

Polynomial time guarantees for the Burer-Monteiro method

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Joint work with **Ankur Moitra** (MIT)
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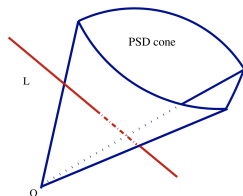
Virtual Seminar on Optimization and Related Areas - 2020

Semidefinite programming

A *semidefinite program* is

$$\begin{aligned} \text{(SDP)} \quad & \min_{X \in \mathcal{S}^n} C \bullet X \\ & \text{s.t. } A_i \bullet X = b_i \text{ for } i \in [m] \\ & X \succeq 0 \end{aligned}$$

where $C, A_1, \dots, A_m \in \mathcal{S}^n$, $b \in \mathbb{R}^m$.



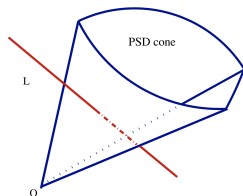
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- This is a *convex* problem.
- Polynomial time solvable with interior point methods (Nesterov-Nemirovski'87).
- Many different applications.



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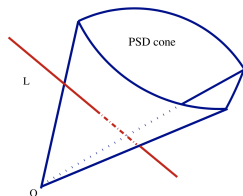
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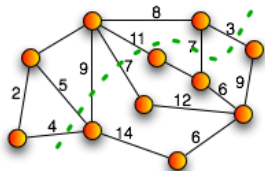
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Goal: Show that SDPs can be solved in polynomial time with a more recent class of methods. The proof is remarkably geometric.

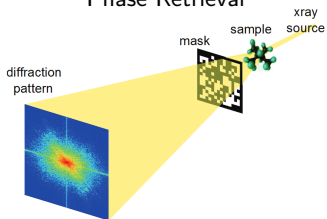


SDP applications

Max-Cut



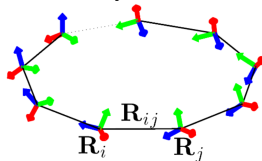
Phase Retrieval



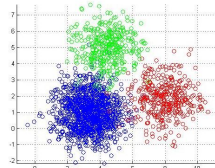
Matrix completion



Rotation synchronization



Clustering



Solving large scale SDPs

Interior point methods intractable for large SDPs (too much memory)

Practical methods

- Low rank factorization (Burer, Monteiro)
- Frank-Wolfe / CGM (Hazan, Jaggi, Freund, Grigas, Mazumder)
- Sketching (Yurtsever, Ding, Udell, Tropp, Cevher)
- Bundle (Helmberg, Rendl, Oustry)
- Subgradients (Nesterov, Yurtsever, Tran Dinh, Cevher)

The Burer-Monteiro method is one of the most widely used in practice.

Burer-Monteiro method

$$\text{(SDP)} \quad \min_{X \in \mathbb{S}^n} C \bullet X \quad \text{s.t.} \quad A_i \bullet X = b_i \text{ for } i \in [m], \quad X \succeq 0$$

Assume the optimal solution has $\text{rank} \leq p$, and factorize

$$X = YY^T \quad \text{where } Y \in \mathbb{R}^{n \times p}$$

Use local optimization to solve the *nonconvex* problem

$$\text{(BM)} \quad \min_{Y \in \mathbb{S}^n} C \bullet YY^T \quad \text{s.t.} \quad A_i \bullet YY^T = b_i \text{ for } i \in [m]$$

How large should we choose p ?

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Theorem (Barvinok-Pataki bound)

BM is equivalent to SDP when $\binom{p+1}{2} \geq m$. So we need $p \gtrsim \sqrt{2m}$.

Known global guarantees on BM

Below Barvinok-Pataki bound

There might be spurious local minima [Waldspurger, Waters].

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Above Barvinok-Pataki bound

Assume $\binom{p+1}{2} > m$.

- BM *should* work [Burer-Monteiro, Journée et al.]

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Assume compactness and $\binom{p+1}{2} > \frac{9}{2} m \log(\sigma^{-1})$ for some $\sigma > 0$.

- Randomly perturb C (magnitude σ). No spurious approximate local minima w.h.p. [Pumir-Jelassi-Boumal]

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No polynomial time guarantees known!

Obstacle: How to find a local minimum that is exactly feasible?

Our results

Assumptions:

- $\binom{p+1}{2} > (1+\eta)m$ for a fixed $\eta > 0$.
- Constraint set is smooth and compact.
- Solve BM using local method with 2nd order guarantees.

Theorem (Polytime optimality)

Randomly perturb C (magnitude σ). Given an initial approx feasible point, then BM computes a point that is approx feasible & approx optimal w.h.p. in $\text{poly}(n, \sigma^{-1})$ iterations.

Smoothed analysis [Spielman-Teng '01]

- Some practical algorithms are slow in a few instances.
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BM for SDP feasibility

Goal:

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Consider the least squares problem:

$$(\text{SDP}_{ls}) \quad \min_{X \in \mathbb{S}^n} \sum_i (A_i \bullet X - b_i)^2 \quad \text{s.t.} \quad X \succeq 0$$

The associated Burer-Monteiro problem is

$$(\text{BM}_{ls}) \quad \min_{Y \in \mathbb{S}^n} \sum_i (A_i \bullet YY^T - b_i)^2$$

Previous work on BM_{ls} relies on RIP [Bhojanapalli-Neyshabur-Srebro].

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Randomly perturb A_1, \dots, A_m (magnitude σ). Then BM_{IS} computes an approx feasible point w.h.p. in $\text{poly}(n, \sigma^{-1})$ iterations.

Optimality/Criticality conditions

$$\text{(SDP)} \quad \min \quad C \bullet X \quad \text{s.t.} \quad A_i \bullet X = b_i \text{ for } i \in [m], \quad X \succeq 0$$

Lemma

Assuming strong duality, X is optimal for SDP iff there exists λ such that

$$A_i \bullet X = b_i, \quad X \succeq 0, \quad S(\lambda)X = 0, \quad S(\lambda) \succeq 0,$$

where $S(\lambda) := C - \sum_i \lambda_i A_i$.

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$$\text{(BM)} \quad \min C \bullet YY^T \quad \text{s.t.} \quad A_i \bullet YY^T = b_i \text{ for } i \in [m]$$

Lemma

Y is a 2-critical point of BM iff there exists λ such that

$$A_i \bullet YY^T = b_i, \quad S(\lambda)Y = 0, \quad S(\lambda) \bullet UU^T \geq 0 \quad \forall U : A_i \bullet UY^T = 0$$

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Spurious critical points

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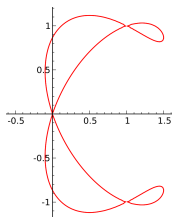
Theorem (Boumal-Voroninski-Bandeira)

Spurious critical points may only exist if

$$\mathcal{C} \in \mathcal{M} + \mathcal{L} \subset \mathbb{S}^n$$

where $\mathcal{M} = \{S : \text{rank} S \leq n-p\}$ and $\mathcal{L} = \text{span}\{A_1, \dots, A_m\}$

- Assume that $\binom{p+1}{2} > m$.
- $\mathcal{M} + \mathcal{L}$ is an *algebraic variety* of codimension $\binom{p+1}{2} - m$.
- Generically, no spurious points.



Approximate optimality/criticality

(SDP) X is δ -optimal if there exists λ such that

$$\|A_i \bullet X - b_i\| \leq \delta, \quad \|S(\lambda)X\| \leq \delta, \quad X \succeq 0, \quad S(\lambda) \succeq -\delta I_n.$$

(BM) Y is ϵ -critical for BM if there exists λ such that

$$\begin{aligned} \|A_i \bullet YY^T - b_i\| &\leq \epsilon, & \|S(\lambda)Y\| &\leq \epsilon^2, \\ S(\lambda) \bullet UU^T &\geq -\epsilon \quad \forall U : \|U\| \leq 1, & \|A_i \bullet UY^T\| &\leq \epsilon. \end{aligned}$$

Theorem (C.-Moitra)

Assume domain is smooth and compact. Given an approx feasible point, local optimization can produce an approx critical point in $\text{poly}(\epsilon^{-1})$.

Spurious approximate critical points

An ϵ -critical point Y of BM is **spurious** if YY^T is not δ -optimal for SDP, with $\delta = O(\epsilon)$.

Spurious approximate critical points

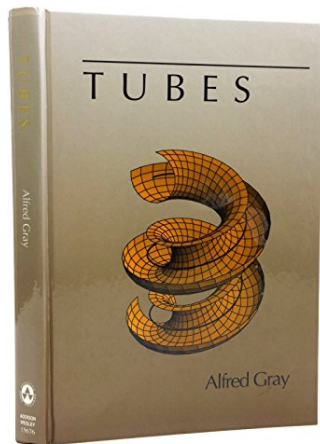
An ϵ -critical point Y of BM is **spurious** if YY^T is not δ -optimal for SDP, with $\delta = O(\epsilon)$.

Theorem (C.-Moitra)

Spurious ϵ -critical points may only exist if

$$C \in \text{tube}_\epsilon(\mathcal{M} + \mathcal{L}) \subset \mathbb{S}^n$$

where $\text{tube}_\epsilon(\mathcal{W}) := \{X : \text{dist}(X, \mathcal{W}) \leq \epsilon\}$



Volumes of tubes

Theorem (Weyl 1939)

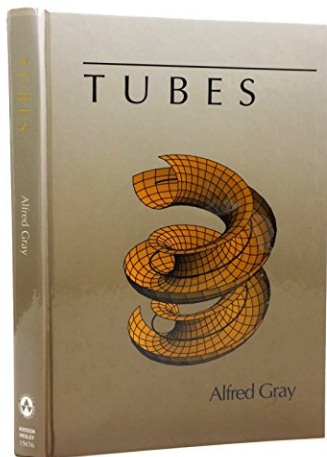
Let $V \subset \mathbb{R}^n$ manifold of codimension c . There are curvature constants $k_i(V)$ such that

$$\text{Vol}[\text{tube}_\epsilon(V)] = \sum_{i=c}^n k_i(V) \epsilon^i$$

Theorem (Lotz 2015)

Let $V \subset \mathbb{R}^n$ variety of codimension c defined by polynomials of degree D . Let x uniformly distributed on a ball of radius σ . Then

$$\Pr[x \in \text{tube}_\epsilon(V)] \leq O(nD\epsilon/\sigma)^c$$



Polytime optimality

Theorem (C.-Moitra)

Assumptions: $\binom{p+1}{2} > (1+\eta)m$, constraint set smooth and compact, solve BM with local method with 2nd order guarantees.

Randomly perturb C (magnitude σ). Given an approx feasible point, BM computes an approx optimal solution w.h.p. in $\text{poly}(n, \sigma^{-1})$ iterations.

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Proof.

Method converges to an ϵ -critical point in $\text{poly}(\epsilon^{-1})$. Using tubes,

$$\Pr[\text{spurious}] \leq \Pr[C \in \text{tube}_\epsilon(\mathcal{M} + \mathcal{L})] \leq \epsilon^{\binom{p+1}{2} - m} \cdot O(n^3/\sigma)^{\binom{p+1}{2}}$$

For $\binom{p+1}{2} > (1+\eta)m$ and $\epsilon = O(\sigma/n^3)^{1+1/\eta}$ the probability is tiny. \square

Polytime feasibility

$$(BM_{ls}) \quad \min_{Y \in \mathbb{S}^n} \sum_i (A_i \bullet YY^T - b_i)^2$$

Theorem (C.-Moitra)

Spurious ϵ -critical points may only exist if

$$\text{tube}_\epsilon(\mathcal{M}) \cap \mathcal{L} \text{ nontrivial}$$

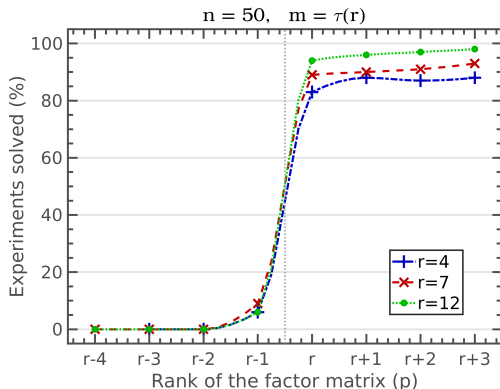
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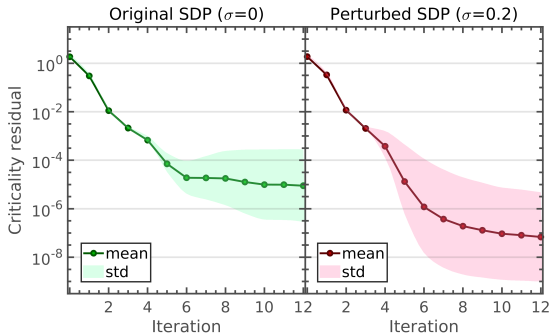
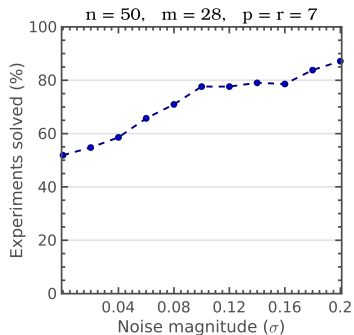
Experiments

- Generate planted matrix of rank r .
- Generate SDP for which planted matrix is optimal.
- Solve BM using augmented Lagrangians.



Experiments

- Fix an SDP instance for which BM behaves badly.
- Perturb the problem with small noise.
- Solve BM using augmented Lagrangians.



Summary

- We proved the first polynomial time guarantees for the Burer-Monteiro method.
- Guarantees work arbitrarily close to the Barvinok-Pataki bound.
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- D. Cifuentes, A. Moitra, *Polynomial time guarantees for the Burer-Monteiro method*, arXiv:1912.01745.
- D. Cifuentes *On the Burer-Monteiro method for general semidefinite programs*, arXiv:1904.07147.

Thanks for your attention

