

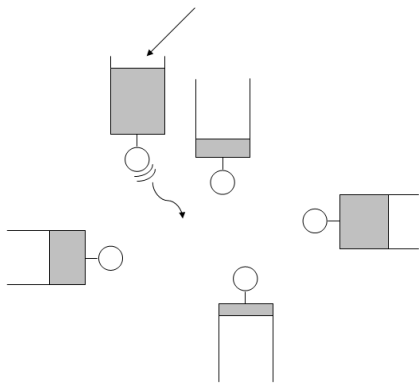
Positive Recurrent Medium Access Algorithm

Devavrat Shah* Jinwoo Shin[†] Prasad Tetali[†]

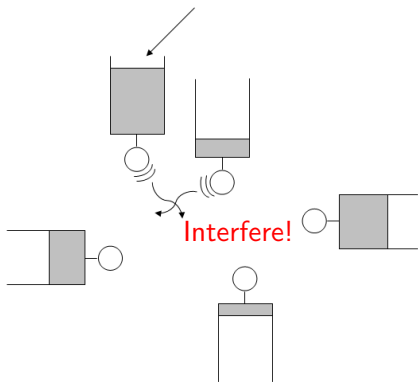
*LIDS, Massachusetts Institute of Technology

[†]Algorithms & Randomness Center, Georgia Institute of Technology

Medium Access Control (MAC) in Wireless Network



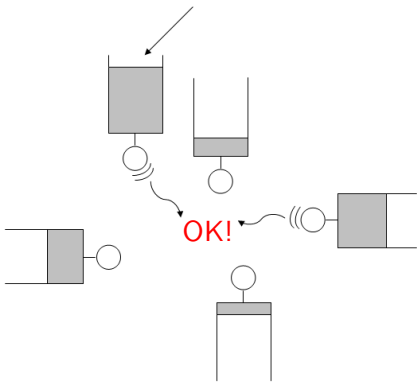
Medium Access Control (MAC) in Wireless Network



Constraints

- Interfering nodes can not transmit simultaneously.

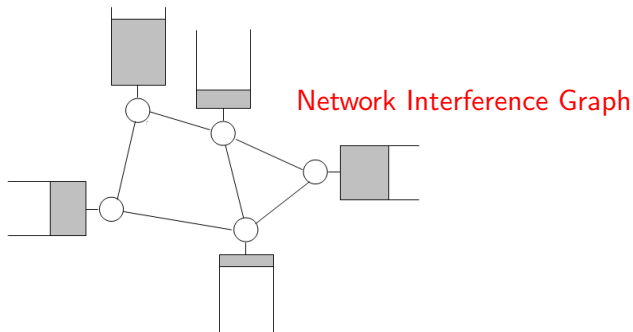
Medium Access Control (MAC) in Wireless Network



Constraints

- Interfering nodes can not transmit simultaneously.

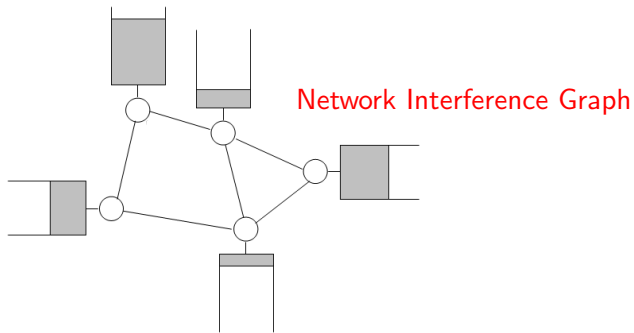
Medium Access Control (MAC) in Wireless Network



Constraints

- Interfering nodes can not transmit simultaneously.
- Nodes have only "local" information
 - Is any interfering neighbor transmitting ?

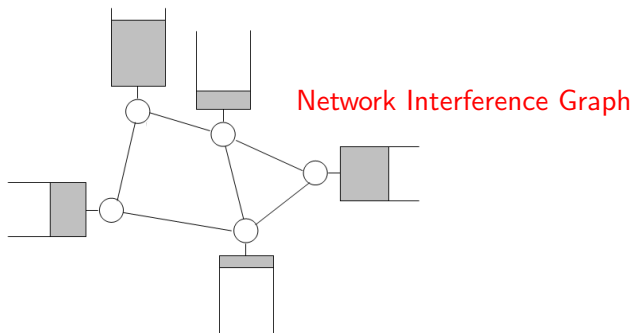
Medium Access Control (MAC) in Wireless Network



Question

- Which nodes should transmit simultaneously using local information.
- So that performance is not compromised.

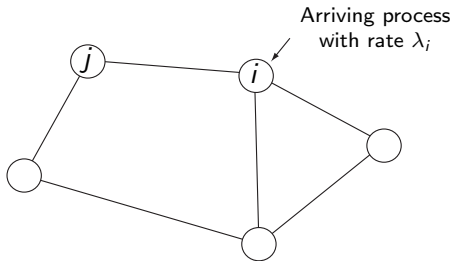
Medium Access Control (MAC) in Wireless Network



Goal

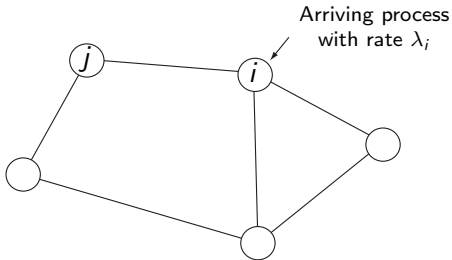
- Design an 'distributed', 'efficient' scheduling algorithm of 'high performance'
 - Decides transmission of non-interfering nodes

Model



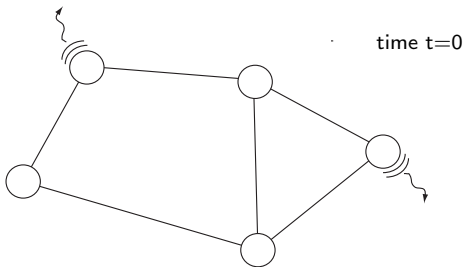
- Network interference graph $G = (V, E)$ with n queues as nodes
 - $E = \{(i, j) : i \text{ and } j \text{ cannot transmit simultaneously}\}$.
 - A packet arrives at queue i with probability λ_i at time $t \in \mathbb{Z}_+$.

Model



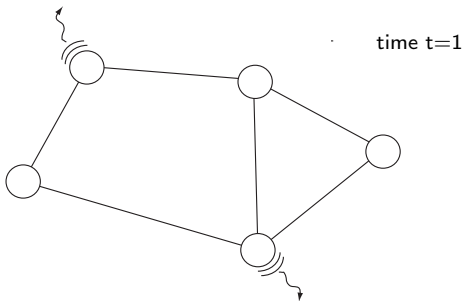
- Network interference graph $G = (V, E)$ with n queues as nodes
 - $E = \{(i, j) : i \text{ and } j \text{ cannot transmit simultaneously}\}$.
 - A packet arrives at queue i with probability λ_i at time $t \in \mathbb{Z}_+$.
- Scheduling algorithm: at each time instance $t \in \mathbb{Z}_+$
 - Selects non-interfering queues (to transmit) i.e. an **independent set** of G .
 - A packet in each selected queue departs (or serviced) from the network.

Model



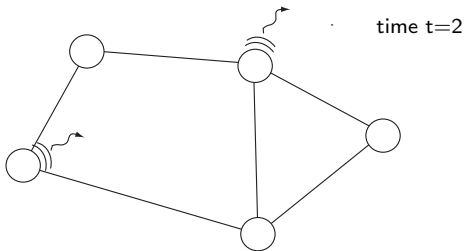
- Network interference graph $G = (V, E)$ with n queues as nodes
 - $E = \{(i, j) : i \text{ and } j \text{ cannot transmit simultaneously}\}$.
 - A packet arrives at queue i with probability λ_i at time $t \in \mathbb{Z}_+$.
- Scheduling algorithm: at each time instance $t \in \mathbb{Z}_+$
 - Selects non-interfering queues (to transmit) i.e. an **independent set** of G .
 - A packet in each selected queue departs (or serviced) from the network.

Model



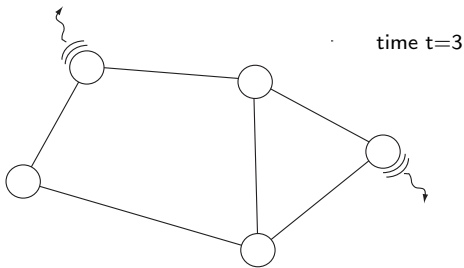
- Network interference graph $G = (V, E)$ with n queues as nodes
 - $E = \{(i, j) : i \text{ and } j \text{ cannot transmit simultaneously}\}$.
 - A packet arrives at queue i with probability λ_i at time $t \in \mathbb{Z}_+$.
- Scheduling algorithm: at each time instance $t \in \mathbb{Z}_+$
 - Selects non-interfering queues (to transmit) i.e. an **independent set** of G .
 - A packet in each selected queue departs (or serviced) from the network.

Model



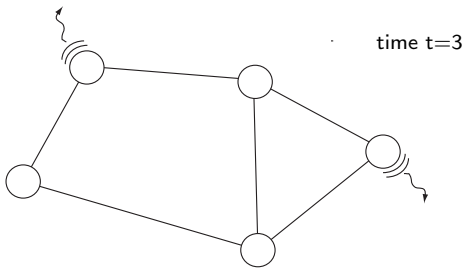
- Network interference graph $G = (V, E)$ with n queues as nodes
 - $E = \{(i, j) : i \text{ and } j \text{ cannot transmit simultaneously}\}$.
 - A packet arrives at queue i with probability λ_i at time $t \in \mathbb{Z}_+$.
- Scheduling algorithm: at each time instance $t \in \mathbb{Z}_+$
 - Selects non-interfering queues (to transmit) i.e. an **independent set** of G .
 - A packet in each selected queue departs (or serviced) from the network.

Model



- Network interference graph $G = (V, E)$ with n queues as nodes
 - $E = \{(i, j) : i \text{ and } j \text{ cannot transmit simultaneously}\}$.
 - A packet arrives at queue i with probability λ_i at time $t \in \mathbb{Z}_+$.
- Scheduling algorithm: at each time instance $t \in \mathbb{Z}_+$
 - Selects non-interfering queues (to transmit) i.e. an **independent set** of G .
 - A packet in each selected queue departs (or serviced) from the network.

Model



- Network interference graph $G = (V, E)$ with n queues as nodes
 - $E = \{(i, j) : i \text{ and } j \text{ cannot transmit simultaneously}\}$.
 - A packet arrives at queue i with probability λ_i at time $t \in \mathbb{Z}_+$.
- Scheduling algorithm: at each time instance $t \in \mathbb{Z}_+$
 - Selects non-interfering queues (to transmit) i.e. an **independent set** of G .
 - A packet in each selected queue departs (or serviced) from the network.
 - **Our primary interest is to design a distributed algorithm minimizing cooperations.**

Queueing Evolution

Notations

- $\mathbf{Q}(t) = [Q_i(t)]$ be the queue-sizes at time t .
- $\sigma_i(t) = \begin{cases} 1 & \text{if queue } i \text{ is transmitting (successfully) at time } t \\ 0 & \text{otherwise} \end{cases}$.
- $\sigma(t) = [\sigma_i(t)] \in \mathcal{J}(G) :=$ Collection of all independent sets in G .

$$Q_i(t+1) = Q_i(t) + A_i(t) - \sigma_i(t) \cdot \mathbf{1}_{\{Q_i(t) > 0\}}$$

- $\mathbf{A}(t) = [A_i(t)]$ be the number of arrival packets at queue i at time t .
- $\mathbb{E}[A_i(t)] = \lambda_i$.

Performance Metric

No common notion in the literature

- Want queues to be kept **small** under **large** arrival rate $\lambda = [\lambda_i]$.
- In our model, $\lambda \in \text{conv}(\mathcal{J}(G))$.
 - Otherwise, queues should grow linearly over time.

Performance Metric

No common notion in the literature

- Want queues to be kept **small** under **large** arrival rate $\lambda = [\lambda_i]$.
- In our model, $\lambda \in \text{conv}(\mathcal{J}(G))$.
 - Otherwise, queues should grow linearly over time.

Scheduling algorithm is

- Positive recurrent if Markov chain $(\mathbf{Q}(t), \sigma(t))$ is pos. rec. for $\lambda \in \text{conv}^\circ(\mathcal{J}(G))$.
 - Hence, queues remain finite with probability 1.
- Rate stable if $\mathbf{Q}(t)/t \rightarrow 0$ with probability 1 for $\lambda \in \text{conv}^\circ(\mathcal{J}(G))$.

Prior MAC Algorithms

Two Recent Research Directions

- I. Starting from [Jiang and Walrand 08]
 - Based on arrival-rate information λ

- II. Starting from [Rajagopalan, Shah and Shin 09]
 - Based on queueing information $\mathbf{Q}(t)$

MAC Algorithm: Example

Each individual queue i makes her own decision as

Attempt to transmit with probability $p_i(t)$ at time t .

MAC Algorithm: Example

Each individual queue i makes her own decision as

Attempt to transmit with probability $p_i(t)$ at time t .

- The transmission of i is successful at time t i.e. $\sigma_i(t) = 1$ if
 - i attempts to transmit at time t &
 - no collision i.e. no (interfering) neighbors of i attempts to transmit at time t

MAC Algorithm: Example

Each individual queue i makes her own decision as

Attempt to transmit with probability $p_i(t)$ at time t .

- The transmission of i is successful at time t i.e. $\sigma_i(t) = 1$ if
 - i attempts to transmit at time t &
 - no collision i.e. no (interfering) neighbors of i attempts to transmit at time t
- Known to be positive recurrent if
 - $p_i(t)$ is some polynomial of $\#$ prior consecutive collisions of i &
 - interference graph G is complete [Hastad et al. 96], bipartite [Goldberg et al. 99].

MAC Algorithm: Example

Each individual queue i makes her own decision as

Attempt to transmit with probability $p_i(t)$ at time t .

- The transmission of i is successful at time t i.e. $\sigma_i(t) = 1$ if
 - i attempts to transmit at time t &
 - no collision i.e. no (interfering) neighbors of i attempts to transmit at time t
- Known to be positive recurrent if
 - $p_i(t)$ is some polynomial of $\#$ prior consecutive collisions of i &
 - interference graph G is complete [Hastad et al. 96], bipartite [Goldberg et al. 99].
- Open question: How about general G ?

MAC Algorithm: Example

Each individual queue i makes her own decision as

Attempt to transmit with probability $p_i(t)$ at time t .

- The transmission of i is successful at time t i.e. $\sigma_i(t) = 1$ if
 - i attempts to transmit at time t &
 - no collision i.e. no (interfering) neighbors of i attempts to transmit at time t
- Known to be positive recurrent if
 - $p_i(t)$ is some polynomial of $\#$ prior consecutive collisions of i &
 - interference graph G is complete [Hastad et al. 96], bipartite [Goldberg et al. 99].
- **Open question: How about general G ?**
 - Next: some positive answers utilizing additional local information

MAC Algorithm using Carrier Sensing (CSMA)

Each individual queue i makes her own decision as

Attempt to transmit with probability $p_i(t)$ at time t .

$$p_i(t) = \begin{cases} 0 & \text{if some (interfering) neighbor attempted at time } t - 1 \\ 1 - \frac{1}{W_i(t)} & \text{else if } i \text{ attempted (to transmit) at time } t - 1 \\ \frac{1}{2} & \text{otherwise} \end{cases} .$$

- Carrier Sensing Information
 - Knowledge whether neighbors attempted to transmit (at the previous time-slot).

MAC Algorithm using Carrier Sensing (CSMA)

Each individual queue i makes her own decision as

Attempt to transmit with probability $p_i(t)$ at time t .

$$p_i(t) = \begin{cases} 0 & \text{if some (interfering) neighbor attempted at time } t - 1 \\ 1 - \frac{1}{W_i(t)} & \text{else if } i \text{ attempted (to transmit) at time } t - 1 \\ \frac{1}{2} & \text{otherwise} \end{cases} .$$

- Carrier Sensing Information
 - Knowledge whether neighbors attempted to transmit (at the previous time-slot).
- Next: Two known successful designs of $W_i(t)$
 - Using arrival-rate information λ [Jiang and Walrand 08]
 - Using queueing information $\mathbf{Q}(t)$ [Rajagopalan, Shah and Shin 09]

CSMA I using Arrival-rate Information

Theorem (Jiang and Walrand 08)

For given arrival rate $\lambda \in \text{conv}^\circ(\mathcal{J}(G))$, there exists $\mathbf{W}^* = \mathbf{W}^*(\lambda, G)$ such that

CSMA using $W_i(t) = W_i^$ is rate stable.*

CSMA I using Arrival-rate Information

Theorem (Jiang and Walrand 08)

For given arrival rate $\lambda \in \text{conv}^\circ(\mathcal{J}(G))$, there exists $\mathbf{W}^* = \mathbf{W}^*(\lambda, G)$ such that

CSMA using $W_i(t) = W_i^$ is rate stable.*

- To find W_i^* at node i (in a distributed manner, without message-passing)
 - Require appropriate updating rule/period of $W_i(t)$
 - So that $W_i(t)$ converges to W_i^* .

CSMA I using Arrival-rate Information

Theorem (Jiang and Walrand 08)

For given arrival rate $\lambda \in \text{conv}^\circ(\mathcal{J}(G))$, there exists $\mathbf{W}^* = \mathbf{W}^*(\lambda, G)$ such that

CSMA using $W_i(t) = W_i^*$ is rate stable.

- To find W_i^* at node i (in a distributed manner, without message-passing)
 - Require appropriate updating rule/period of $W_i(t)$
 - So that $W_i(t)$ converges to W_i^* .
 - Design such an updating period for rate stability.
[Jiang, Shah, Shin and Walrand 09]

CSMA I using Arrival-rate Information

Theorem (Jiang and Walrand 08)

For given arrival rate $\lambda \in \text{conv}^\circ(\mathcal{J}(G))$, there exists $\mathbf{W}^* = \mathbf{W}^*(\lambda, G)$ such that

CSMA using $W_i(t) = W_i^*$ is rate stable.

- To find W_i^* at node i (in a distributed manner, without message-passing)
 - Require appropriate updating rule/period of $W_i(t)$
 - So that $W_i(t)$ converges to W_i^* .
 - Design such an updating period for rate stability.
[Jiang, Shah, Shin and Walrand 09]
- However, should assume that λ is possible to estimate.
 - In practice, λ is difficult to collect/know in many applications.

CSMA I using Arrival-rate Information

Theorem (Jiang and Walrand 08)

For given arrival rate $\lambda \in \text{conv}^\circ(\mathcal{J}(G))$, there exists $\mathbf{W}^* = \mathbf{W}^*(\lambda, G)$ such that

CSMA using $W_i(t) = W_i^*$ is rate stable.

- To find W_i^* at node i (in a distributed manner, without message-passing)
 - Require appropriate updating rule/period of $W_i(t)$
 - So that $W_i(t)$ converges to W_i^* .
 - Design such an updating period for rate stability.
[Jiang, Shah, Shin and Walrand 09]
- However, should assume that λ is possible to estimate.
 - In practice, λ is difficult to collect/know in many applications.
- Question: Possible to design $\mathbf{W}(t)$ using queueing information?

CSMA II using Queueing Information

Theorem (Shah and Shin 10)

CSMA is positive recurrent if

$$W_i(t) = \max \left\{ \log Q_i(t), e^{\sqrt{\log \log Q_{\max}(t)}} \right\},$$

where $Q_{\max}(t) = \max_i Q_i(t)$.

CSMA II using Queueing Information

Theorem (Shah and Shin 10)

CSMA is positive recurrent if

$$W_i(t) = \max \left\{ \log Q_i(t), e^{\sqrt{\log \log Q_{\max}(t)}} \right\},$$

where $Q_{\max}(t) = \max_i Q_i(t)$.

- Myopic & robust against the arrival assumption.

CSMA II using Queueing Information

Theorem (Shah and Shin 10)

CSMA is positive recurrent if

$$W_i(t) = \max \left\{ \log Q_i(t), e^{\sqrt{\log \log Q_{\max}(t)}} \right\},$$

where $Q_{\max}(t) = \max_i Q_i(t)$.

- Myopic & robust against the arrival assumption.
- To compute $W_i(t)$, it requires to know global information $Q_{\max}(t)$.

CSMA II using Queueing Information

Theorem (Shah and Shin 10)

CSMA is positive recurrent if

$$W_i(t) = \max \left\{ \log Q_i(t), e^{\sqrt{\log \max_{j \in \mathcal{N}(i)} W_j(t-1)}} \right\},$$

where $Q_{\max}(t) = \max_i Q_i(t)$.

- Myopic & robust against the arrival assumption.
- To compute $W_i(t)$, it requires to know global information $Q_{\max}(t)$.

CSMA II using Queueing Information

Theorem (Shah and Shin 10)

CSMA is positive recurrent if

$$W_i(t) = \max \left\{ \log Q_i(t), e^{\sqrt{\log \max_{j \in \mathcal{N}(i)} W_j(t-1)}} \right\},$$

where $Q_{\max}(t) = \max_i Q_i(t)$.

- Myopic & robust against the arrival assumption.
- To compute $W_i(t)$, it requires to know global information $Q_{\max}(t)$.
 - Still require some explicit message passing (minimal though)

CSMA II using Queueing Information

Theorem (Shah and Shin 10)

CSMA is positive recurrent if

$$W_i(t) = \max \left\{ \log Q_i(t), e^{\sqrt{\log \max_{j \in \mathcal{N}(i)} W_j(t-1)}} \right\},$$

where $Q_{\max}(t) = \max_i Q_i(t)$.

- Myopic & robust against the arrival assumption.
- To compute $W_i(t)$, it requires to know global information $Q_{\max}(t)$.
 - Still require some explicit message passing (minimal though)

Main Result of This Talk

- We revise the algorithm so that it does not require such message passing.

CSMA II using Queueing Information

Theorem (Shah and Shin 10)

CSMA is positive recurrent if

$$W_i(t) = \max \left\{ \log Q_i(t), e^{\sqrt{\log \max_{j \in \mathcal{N}(i)} W_j(t-1)}} \right\},$$

where $Q_{\max}(t) = \max_i Q_i(t)$.

- Myopic & robust against the arrival assumption.
- To compute $W_i(t)$, it requires to know global information $Q_{\max}(t)$.
 - Still require some explicit message passing (minimal though)

Main Result of This Talk

- We revise the algorithm so that it does not require such message passing.
 - Motivation : Possible to learn $W_j(t)$ using carrier sensing without message passing?

Main Issue: Online Learning Problem

How to learn weights of neighbors without message passing?

- Equivalent question: how to learn access probabilities of (interfering) neighbors?
 - since recall access probability $p_i(t) = 1 - \frac{1}{W_i(t)}$.

Main Issue: Online Learning Problem

How to learn weights of neighbors without message passing?

- Equivalent question: how to learn access probabilities of (interfering) neighbors?
 - since recall access probability $p_i(t) = 1 - \frac{1}{W_i(t)}$.
- May be possible using carrier sensing information since

Access probability \approx How often attempt \approx Carrier Sensing

Main Issue: Online Learning Problem

How to learn weights of neighbors without message passing?

- Equivalent question: how to learn access probabilities of (interfering) neighbors?
 - since recall access probability $p_i(t) = 1 - \frac{1}{W_i(t)}$.

- May be possible using carrier sensing information since

Access probability \approx How often attempt \approx Carrier Sensing

- Non-trivial online learning problem since
 - $W_j(t)$ is changing

Main Issue: Online Learning Problem

How to learn weights of neighbors without message passing?

- Equivalent question: how to learn access probabilities of (interfering) neighbors?
 - since recall access probability $p_i(t) = 1 - \frac{1}{W_i(t)}$.

- May be possible using carrier sensing information since

Access probability \approx How often attempt \approx Carrier Sensing

- Non-trivial online learning problem since
 - $W_j(t)$ is changing
 - # samples is affected by many random environments

Main Issue: Online Learning Problem

How to learn weights of neighbors without message passing?

- Equivalent question: how to learn access probabilities of (interfering) neighbors?
 - since recall access probability $p_i(t) = 1 - \frac{1}{W_i(t)}$.
- May be possible using carrier sensing information since

Access probability \approx How often attempt \approx Carrier Sensing

- Non-trivial online learning problem since
 - $W_j(t)$ is changing
 - # samples is affected by many random environments
 - how much error is allowed for positive recurrence?

New Algorithm with Learning

Recall the original positive recurrent algorithm

- When the medium is free, each queue i attempts to transmit with probability

$$1 - \frac{1}{W_i(t)} = 1 - \frac{1}{\max \left\{ \log Q_i(t), e^{\sqrt{\log \max_{j \in \mathcal{N}(i)} W_j(t-1)}} \right\}}.$$

New Algorithm with Learning

Revise the original positive recurrent algorithm using estimator L_j^i

- When the medium is free, each queue i attempts to transmit with probability

$$1 - \frac{1}{W_i(t)} = 1 - \frac{1}{\max \left\{ \log Q_i(t), e^{\sqrt{\log \max_{j \in \mathcal{N}(i)} L_j^i(t)}} \right\}}.$$

New Algorithm with Learning

Revise the original positive recurrent algorithm using estimator L_j^i

- When the medium is free, each queue i attempts to transmit with probability

$$1 - \frac{1}{W_i(t)} = 1 - \frac{1}{\max \left\{ \log Q_i(t), e^{\sqrt{\log \max_{j \in \mathcal{N}(i)} L_j^i(t)}} \right\}}.$$

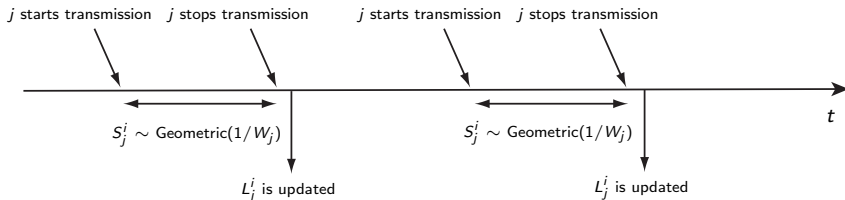
In addition, each queue i maintains $L_j^i(t)$, $S_j^i(t)$ for $j \in \mathcal{N}(i)$: for some function g

- If $\sigma_j(t-1) = 1$, $S_j^i(t) = S_j^i(t-1) + 1$.
- Else if $S_j^i(t-1) > 0$, $S_j^i(t) = 0$ and

$$L_j^i(t) = \begin{cases} L_j^i(t-1) + \Delta & \text{if } S_j^i(t-1) \geq L_j^i(t-1) \\ L_j^i(t-1) - \Delta & \text{otherwise} \end{cases}, \quad \text{where } \Delta = \frac{1}{g(L_j^i(t-1))}.$$

★ $L_j^i(t)$ and $S_j^i(t)$ are long-term and temporal estimators of $W_j(t)$ at queue i , respectively.

New Algorithm with Learning



In addition, each queue i maintains $L_j^i(t)$, $S_j^i(t)$ for $j \in \mathcal{N}(i)$: for some function g

- If $\sigma_j(t-1) = 1$, $S_j^i(t) = S_j^i(t-1) + 1$.
- Else if $S_j^i(t-1) > 0$, $S_j^i(t) = 0$ and

$$L_j^i(t) = \begin{cases} L_j^i(t-1) + \Delta & \text{if } S_j^i(t-1) \geq L_j^i(t-1) \\ L_j^i(t-1) - \Delta & \text{otherwise} \end{cases}, \quad \text{where } \Delta = \frac{1}{g(L_j^i(t-1))}.$$

★ $L_j^i(t)$ and $S_j^i(t)$ are **long-term** and **temporal** estimators of $W_j(t)$ at queue i , respectively.

New Algorithm: Positive Recurrence

Theorem (Shah, **Shin** and Tetali)

The network Markov chain induced by the revised algorithm is positive recurrent if

$$\lambda \in \text{conv}^\circ(\mathcal{J}(G)) \quad \text{and} \quad g(x) = e^{e^{\log^{1/4} x}}.$$

New Algorithm: Positive Recurrence

Theorem (Shah, **Shin** and Tetali)

The network Markov chain induced by the revised algorithm is positive recurrent if

$$\lambda \in \text{conv}^\circ(\mathcal{J}(G)) \quad \text{and} \quad g(x) = e^{e^{\log^{1/4} x}}.$$

- In the proof, we use the following Lyapunov function

$$F(t) = \sum_i h(Q_i(t)) + \sum_{i,j} g(L_j^i(t))^2 + \sum_{i,j} g(S_j^i(t)),$$

where $h = \int \log \log$.

New Algorithm: Positive Recurrence

Theorem (Shah, **Shin** and Tetali)

The network Markov chain induced by the revised algorithm is positive recurrent if

$$\lambda \in \text{conv}^\circ(\mathcal{J}(G)) \quad \text{and} \quad g(x) = e^{e^{\log^{1/4} x}}.$$

- In the proof, we use the following Lyapunov function

$$F(t) = \sum_i h(Q_i(t)) + \sum_{i,j} g(L_j^i(t))^2 + \sum_{i,j} g(S_j^i(t)),$$

where $h = \int \log \log$.

- Main additional techniques
 - Careful martingale arguments to control L_j^i .

New Algorithm: Positive Recurrence

Theorem (Shah, **Shin** and Tetali)

The network Markov chain induced by the revised algorithm is positive recurrent if

$$\lambda \in \text{conv}^\circ(\mathcal{J}(G)) \quad \text{and} \quad g(x) = e^{e^{\log^{1/4} x}}.$$

- In the proof, we use the following Lyapunov function

$$F(t) = \sum_i h(Q_i(t)) + \sum_{i,j} g(L_j^i(t))^2 + \sum_{i,j} g(S_j^i(t)),$$

where $h = \int \log \log$.

- Main additional techniques
 - Careful martingale arguments to control L_j^i .
 - 'Hitting time' of Markov chains.

Summary & Wide-applicability

In summary

- We present a myopic, positive recurrent MAC algorithm, where individual queues
 - Use only local & primitive (carrier sensing) information
 - Performs few logical operations per each time.

Summary & Wide-applicability

In summary

- We present a myopic, positive recurrent MAC algorithm, where individual queues
 - Use only local & primitive (carrier sensing) information
 - Performs few logical operations per each time.
 - It essentially simulates the max weight algorithm [Tassiulas and Ephremides 92].

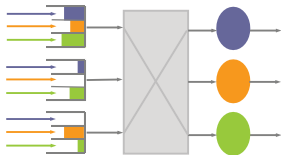
Summary & Wide-applicability

In summary

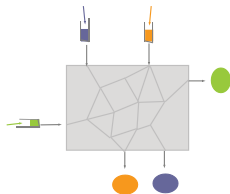
- We present a myopic, positive recurrent MAC algorithm, where individual queues
 - Use only local & primitive (carrier sensing) information
 - Performs few logical operations per each time.
 - It essentially simulates the max weight algorithm [Tassiulas and Ephremides 92].

Our framework to design such algorithms has wide-applicability

- In the context of stochastic processing networks [Harrison 00].



High speed switch scheduling
(Matching constraints)



Scheduling in optical core networks
(Multi-commodity-type constraints)