $\mu \preccurlyeq \mu_x \times \mu_\omega \longrightarrow$ (Upper bound measure) μ_x is a probability measure $supp(\mu_x) \subset \chi, \quad supp(\mu) \subset \mathcal{K}$

 μ : Slack Measure

 μ_x : Probability Measure Assigned to x

 μ_{ω} : Known Probability Measure of ω

 $\mu_x \times \mu_\omega$: joint measure of x and ω

Interpretation of Measure LP:

 $\mathbf{P}^* = \text{maximize}$ Probability_{pr(ω)} ($p_i(x, \omega) \ge 0, i = 1, ..., n_p$) $x \in \mathbb{R}^n$ subject to $g_i(x) \ge 0, i = 1, ..., n_q$

 $\mathcal{K} = \{ (x, \omega) \in \mathbb{R}^n \times \mathbb{R}^m : p_i(x, \omega) \ge 0, \ i = 1, ..., n_p \} \quad \chi = \{ x \in \mathbb{R}^n : g_i(x) \ge 0, \ i = 1, ..., n_q \}$



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- **Suppose** that measure μ_x assigned to the x is given:
- We want to calculate the **probability of success** in terms of the probability measures μ_x and μ_{ω} .

Probability $(p_i(x,\omega) \ge 0, i = 1, ..., n_p)$



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Probability($p_i(x,\omega) \ge 0, i = 1, ..., n_p$)

• From the definition of the probability:

$$\begin{aligned} & \text{Probability}_{\text{pr}(\omega)}(\ p_i(x,\omega) \ge 0, \ i = 1, ..., n_p \) \\ & = \int_{\mathcal{K} = \{\ p_i(x,\omega) \ge 0, \ i = 1, ..., n_p \ \}} d(\mu_x \times \mu_\omega) \end{aligned}$$





18

Probability($p_i(x,\omega) \ge 0, i = 1, ..., n_p$) = $\int_{\mathcal{K}=\{p_i(x,\omega)\ge 0, i=1,...,n_p\}} d(\mu_x \times \mu_\omega)$

- This is a **multivariate integral** over the (nonconvex)set \mathcal{K}
- Such integral, in general, does not have a **closed form solution**.



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- This is a **multivariate integral** over the (nonconvex)set \mathcal{K}
- Such integral, in general, does not have a **closed form solution**.
- To calculate this integral, we introduce a **slack measure** μ .
- Measure μ is supported in the set \mathcal{K}
- Measure μ is equal to measure $\mu_x \times \mu_\omega$ in the set \mathcal{K}

Probability(
$$p_i(x,\omega) \ge 0, i = 1, ..., n_p$$
) = $\int d\mu$





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Probability(
$$p_i(x,\omega) \ge 0, i = 1, ..., n_p$$
) = $\int d\mu$

 y_0 : zero-order moment of μ





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 \succ To construct such **measure** μ , we solve the following optimization

$$\max_{\mu} \int d\mu$$
$$\mu \preccurlyeq \mu_x \times \mu_\omega \qquad supp(\mu) \in \mathcal{K}$$





22

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) = $\int d\mu$

 \succ To construct such **measure** μ , we solve the following optimization

$$\max_{\mu} \int d\mu \qquad \qquad \text{Optimal Solution}$$
$$\mu \preccurlyeq \mu_x \times \mu_\omega \qquad supp(\mu) \in \mathcal{K}$$





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> To maximize the probability of success ,at the same time, we look for measure μ and measure μ_x .

maximize Probability $(p_i(x,\omega) \ge 0, i = 1, ..., n_p) =$

$$\max_{\mu \neq \mu_x} \int d\mu$$

$$\mu \preccurlyeq \mu_x \times \mu_\omega \quad supp(\mu) \in \mathcal{K}$$

$$\mu_x \text{ is a probability measure}$$

$$supp(\mu_x) \subset \chi$$



Reformulate Chance Optimization problem in terms of measures

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$$\mathcal{K} = \{(x,\omega) \in \mathbb{R}^n \times \mathbb{R}^m : p_i(x,\omega) \ge 0, \ i = 1, ..., n_p \}$$
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Infinite dimensional Linear Program in Measures

$$\mathbf{P}^*_{\mu} := \text{maximize}_{\mu_x,\mu} \int d\mu,$$

s.t. $\mu \preccurlyeq \mu_x \times \mu_\omega$ μ_x is a probability measure $supp(\mu_x) \subset \chi, \quad supp(\mu) \subset \mathcal{K}$



25

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> If $x^* \in \chi$ is unique global optimal solution of the original problem, Then $\mu^* = \delta_{x^*}$ is unique optimal solution of measure -LP.



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> If $x^* \in \chi$ is unique global optimal solution of the original problem, Then $\mu^* = \delta_{x^*}$ is unique optimal solution of measure -LP.



▶ If $x^{*i} \in \chi$, i = 1, ..., r are "r" global optimal solution of the original problem, Then $\mu^* = \sum_{i=1}^r \beta_i \delta_{x^{*i}}$, $\beta_i > 0$, $\sum_{i=1}^r \beta_i = 1$ is unique optimal solution of optimization in measures.

$$\mu^* = \sum_{i=1}^r \beta_i \delta_{x^{*i}}, \ \beta_i > 0, \sum_{i=1}^r \beta_i = 1$$





3 Equivalent Problem in the moment space:

- Instead of looking for measures, we look for the moment sequence (i.e. $E[x^{\alpha}], \alpha = 0, ..., \infty$) of the measures.
- We need to write the objective function and constraints of the measure-LP in terms of the moments.

Let $\mathbf{K} = \{x \in \mathbb{R}^n : g_i(x) \ge 0, i = 1, ..., m\}$ be a semialgebraic (Archimedean).

Sequence y has a representing measure with support contained in the set \mathbf{K} , if and only if, it satisfies:

 $\mathbf{M}_d(y) \succcurlyeq 0, \quad \forall d$ Moment Matrix

$$\mathbf{M}_{d-d_{g_i}}(g_i y) \succcurlyeq 0, \ i = 1, ..., m, \quad \forall d$$

Chapter 3: Jean Bernard Lasserre, "Moments, Positive Polynomials and Their Applications" Imperial College Press Optimization Series, V. 1, 2009.

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$$\mathbf{M}_{d}(y) \succcurlyeq 0, \quad \forall d \qquad \qquad \mathbf{M}_{d-d_{g_{i}}}(g_{i}y) \succcurlyeq 0, \quad i = 1, ..., m, \quad \forall d$$
Moment Matrix Localizing Matrix

Example: Moment matrix of order d = 2 of a measure in \mathbb{R}

$$\mathbf{M}_{2}(y) = \mathbf{E}[B_{2}(x)B_{2}^{T}(x)] = \mathbf{E}_{\mu}\begin{bmatrix}1\\x_{1}\\x_{1}^{2}\end{bmatrix}\begin{bmatrix}1 & x_{1} & x_{1}^{2}\end{bmatrix} = \mathbf{E}_{\mu}\begin{bmatrix}1 & x_{1} & x_{1}^{2}\\x_{1} & x_{1}^{2} & x_{1}^{3}\\x_{1}^{2} & x_{1}^{3} & x_{1}^{4}\end{bmatrix} = \begin{bmatrix}y_{0} & y_{1} & y_{2}\\y_{1} & y_{2} & y_{3}\\y_{2} & y_{3} & y_{4}\end{bmatrix}$$

Let $\mathbf{K} = \{x \in \mathbb{R}^n : g_i(x) \ge 0, i = 1, ..., m\}$ be a semialgebraic (Archimedean).

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Example: Localizing matrix for moments up to order 4 of a Measure μ in \mathbb{R}^2 and polynomial $g(x) = a - x_1^2 - x_2^2$

$$\mathbf{M}_{1}(gy) = \mathbf{E}[g(x)B_{1}(x)B_{1}^{T}(x)] = \begin{bmatrix} ay_{00} - y_{20} - y_{02} & ay_{10} - y_{30} - y_{12} & ay_{01} - y_{21} - y_{03} \\ ay_{10} - y_{30} - y_{12} & ay_{20} - y_{40} - y_{22} & ay_{11} - y_{31} - y_{13} \\ ay_{01} - y_{21} - y_{03} & ay_{11} - y_{31} - y_{13} & ay_{02} - y_{22} - y_{04} \end{bmatrix}$$

Let $\mathbf{K} = \{x \in \mathbb{R}^n : g_i(x) \ge 0, i = 1, ..., m\}$ be a semialgebraic (Archimedean).

Sequence y has a representing measure with support contained in the set \mathbf{K} , if and only if, it satisfies:

$$\mathbf{M}_{d}(y) \succcurlyeq 0, \quad \forall d \qquad \qquad \mathbf{M}_{d-d_{g_{i}}}(g_{i}y) \succcurlyeq 0, \quad i = 1, ..., m, \quad \forall d$$

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2 Equivalent Problem in the measure space:

$$\mathbf{P}_{\mu}^{*} := \text{maximize}_{\mu_{x},\mu} \int d\mu,$$

s.t. $\mu \preccurlyeq \mu_{x} \times \mu_{\omega}$
 $\mu_{x} \text{ is a probability measure}$
 $supp(\mu_{x}) \subset \chi, \quad supp(\mu) \subset \mathcal{K}$

$$\mathcal{K} = \{ (x, \omega) \in \mathbb{R}^n \times \mathbb{R}^m : p_i(x, \omega) \ge 0, \ i = 1, ..., n_p \}$$
$$\chi = \{ x \in \mathbb{R}^n : g_i(x) \ge 0, \ i = 1, ..., n_g \}$$

3 Moment Representation of Measures:



1 Chance Optimization	$\mathbf{P}^* = \underset{x \in \mathbb{R}^n}{\operatorname{maximize}}$	Probability _{pr(ω)} ($p_i(x, \omega) \ge 0, i = 1, .$	\dots, n_p)
	subject to	$g_i(x) \ge 0, \ i = 1,, n_g$	
2 Equivalent Problem in the measure space: Infinite dimensional LP		$\mathbf{P}^*_{\mu} := \text{maximize}_{\mu_x,\mu} \int d\mu,$	
		s.t. $\mu \preccurlyeq \mu_x \times \mu_\omega$ μ_x is a probability measure $supp(\mu_x) \subset \chi, supp(\mu) \subset \mathcal{K}$	
3 Equivalent Problem in the r	noment space:		- Equivalent –
Infinite dimensional SDP	$\mathbf{P}^*_{\mathbf{m}}$	$\begin{array}{ll} \text{nom} := & \text{maximize}_{y,y_x} & y_0 \\ \text{s.t.} & M_{\infty}(\mathbf{y}) \succcurlyeq 0, \ M_{\infty}(p_i y) \succcurlyeq 0, j = 1, \dots, n_p \\ & M_{\infty}(y_x) \succcurlyeq 0, \ M_{\infty}(g_i y) \succcurlyeq 0, i = 1, \dots, n_g \\ & M_{\infty}(y_{\omega} \times y_x - y) \succcurlyeq 0 \end{array}$	$y_{x_0}=1$

3 Equivalent Problem in the moment space:	$\mathbf{P}^*_{\mathbf{mom}} := \operatorname{maximize}_{y, y_x} y_0$
Infinite dimensional SDP	s.t. $M_{\infty}(\mathbf{y}) \geq 0, \ M_{\infty}(p_i y) \geq 0, \ j = 1, \dots, n_p$
	$M_{\infty}(y_x) \succcurlyeq 0, \ M_{\infty}(g_i y) \succcurlyeq 0, i = 1, \dots, n_g, \ y_{x_0} = 1$
	$M_{\infty}(y_{\omega} \times y_x - y) \succcurlyeq 0 \qquad \qquad$
	Relaxation
4 Finite SDP in moments:	$\mathbf{P}_{\mathbf{mom}}^{*\mathbf{u}} := \operatorname{maximize}_{y, y_x} y_0 \qquad \qquad$
Truncated moment SDP	s.t. $M_d(\mathbf{y}) \geq 0, \ M_{d-d_{p_i}}(p_i y) \geq 0, j = 1, \dots, n_p$
in terms of moment up to order 2d	$M_d(y_x) \ge 0, \ M_{d-d_{g_i}}(g_i y) \ge 0, i = 1, \dots, n_g, \ y_{x_0} = 1$
	$M_d(y_\omega \times y_x - y) \succcurlyeq 0$

3 Equivalent Problem in the moment space:	$\mathbf{P}^*_{\mathbf{mom}} := \max inize_{y,y_x} y_0$
Infinite dimensional SDP	s.t. $M_{\infty}(\mathbf{y}) \geq 0, \ M_{\infty}(p_i y) \geq 0, \ j = 1, \dots, n_p$
	$M_{\infty}(y_x) \succcurlyeq 0, \ M_{\infty}(g_i y) \succcurlyeq 0, i = 1, \dots, n_g, \ y_{x_0} = 1$
	$M_{\infty}(y_{\omega} \times y_x - y) \succcurlyeq 0 \qquad \qquad$
	Relaxation
4 Finite SDP in moments:	$\mathbf{P}_{\mathbf{mom}}^{\mathbf{H}\mathbf{d}} := \max \operatorname{maximize}_{y, y_x} y_0 \qquad \qquad$
Truncated moment SDP	s.t. $M_d(\mathbf{y}) \geq 0, \ M_{d-d_{p_i}}(p_i y) \geq 0, j = 1, \dots, n_p$
in terms of moment up to order $2d$	$M_d(y_x) \ge 0, \ M_{d-d_{g_i}}(g_i y) \ge 0, i = 1, \dots, n_g, \ y_{x_0} = 1$
	$M_d(y_\omega \times y_x - y) \succcurlyeq 0$
Theorem:	
Optimal solution of the finite SDP converged	, we see to the optimal solution of the original SDP as $d o \infty$
\succ For all $d \geq 1$ $\mathbf{P_{mom}^{*d}} \geq \mathbf{P^{*}}$ Up	per bound of optimal objective function of chance optimization
$\mathbf{P_{mom}^{*d}} \geq \mathbf{P_{mom}^{*d+1}}$	$lim_{d ightarrow\infty}\mathbf{P^{*d}_{mom}}=\mathbf{P^{*}}$ monotonically converges

• Theorem 3.3 : A. Jasour, N. S. Aybat, and C. Lagoa "Semidefinite Programming For Chance Constrained Optimization Over Semialgebraic Sets", SIAM Journal on Optimization, 25(3), 1411–1440, 2015.

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1 Chance Optimization	$\mathbf{P}^* = \max_{x \in \mathbb{R}^n}$	Probability _{pr(ω)} ($p_i(x, \omega) \ge 0, i = 1,, n_p$)	^
	subject to	$g_i(x) \ge 0, \ i = 1,, n_g$	- Equivalent
2 Equivalent Problem in the	measure space:	$\mathbf{P}^*_{\mu} := \text{maximize}_{\mu_x,\mu} \int d\mu,$	
Infinite dimensional LP		s.t. $\mu \preccurlyeq \mu_x \times \mu_\omega$	
		μ_x is a probability measure	
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			\equiv Equivalent \perp
3 Equivalent Problem in the	moment space:	$\mathbf{P}^*_{\mathbf{mom}} := \operatorname{maximize}_{y, y_x} y_0$	
Infinite dimensional SDP		s.t. $M_{\infty}(\mathbf{y}) \succeq 0, \ M_{\infty}(p_i y) \succeq 0, \ j = 1, \dots, n$	p \checkmark
		$M_{\infty}(y_x) \succcurlyeq 0, \ M_{\infty}(g_i y) \succcurlyeq 0, i = 1, \dots, n$	$b_g, \ y_{x_0} = 1$
		$M_{\infty}(y_{\omega} \times y_x - y) \succcurlyeq 0$	
		1	Relaxation
4 Finite SDP in moments:	I	$\mathbf{P}_{\mathbf{mom}}^{*\mathbf{d}} := \operatorname{maximize}_{y, y_x} y_0$	\prec \succ
Truncated moment SDP		s.t. $M_d(\mathbf{y}) \succeq 0, \ M_{d-d_{p_i}}(p_i y) \succeq 0, \ j = 1, \dots, n$	p
		$M_d(y_x) \succcurlyeq 0, \ M_{d-d_{g_i}}(g_i y) \succcurlyeq 0, i = 1, \dots, r$	$h_g, y_{x_0} = 1$
		$M_d(y_\omega \times y_x - y) \succcurlyeq 0$	

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Extraction of the Solution from the moments:

- We are going to identify the **Dirac measures** by looking at the moments of x obtained by solving finite SDP.
- We extract the solution by looking at the **support** of the Dirac measures.



Extraction of the Solution from the moments:

- We are going to identify the **Dirac measures** by looking at the moments of *x* obtained by solving finite SDP.
- We extract the solution by looking at the **support** of the Dirac measures.



Dirac Measure:

Sequence $y = [y_{\alpha}, \alpha = 0, ..., 2d]$ is the moment sequence of a Dirac measure if and only if: $M_d(y) \succcurlyeq 0$, $\operatorname{Rank}(M_d(y)) = 1$

To extract the support (solution):

$$\delta_{x^*} \longrightarrow x^* = \mathbf{E}[\delta_{x^*}] = y_1$$



Extraction of the Solution from the moments:

- We are going to identify the **Dirac measures** by looking at the moments of x obtained by solving finite SDP.
- We extract the solution by looking at the **support** of the Dirac measures.



r -atomic measure:

Sequence $y = [y_{\alpha}, \alpha = 0, ..., 2d]$ is the moment sequence of linear positive combination of r Dirac measure (r -atomic representation) if and only if

 $M_d(y) \succcurlyeq 0$, $\operatorname{Rank}(M_d(y)) = \operatorname{Rank}(M_{d-1}(y)) = r$ (M_d is a flat extension of M_{d-1})

 \succ To extract the support (solution):

 \blacktriangleright To extract the support (solution): we need to solve a linear algebra (relies on moment matrix factorization $M_d(y) = VV^T$).¹



1: Algorithm 4.2 : Jean Bernard Lasserre, "Moments, Positive Polynomials and Their Applications" Imperial College Press Optimization Series, V. 1, 2009.

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Chance Optimization
$$\mathbf{P}^* = \underset{x \in \mathbb{R}^n}{\operatorname{assigned}}$$
Probability $p_{\mathbf{p}(\omega)}(p_i(x,\omega) \ge 0, i = 1, ..., n_p)$ subject to $g_i(x) \ge 0, i = 1, ..., n_g$ Moment Relaxation (SDP) $\begin{bmatrix} \mathbf{P}^{*d}_{\mathsf{mom}} := \max(y_y, y_g) \\ s.t. \quad M_d(y) \ge 0, \quad M_{d-d_{p_i}}(p_iy) \ge 0, \quad j = 1, ..., n_p \\ M_d(y_x) \ge 0, \quad M_{d-d_{q_i}}(g_iy) \ge 0, \quad i = 1, ..., n_g, \quad y_{x_0} = 1 \\ M_d(y_\omega \times y_x - y) \ge 0 \end{bmatrix}$ • Finite SDP of order d : $\mathbf{P}^{*d}_{\mathsf{mom}}$ is an upper bound of \mathbf{P}^* • As $d \to \infty$ $\mathbf{P}^{*d}_{\mathsf{mom}} \downarrow \mathbf{P}^*$ • If obtained solution y_x^* satisfies rank condition Rank $M_d(y_x^*) = \operatorname{Rank} M_{d-v}(y_x^*) = r \quad v = \max\{d_{g_i}\}$ $x_i^*, i = 1, ..., r, global solutions can be extracted by linear algebra from y_x^* > Otherwise, increase d and solve new SDP.$

Example 1

$$\begin{split} \mathbf{P}^* &= \underset{x}{\operatorname{maximize}} \quad \operatorname{Probability}(\ p(x,\omega) \geq 0 \) \\ &\text{subject to} \qquad -1 \leq x \leq 1 \\ &p(x,\omega) = 0.5\omega \left(\omega^2 + (x-0.5)^2\right) - \left(\omega^4 + \omega^2 (x-0.5)^2 + (x-0.5)^4\right) \\ &\omega \sim Uniform[-1,1] \end{split}$$



Example 1

$$\begin{aligned} \mathbf{P}^* &= \underset{x}{\operatorname{maximize}} \quad \operatorname{Probability}(\ p(x,\omega) \ge 0 \) \\ \text{subject to} &-1 \le x \le 1 \\ p(x,\omega) &= 0.5\omega \left(\omega^2 + (x-0.5)^2\right) - \left(\omega^4 + \omega^2 (x-0.5)^2 + (x-0.5)^4\right) \\ \omega &\sim Uniform[-1,1] \end{aligned}$$

Moment SDP of Order 4:

 $\max_{y,y_x} y_{00}$

$$M_{2}(y) \succeq 0 \Rightarrow \begin{pmatrix} y_{00} & y_{10} & y_{01} & y_{20} & y_{11} & y_{02} \\ y_{10} & y_{20} & y_{11} & y_{30} & y_{21} & y_{12} \\ y_{01} & y_{11} & y_{02} & y_{21} & y_{12} & y_{03} \\ y_{20} & y_{30} & y_{21} & y_{40} & y_{31} & y_{22} \\ y_{11} & y_{21} & y_{12} & y_{31} & y_{22} & y_{13} \\ y_{02} & y_{12} & y_{03} & y_{22} & y_{13} & y_{04} \end{pmatrix} \succeq 0 \qquad M_{2}(y_{x}y_{q}) - M_{2}(y) = \succeq 0 \Rightarrow \begin{pmatrix} 1 & y_{x1} & 0 & y_{x2} & 0 & 1/3 \\ y_{x1} & y_{x2} & 0 & y_{x3} & 0 & 1/3y_{x1} \\ 0 & 0 & 1/3 & 0 & 1/3y_{x1} & 0 \\ y_{x2} & y_{x3} & 0 & y_{x4} & 0 & 1/3y_{x2} \\ 0 & 0 & 1/3y_{x1} & 0 & 1/3y_{x2} & 0 \\ 1/3 & 1/3y_{x1} & 0 & 1/3y_{x2} & 0 \\ 1/3 & 1/3y_{x1} & 0 & 1/3y_{x2} & 0 \\ y_{x2} & y_{x3} & 0 & 2/5 \end{pmatrix} - M_{2}(y) = \succeq 0 \qquad \left| y_{x} \right| \leq 1$$

$$M_{2}(y_{x}) \succeq 0 \Rightarrow \begin{pmatrix} y_{x_{0}} & y_{x_{1}} & y_{x_{2}} \\ y_{x_{1}} & y_{x_{2}} & y_{x_{3}} \\ y_{x_{2}} & y_{x_{3}} & y_{x_{4}} \end{pmatrix} \succeq 0 \qquad y_{x_{0}} = 1$$

$$M_{1}(py) \succeq 0 \Rightarrow -y_{04} + \frac{1}{2}y_{03} - y_{22} + y_{12} - \frac{1}{4}y_{02} + \frac{1}{2}y_{21} - \frac{1}{2}y_{11} + \frac{1}{8}y_{01} - y_{40} + 2y_{30} - \frac{3}{2}y_{20} + \frac{1}{2}y_{10} - \frac{1}{16} \succeq 0$$



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Obtained result:

 $y = \langle [0.6610, \rangle 0.3305, 0.1484, 0.1687, 0.0742, 0.1022, 0.0878, 0.0387, 0.0511, 0.0406, 0.0465, 0.0210, 0.0263, 0.0203, 0.0203]$

Upper bound of probability of success

 $y_x = [1, (0.5, 0.2558, 0.1330, 0.8521]$

Rank Test:





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Example: 2

 $\mathbf{P}^* = \underset{x}{\text{maximize}} \quad \text{Probability}(\ p(x,\omega) \ge 0 \) \qquad \qquad p(x,\omega) = \{ x \in \mathbb{R}^2 : -\frac{1}{16}x_1^4 + \frac{1}{4}x_1^3 - \frac{1}{4}x_1^2 - \frac{9}{100}x_2^2 + \frac{29}{400} \ge 0 \}$ subject to $-1 \le x \le 1 \qquad \qquad \omega \sim Uniform[-1,1]$

d=5 $y_x = [1, 0, 0.44, 0, 0.19, 00, 0.08, 0, 0.06, 0, 0.91]$

Rank Test:

Rank
$$M_d(y_x) = \text{Rank } M_{d-1}(y_x) \approx 2$$

$$x_2^* = -0.66, x_1^* = 0.66$$



https://github.com/jasour/rarnop19/tree/master/Lecture7_ChanceOptimization/Example_2_Moment_ChanceOpt

Measure and Moment based Chance Optimization Dual Optimization

Chance Optimization	$\mathbf{P}^* = \max_{x \in \mathbb{R}^n}$	Probability _{pr(ω)} ($p_i(x, \omega) \ge 0, i = 1,, n_p$)
	subject to	$g_i(x) \ge 0, \ i = 1,, n_g$
Finite Moment SDP:	F	$\mathbf{p}_{\mathbf{mom}}^{*\mathbf{d}} := \operatorname{maximize}_{y, y_x} y_0$
		s.t. $M_d(\mathbf{y}) \geq 0, \ M_{d-d_{p_i}}(p_i y) \geq 0, j = 1, \dots, n_p$
		$M_d(y_x) \ge 0, \ M_{d-d_{g_i}}(g_i y) \ge 0, i = 1, \dots, n_g, \ y_{x_0} = 1$
		$M_d(y_\omega \times y_x - y) \succcurlyeq 0$

> We find the **dual optimization** of **Moment-SDP.** (Duality of Conic Program)

Dual Optimization:

Moment SDP

1

$$\mathbf{P_{mom}^{*d}} := \max i = \max y_{i} \quad y_{0}$$
s.t. $M_{d}(\mathbf{y}) \succeq 0, \ M_{d-d_{p_{i}}}(p_{i}y) \succeq 0, \quad j = 1, \dots, n_{p}$
 $M_{d}(y_{x}) \succeq 0, \ M_{d-d_{g_{i}}}(g_{i}y) \succeq 0, \quad i = 1, \dots, n_{g}, \ y_{x_{0}} = 1$
 $M_{d}(y_{\omega} \times y_{x} - y) \succeq 0$

Dual SDP

$$\mathbf{P}_{sos}^{*d} = \min_{\beta \in \mathbb{R}, \mathcal{W}(x,\omega) \in \mathbb{R}_d[x,\omega]} \beta$$
subject to

$$\mathcal{W}(x,\omega) - 1 \ge 0 \quad \forall (x,\omega) \in \mathcal{K}$$

$$\beta - \int \mathcal{W}(x,\omega) d\mu_{\omega} \ge 0 \quad \forall x \in \chi$$

$$\beta \ge 0, \mathcal{W}(x,\omega) \ge 0$$

$$\mathbf{SOS}$$

$$\mathcal{W}(x,\omega) d\mu_{\omega} = \mathbf{E}[\mathcal{W}(x,\omega)]$$

Sum-Of-Squares (SOS) optimization

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Interpretation of the dual problem

Dual optimization:	$ \min_{\beta \in \mathbb{R}, \mathcal{W}(x, \omega) \in \mathcal{C} } $	eta	•	$\mathcal{W}(x,\omega) \geq 0 \qquad \mathcal{W}(x,\omega) \geq 1 \ \forall (x,\omega) \in \mathcal{K}$
	subject to	$\mathcal{W}(x,\omega) \ge 1 \forall (x,\omega) \in \mathcal{K}$	•	Minimizes scaler $\beta \geq 0$
		$\beta \geq \int \mathcal{W}(x,\omega) d\mu_{\omega} \forall x \in \chi$	•	eta is upper bound of $\int \mathcal{W}(x,\omega) d\mu_\omega$
		$\beta \ge 0, \mathcal{W}(x, \omega) \ge 0$	•	$\int \mathcal{W}(x,\omega) d\mu_{\omega} = \mathbf{E}[\mathcal{W}(x,\omega)]$

Interpretation of the dual problem

Dual optimization: $\min_{\beta \in \mathbb{R}, \mathcal{W}(x, \omega) \in \mathcal{C}}$	eta	• $\mathcal{W}(x,\omega) \ge 0$ $\mathcal{W}(x,\omega) \ge 1 \forall (x,\omega) \in \mathcal{K}$
subject to	$\mathcal{W}(x,\omega) \ge 1 \forall (x,\omega) \in \mathcal{K}$	• Minimizes scaler $\beta \ge 0$
	$\beta \geq \int \mathcal{W}(x,\omega) d\mu_{\omega} \forall x \in \chi$	• β is upper bound of $\int \mathcal{W}(x,\omega) d\mu_{\omega}$
	$\beta \ge 0, \mathcal{W}(x, \omega) \ge 0$	• $\int \mathcal{W}(x,\omega) d\mu_{\omega} = \mathbf{E}[\mathcal{W}(x,\omega)]$

• For a given design variable x^* :



• $\mathcal{W}(x^*,\omega)$:

is an **upper bound** polynomial approximation of the indicator function of $\mathcal{K} = \{(x^*, \omega) : p_i(x^*, \omega) \ge 0, i = 1, ..., n_p\}$

•
$$E[\mathcal{W}(x,\omega)] = \int \mathcal{W}(x,\omega) d\mu_{\omega}$$
:

is an **upper bound** of probability of success for given x^*

52

Interpretation of the dual problem

Dual optimization:	$ \min_{\beta \in \mathbb{R}, \mathcal{W}(x, \omega) \in \mathcal{C} } $	eta	•	$\mathcal{W}(x,\omega) \geq 0 \qquad \mathcal{W}(x,\omega) \geq 1 \ \forall (x,\omega) \in \mathcal{K}$
1 1 1 1	subject to	$\mathcal{W}(x,\omega) \ge 1 \forall (x,\omega) \in \mathcal{K}$	•	Minimizes scaler $\beta \ge 0$
		$\beta \geq \int \mathcal{W}(x,\omega) d\mu_{\omega} \forall x \in \chi$	•	eta is upper bound of $\int \mathcal{W}(x,\omega) d\mu_\omega$
		$\beta \ge 0, \mathcal{W}(x, \omega) \ge 0$	•	$\int \mathcal{W}(x,\omega) d\mu_{\omega} = \mathbf{E}[\mathcal{W}(x,\omega)]$

• For a given design variable x^* :



• $\mathcal{W}(x^*,\omega)$:

is an **upper bound** polynomial approximation of the indicator function of $\mathcal{K} = \{(x^*, \omega) : p_i(x^*, \omega) \ge 0, i = 1, ..., n_p\}$

•
$$E[\mathcal{W}(x,\omega)] = \int \mathcal{W}(x,\omega) d\mu_{\omega}$$
:

is an **upper bound** of probability of success for given x^*

• $E[W(x,\omega)] = \int W(x,\omega) d\mu_{\omega}$: Upper bound **probability of success** as a function of x

 β : Upper bound of maximum **probability of success.**

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https://github.com/jasour/rarnop19/tree/master/Lecture7_ChanceOptimization/Example_1_Dual_ChanceOpt

ω



Moment SDP: $x^* = y_{x_1} = 0.5$



55

Dual Optimization (SOS) d = 5:



https://github.com/jasour/rarnop19/tree/master/Lecture7_ChanceOptimization/Example_1_Dual_ChanceOpt

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Dual Optimization (SOS) d = 5:







Dual Optimization (SOS) d = 5:



Moment SDP:

 $x^* = y_{x_1} = 0.5$

Chance Constrained Set: $\{x \in \mathbb{R}^n : Prob(Success) \ge 1 - \Delta\}$



Example 1: Modified SOS Program for Chance Constrained Set



Example: Modified SOS Program for Chance Constrained Set



Example: Modified SOS Program for Chance Constrained Set



Chance Constrained Set: Inner Approximation

- > We can apply same methodology to the Complement Set (failure Set)
 - Chance Constrained Set: $\{x : \mathbb{R}^n : Prob(failure) \le \Delta\}$ • Outer approximation: $\chi_{cc} = \{x \in \mathbb{R}^n : \int \mathcal{W}(x, \omega) \ d\mu_{\omega} \le \Delta\}$
 - Inner approximation of $\{x \in \mathbb{R}^n : Prob(Success) \ge 1 \Delta\}$

Example: Inner approximation

 $\mathcal{K} = \{(x,\omega) : p(x,\omega) = (0.8x - 0.1)^4 - 0.27\omega((0.8x - 0.1)^2 + 0.3\omega^2) + 0.3\omega^2(0.8x - 0.1)^2 + +0.09\omega^4 \ge 0\}$ $\omega \sim Uniform[-1,1]$ $\{x: Prob(Success) \ge 1 - \Delta\}$



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> For more **details**, **examples**, **codes**, **applications** in uncertain dynamical systems and robotics:

rarnop.mit.edu, Ashkan Jasour, "Risk Aware and Robust Nonlinear Planning(rarnop)", Course Notes for MIT 16.S498, Fall, 2019.

Related Publications: jasour.mit.edu/publications