Capacity Definitions of Composite Channels with Receiver Side Information

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Shannon Capacity Definition for General Channels and Limitations

Information Stable Channels

- Input/output behave ergodically
- Memoryless channels [Shannon 1948] $C = \max_{X} I(X;Y)$
- With memory [Dobrushin 1963] $C = \limsup_{n \to \infty} \frac{1}{n} I(X^n; Y^n)$

General Channels: [Verdu & Han 1994]

- Normalized mutual information $(1/n)I(X^n;Y^n)$ by diverge
- Distribution of information density

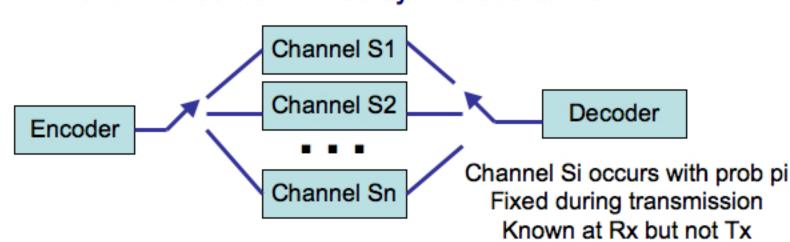
$$\frac{1}{n}i_{X^{n}W^{n}}(a^{n};b^{n}) = \frac{1}{n}\log\frac{P_{Y^{n}|X^{n}}(b^{n}|a^{n})}{P_{Y^{n}}(b^{n})}$$
• Relationship $I(X^{n};Y^{n}) = \mathbf{E}\left\{i_{X^{n}W^{n}}(X^{n};Y^{n})\right\}$

Shannon Capacity for General Channels:

- Iiminf in probability of normalized information density
- Example: composite channels (information unstable)

$$C = \sup_{X} \underline{I}(X; Y \mid S) = \sup_{X} \sup \{\alpha : \lim \Pr[(1/n) i_{X^n W^n}(X^n; Y^n \mid S) \le \alpha] = 0\}$$

- mixture of stationary ergodic channels
- include slowly fading wireless channels
- Performance dominated by "worst channel"



Limitations of Shannon Capacity Definition

- Choice of codebook
 - A single encoder/decoder under Shannon definition
 - Reasonable to assume a single encoder without CSIT
 - Choice of different decoders with CSIR?

• Rethinking: transmitted rate received rate

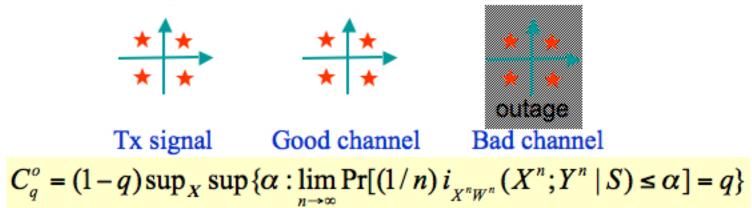
- Shannon: ALL Tx information decoded at ALL time
- Relax the constraint:
 - Decode portion of the time?
 - Decode partial information?

 Expected capacity
- Combined —— Expected capacity with outage

Alternative Definition: Outage Capacity

Outage Capacity

- Decode portion (1-q) of the time
- In non-outage states, transmit rate Rt = receive rate Rr



- Direct generalization of Shannon capacity $C = C_0^o$
- q can be chosen to max C_a^o
- When outage occurs

Example 1: Gilbert-Elliott Channel with Different Configurations

- ARQ for retransmission
- Approximate unreliable data from surroundings

Alternative Definitions: Expected Capacity and Expected Capacity with Outage

Refined characterization

Expected Capacity

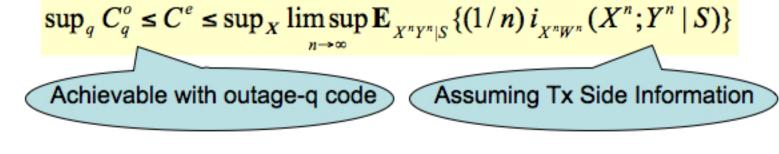
Decode all the time

Coarse characterization

Partial decoding, receive rate Rr(s) <= transmit rate Rt



- Definition: supremum of
- Capacity Bounds



 $\mathbf{E}_{s}R_{s}$ rith

Broadcast Channel Codes for Expected Capacity

- Channel states virtual multiple receivers
- BC strategy for slowly fading channels [Shamai 2003]
- Gilbert-Elliott channel, BSC with random crossover prob

Expected Capacity with Outage

• $C_q^e \ge \sup_{\varepsilon \ge 0} C_{q+\varepsilon}^o$ achievable with outage $(q+\varepsilon)$ be $C_q^e \le (1-q) \sup_X \sup_n \limsup_{n \to \infty} \mathbf{E} \left\{ \frac{1}{n} i(X^n; Y^n \mid S) \middle| \frac{1}{n} i(X^n; Y^n \mid S) > \alpha \right\}$ Subject to outage constraint Assuming CSIT for non-outage states

- Two-state Markov Chain
- Initial state distribution $\epsilon_G^{\pi_G}$ π_B
- Stationarity and ergodicity varies with channel parameters
- Case 1: Stationary and Ergodic $\pi_G = g/(g+b), \pi_B = b/(g+b)$

• Shannon capacity = Expected Capacity = $\pi_G C_G + \pi_B C_B$

- Outage C (expected C with outage) = $(1-q)(\pi_{G}C_{G} + \pi_{R}C_{R})$
- Case 2: Nonstationary and Ergodic $\pi_G \neq g/(g+b), b \neq 0, g \neq 0$
 - Effect of initial state distribution: transient
 - All four capacity definitions same with Case 1

• Case 3: Stationary and Nonergodic b = g = 0

- Initial state chosen according to $\{\pi_G, \pi_B\}$ in fixed
- Shannon Capacity $C = C_B = 1 h(p_B)$ h(p) binary entropy
- Outage capacity $C_q^o = (1-q)C_B$ $q < \pi_B$ rerwise $C_q^o = (1-q)C_G$
- Expected capacity $\max_{0 \le r \le 1/2} 1 h(r * p_B) + \pi_G[h(r * p_G) h(p_G)]$ where a*b = a(1-b) + b(1-a), binary convolution
 - strictly less than $\pi_G C_G + \pi_B C_B$ loss incurred from lack of CSIT
 - BC code achieves 1-h(r*p_B) for bad channel,
 and additional h(r*p_G)-h(p_G) for good channel

Example 2: Binary Symmetric Channel with Random Crossover Probabilities

• Random crossover probability p with distribution f(p), $0 \le p \le (1/2)$ corresponding cdf F(p)

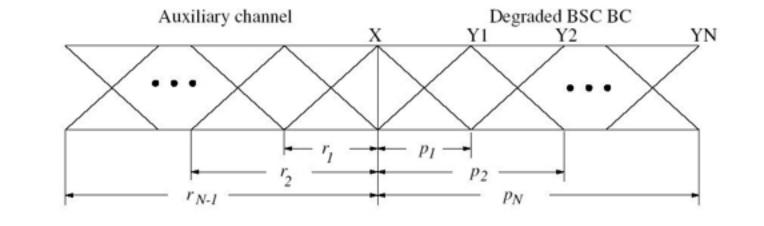
• Outage capacity, $C_q^o = (1-q)[1-h(p_q)]$ th $p_q = \inf\{p: F(p) \ge 1-q\}$

Shannon capacity C = 1 - h(p*), where p* = inf{p: F(p) = 1}

stochastically degraded BC

· capacity region traced by augmenting auxiliary channels

cascade of BSC



In continuous case: define increasing function r(p) as overall crossover prob of auxiliary channels up to that indexed by p

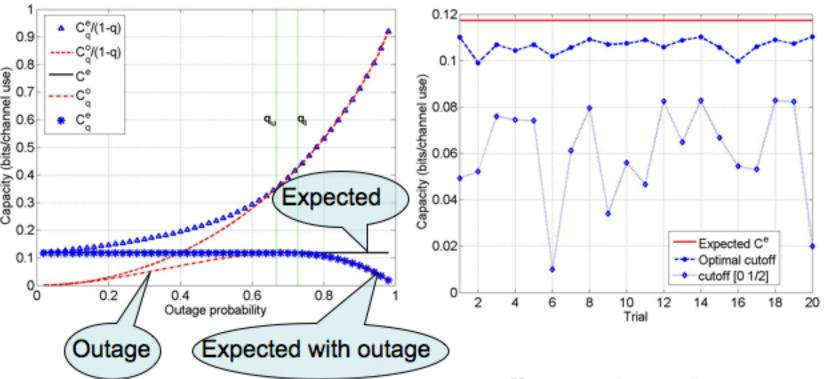
Incremental rate for layer p $|dR(p)| = h(p*r_p) - h(p*r_{p-dp})$ Expected rate $C^e = \max_{r(p)} \int_0^{1/2} f(p)R(p)dp = -\max_{r(p)} \int_0^{1/2} F(p)dR(p)$ optimization solved by functional analysis and Euler eqn

Expected Capacity with outage:

Same as Ce of a modified composite channel with pdf

$$\widetilde{f}(p) = \begin{cases} f(p)/(1-q), & p \le p \\ 0, & p > p_q \end{cases}$$

Numerical example: uniformly distributed f(p) on [0,1/2]



- Shannon capacity = 0
- cutoff range [p_I, p_U] captures most benefit from optimization
- Nonzero incremental rate dR(p) only for $0.136 = p_l \le p \le p_u = 1/6$

Future Work: Joint Source-Channel Coding

New end-to-end performance metric: expected distortion

- Multi-resolution source code (SC) combined with BC channel code (CC): rates in BC region to min expected distortion
- •Distortion with multi-resolution SC: Gaussian source successively refinable, bounds exist for general sources
- •Transmit over two parallel non-ergodic links [Effros et al 04]: compare with multi-description SC and time-sharing CC

Non-ergodic sources

- Ergodic source/channel separation: simple interface H<C
- Source/Channel codes separable without loss for some notion of capacity and some end-to-end performance metric?
- In case separation fails, choice of interface? Performance vs. complexity tradeoff1