The intermediate density scaling regime



Previous work on the scaling behavior of capacity of ad hoc networks studied two regimes: the dense regime, where an increasing number of nodes is placed in a fixed area: and the extended regime, where area and the number of nodes scale identically.

We aim to study a regime where the scaling of area is treated as a free parameter.

This is joint work with A. Ozgur and O. Leveque (EPFL) and D. Tse (Berkeley).

We characterize the capacity of a random ad hoc network model when area scales independently of the number of nodes.

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The scaling regime we consider reveals optimal communication strategies as we vary the area scaling and the path loss.

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Physical area is a fundamentally distinct parameter from network size, and should be allowed to scale independently



We are interested in developing a parsimonious characterization of the various *operating regimes* for wireless networks, and how these operating regimes depend on engineering parameters such as:

- Number of nodes
- Power
- Area
- Path loss characteristics

Joint work with A. Ozgur, O. Leveque, D. Tse.

Prior results on scaling

Two main network models:

- Dense networks: Area held constant, and number of nodes → 1
- Extended networks: Area increases proportional to number of nodes

Starting with Gupta and Kumar (2000), where the dense network model was studied under a multihop transmission strategy, various works studied performance in these regimes.

Most recently Ozgur et al. (2007) characterized scaling laws for capacity in both dense and extended networks.



Our approach here: area should be a distinct parameter!

• We consider a random network model where n nodes are located uniformly at random in an area A.

As we only consider scaling behavior of capacity, we assume A = n^{β} , where $\beta \downarrow 0$.

- Nodes are grouped into random source-destination pairs, with uniform traffic matrix.
- We assume that each node has a transmit power constraint P that does not scale with n, and that the path loss exponent is α.

Upper bound on capacity

We employ a cutset bound.

For presentation simplicity, consider 1-D.

Start by considering n^γ sources transmitting to n^γ destinations, separated by n^γ nodes:



Using an analog of the argument in Ozgur et al., we can show that the capacity of this system is exactly the cutset bound for the full 1-D network.

Upper bound on capacity



By showing that independent transmissions give the upper bound, then adding together received power from all transmit nodes, we obtain:

C(S, D) · $n^{\gamma} \notin O(\min\{ n^{(1-\beta)\alpha + \gamma(1-\alpha)}, 1\}).$

Thus the best exponent is:

 $\max_{0 \cdot \gamma \cdot 1} \min \{(2 - \alpha)\gamma + (1 - \beta)\alpha, \gamma\}$

We refer to the optimizing value γ^* as the optimal cluster size.

Achievability



• When $\beta > 1$:

The network is "overextended", but capacity achieving schemes are identical to extended network (cf. Ozgur et al.): hierarchical cooperation with MIMO if $\alpha < 2$, multihop if $\alpha > 2$.

When β < 1:

If $\alpha < 1/\beta$ or $\alpha < 2$,

then hierarchical cooperation is optimal.

If $\alpha > 1/\beta$ and $\alpha > 2$:

Neither hierarchical cooperation nor multihop is optimal!

Achievability



- We consider a scheme that uses multihop transmission at the level of clusters; each hop is realized using hierarchical cooperation via MIMO.
- Suppose we use the optimal cluster size, and consider two adjacent clusters of size n^{y*}.
- These two clusters can be equivalently viewed as a dense network with O(n^{γ*}) nodes and per node power constraint P¢ (A n^{γ*} /n)^{-α}.
- Our key insight is that this per node power constraint is equal to P $/n^{\gamma^*}$, which is exactly the power threshold needed to execute the hierarchical cooperation scheme of Ozgur et al. in dense networks.
- Thus between adjacent clusters, hierarchical cooperation suffices to achieve throughput $O(n^{\gamma*})$.

Summary



Treating area as a free parameter leads to a new, "intermediate density" operating regime with a new transmission scheme: Multihop transmission between clusters, with hierarchical cooperation via MIMO to achieve cluster-to-cluster hops.

The diagram on the first slide is the generalization to 2-D, and demonstrates how the optimal scheme depends on the area scaling and the path loss exponent.

However, this is still not a complete story: we are still investigating whether there is a unifying perspective that resolves the different schemes present in that diagram.