

Canonical vs Micro-Canonical Sampling Methods in a 2D Ising model¹

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December, 1990

¹This work was supported in part by the Applied Mathematical Sciences subprogram of the Office of Energy Research, U.S. Department of Energy under Contract DE-AC03-76SF00098.

KEYWORDS

2D Ising Model, Micro-Canonical, Specific Heat

ABSTRACT

Canonical and micro-canonical Monte Carlo algorithms were implemented on a 2D Ising model. Expressions for the internal energy, U , inverse temperature, Z , and specific heat, C , are given. These quantities were calculated over a range of temperatures, lattice sizes, and time steps. Both algorithms accurately simulate the Ising model. To obtain greater than three decimal accuracy from the micro-canonical method requires that the more complicated expression for Z be used. The overall difference between the algorithms is small. The physics of the problem under study should be the deciding factor in determining which algorithm to use.

1. INTRODUCTION

In the study of phase transitions and other critical phenomena the Monte Carlo method has emerged as one of the most powerful simulation techniques—canonical and micro-canonical being just two of the more common approaches. Determining which is best for a particular problem can be difficult. It is the goal of this paper to help the researcher by comparing the ability of these two algorithms to simulate a 2D Ising model, with an emphasis on illustrating the differences in behavior and accuracy as a function of temperature and lattice size.

In the canonical approach, one computes the state of each point from the previous state using a random number generator. Usually, each state is weighted according to a probability proportional to the Boltzman factor $\exp(-E/kT)$, with E being the energy of the state [1].

The micro-canonical Monte Carlo method consists of constraining the total energy of the system, while letting the energy distribution evolve. The transfer of energy is carried out by a new set of variables, called demons, which correspond to the kinetic energy in molecular dynamics calculations [2].

2. THE UPDATING ALGORITHMS

In both algorithms, the central operations are performed on a lattice of spins, S , that are either up (+1) or down (-1). For our model, we will define the energy of a particular site i as

$$E_i = \sum (1 - S_i S_j), \quad (1)$$

where the sum is over the four nearest neighbors j of i [3]. This has the operational effect of making a lattice with aligned spins have lower energy than an unaligned lattice. Note that flipping the spin of i produces a change in energy

$$\Delta E_i = 2 \sum S_i S_j. \quad (2)$$

A quantity of particular interest in our experiments is the internal energy, U . In terms of the previous notation

$$-U = \frac{1}{2} - \frac{1}{2N} \sum_{i=1}^N E_i, \quad (3)$$

where N is the number of points in the lattice. In the limiting case of $N \rightarrow \infty$, U is known exactly

$$U = \frac{1 + [2 \tanh^2(H) - 1] 2K(k_1)/\pi}{\tanh(H)}, \quad (4)$$

where $H = 2Z$, $k_1 = 2 \sinh(H)/\cosh^2(H)$, and $K(k_1) = F(\pi/2|k_1)$ is the complete elliptic integral of the first kind [4,5]. This provides a way to compare the two algorithms.

Having defined the spin structure and the energy, the canonical scheme for changing spins can best be explained by the following piece of pseudo-code:

r = random number between 0 and 1

$B = \exp(-\Delta E_i Z)$

if ($r < B$) **then**

$S_i = -S_i$

endif

where the temperature, $T = 1/Z$, is an input parameter of the program [6]. Executing the above procedure on every site in the lattice constitutes one iteration, or time step, of the algorithm.

The micro-canonical procedure is a bit more complicated. In addition to the spin lattice, we have a corresponding lattice of demons, D . Each element in D , D_i , is restricted by the condition that $D_i \in \{0, 1, 2, \dots, D_{\max}\}$. D_i can be thought of as the kinetic energy conjugate to the i^{th} point in the lattice. The most important property of the micro-canonical updating algorithm is that the energy at each point be conserved

$$E_i + 4D_i = \text{constant} \Rightarrow E_T = 4 \sum_{i=1}^N D_i + \sum_{i=1}^N E_i, \quad (5)$$

where E_T is the total energy of the lattices. Eq. (5) illustrates the central difference between the two algorithms. Canonical sampling selects configurations based on their Boltzman weight, while micro-canonical sampling selects configurations that satisfy the total energy constraint of Eq. (5). As a consequence of Eq. (5)

$$\Delta E_i + 4\Delta D_i = 0, \quad (6)$$

which gives some insight as to how to construct the updating algorithm. The spin flipping procedure used in our experiments was equivalent to the following code fragment:

```

Di' = (4Di - ΔEi)/4
if (0 ≤ Di' ≤ Dmax) then
    Di = Di'
    Si = -Si
endif [7]

```

The factor of four comes about from the property—obtained from Eq. (1)—that $\Delta E_i \in \{-8, 4, 0, 4, 8\}$. A convenient way of running the program is to have each demon unit correspond to the smallest change in ΔE_i . For a detailed explanation of implementing this algorithm see ref. [8].

Eq. (6) obeys the principle of detailed balance [9], implying that S and D are governed by traditional thermodynamic principles. This provides an intuitive rational for believing that the micro-canonical algorithm works. As the system evolves, the demons become distributed according to their Boltzman factors. The demon average will then be related to the temperature by

$$\frac{1}{N} \sum_{i=1}^N D_i = \langle D_i \rangle = \frac{\sum \gamma \exp(-4\gamma Z)}{\sum \exp(-4\gamma Z)}, \quad (7)$$

where the sums are carried out from $\gamma = 0$ to D_{\max} . Given a particular state D, $\langle D_i \rangle$ can be calculated, and Eq. (5) can be numerically inverted to find the temperature. Thus, the temperature is an output rather than an input of the algorithm.

3. RUNNING THE ALGORITHMS

Both algorithms were implemented with doubly periodic boundary conditions. A checkerboard updating procedure was used to avoid the result of [10]—that any algorithm which updates all spins simultaneously cannot simulate the Ising model. All the spins were initially set to +1. To compensate for the relaxation of the system from its starting state, some number of initial steps, t_i , need to be discarded. Berretti and Sokal [11] point out that t_i should not be larger than $\sim \frac{t_t}{4}$, t_t being the total number of iterations of the algorithm.

In the micro-canonical program the demons were initialized to either 2 or 0. An input parameter was used to set the ratio of the number of 2's to the number of 0's, depending upon the desired value of the total energy. In order to speed up the algorithm it was necessary to increase the thermal contact by "scrambling" the demons. This was done by offsetting the entire demon lattice by 3 positions in both the x and y directions after each iteration. The value of D_{\max} needed to be set so that there were neither too few nor too many energy levels for the particular range of Z . The best results seem to occur when D_{\max} was allowed to vary dynamically so that the highest energy level contained $\sim 0.1\%$ of the demons.

A listing of the Fortran program used to implement these sampling techniques is given in Appendix B.

4. RESULTS

A survey of both algorithms using a 100x100 lattice ($t_t = 1200$ and $t_i = 200$), over the range $0 < Z < 1$, was conducted on a Stardent GK3000 mini-super-computer. The main output was the internal energy, U , which was calculated after each time step and then averaged for the whole run. These results (see Figs. 1a, b and Table I) illustrate the short term behavior of the algorithms. Both algorithms seem to follow the exact curve fairly well over the range $0.2 < Z < 0.7$. However, near the critical temperature, $Z_c = \frac{1}{2}$

$\log(1 + \sqrt{2}) = 0.44068\dots$, both produce results above the exact value (see Fig. 2). The kink in the internal energy that should occur at Z_c , seems to take place at $Z \approx 0.435$.

Comparing the relative accuracies of each method required much longer runs. These were carried out on a Cray 2 super-computer. The ratio of U to U_{exact} is shown in Fig. 3 ($N = 100 \times 100$, $t_t = 100,000$ and $t_i = 25,000$). The numerical values are given in Table II. In general, one sees that the canonical is consistently much closer to the exact value. The micro-canonical appears to be correlated with Z . This correlation could be due to the fact that for finite N

$$\langle D_i \rangle = \frac{\sum \gamma \exp[-4\gamma Z - (4\gamma Z)^2/2CN] + O(1/N)}{\sum \exp[-4\gamma Z - (4\gamma Z)^2/2CN] + O(1/N)}, \quad (8)$$

where C is the specific heat (see ref. [3]). Runs of $N = 40 \times 40$ and $N = 200 \times 200$ ($t_t = 100,000$ and $t_i = 25,000$) were conducted for both algorithms. Figs. 4a and 4b show U/U_{exact} for two different lattice sizes for the canonical and micro-canonical methods respectively. The canonical method changes little with lattice size, while the micro-canonical method exhibits increased variation with decreasing N . This variation could also be related to Eq. (8).

Another quantity of interest is the specific heat. In the canonical case, C can be calculated from the standard deviation of U , σ_U :

$$-C_{\text{can}} = Z^2 \frac{\partial U}{\partial Z} = Z^2 (N\sigma_U^2). \quad (9)$$

The derivation of Eq. (9) is given in Appendix A. Since both Z and U vary in the micro-canonical method, Eq. (9) cannot be used. That the micro-canonical method exhibits the same behavior as the canonical method can be shown using the following empirical equation

$$-C_{\text{micro}} = \frac{(N\sigma_Z^2)(N\sigma_U^2)}{K_m Z}, \quad (10)$$

where σ_Z is the standard deviation of Z , and K_m is a constant equal to one with units of energy. C_{can} and C_{micro} are plotted in Fig.5 ($N = 100 \times 100$, $t_t = 100,000$, $t_i = 25,000$).

Both agree with C_{exact} qualitatively, but fall short quantitatively. In the case of C_{can} , the shortfall is an indication that the successive configurations of S are correlated. This may also be true for C_{micro} , indicating that the correlation in the micro-canonical method is greater—a believable hypothesis since the algorithm is deterministic. $C_{\text{can}}/C_{\text{exact}}$ and $C_{\text{micro}}/C_{\text{exact}}$ are plotted in Fig. 6 for $(N = 100 \times 100, t_t = 1,000, t_i = 250)$ and $(N = 100 \times 100, t_t = 100,000, t_i = 25,000)$. Fig. 6 shows that there is a consistency in the difference between C_{can} and C_{micro} , and that both fall short of C_{exact} in the same way. This suggests that C_{micro} really does describe the specific heat. Fig. 6 also demonstrates that the variations due to different initial conditions are smoothed out as t_t is increased.

Finally, runs of $N = 200 \times 200, t_t = 1,000,000, t_i = 250,000$ were conducted for both algorithms at $Z \approx 0.4$. No significant difference was found with the $t_t = 100,000$ data.

5. CONCLUSIONS

In this paper extensive surveys of the canonical and micro-canonical sampling methods were conducted over $0.2 < Z < 0.7, 40 \times 40 \leq N \leq 200 \times 200,$ and $1,000 \leq t_t \leq 1,000,000$. In each case $U, Z, \sigma_U,$ and $\sigma_Z,$ were examined. The main results are:

- I) For short runs, $t_t = 1,000,$ both algorithms give nearly identical results.
- II) In longer runs, $t_t = 100,000,$ it appears as though the more complex formulation of Z is required for the micro-canonical method to match the canonical method's accuracy.
- III) The specific heat indicates that both algorithms suffer from successive configurations being correlated, with the micro-canonical algorithm suffering more.

For the researcher debating about which algorithm to use for his or her particular model, the main result of this work is that the two algorithms are equivalent enough in accuracy over $0.2 < Z < 0.7,$ that the particular physics involved should be the determining factor. The canonical approach is simpler. One can get good results using a

smaller lattice. Although, this performance advantage can be offset by the need for random numbers and the exponential function, depending upon the implementation. The main advantage of the micro-canonical approach is its temperature independence. This makes it ideal for studying systems where the temperature is either not uniform or evolving. Finally, a different set of situations can be explored since the demons correspond to their own physical system—the kinetic energy of the lattice sites.

ACKNOWLEDGEMENTS

I would like to thank Prof. Alexandre Chorin for his guidance and support, Dr. M. Creutz, Dr. B. Alpert, and A. Qi for many helpful discussions, and the Department of Energy's Science and Engineering Research Semester for sponsoring me.

Figure Texts

Fig. 1. Internal energy vs. inverse temperature for (a) canonical and (b) micro-canonical approaches ($N = 100 \times 100$, $t_t = 1200$, $t_i = 200$).

Fig. 2. Behavior of the the internal energy near the critical temperature ($N = 100 \times 100$, $t_t = 1200$, $t_i = 200$).

Fig. 3. Ratio of the exact to the computed values of the internal energy ($N = 100 \times 100$, $t_t = 100,000$, $t_i = 25,000$).

Fig. 4. Effect of changing the lattice size, N , on (a) canonical and (b) micro-canonical approaches ($t_t = 100,000$, $t_i = 25,000$).

Fig. 5. Specific heat (C_{can} and C_{micro}) vs. inverse temperature ($N = 100 \times 100$, $t_t = 100,000$, $t_i = 25,000$).

Fig. 6. Effect of increasing the total number of time steps, t_t , on $C_{\text{can}}/C_{\text{exact}}$ and $C_{\text{micro}}/C_{\text{exact}}$ ($N = 100 \times 100$).

Fig. 1a.

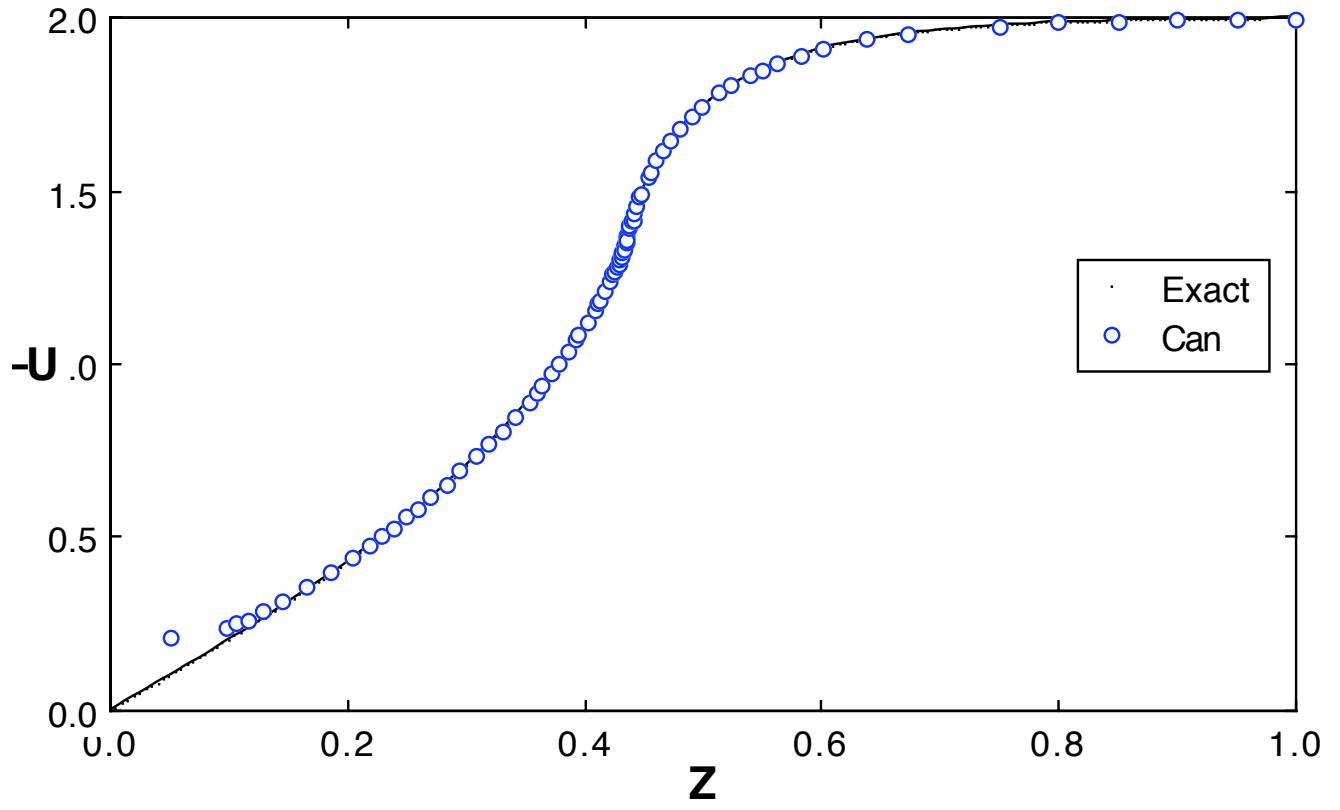


Fig. 1b.

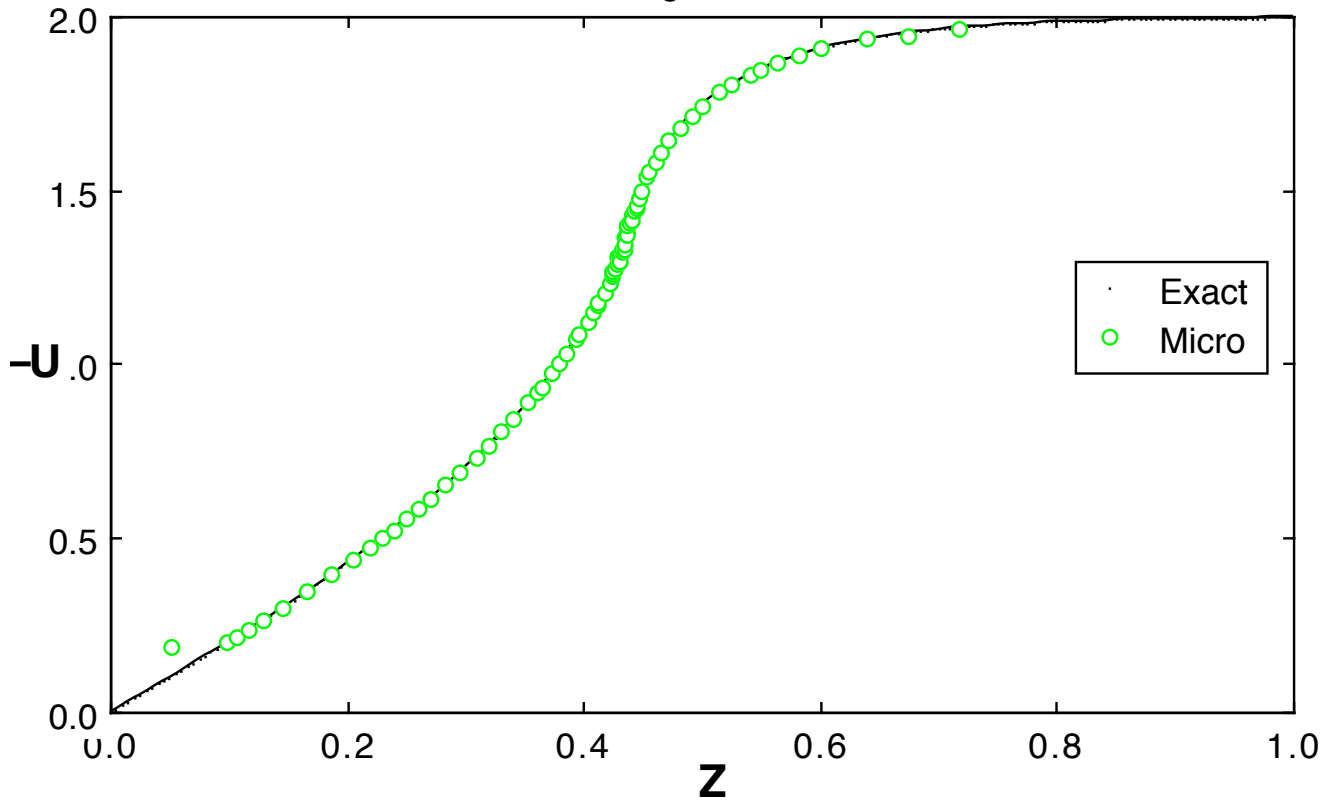


Fig. 2.

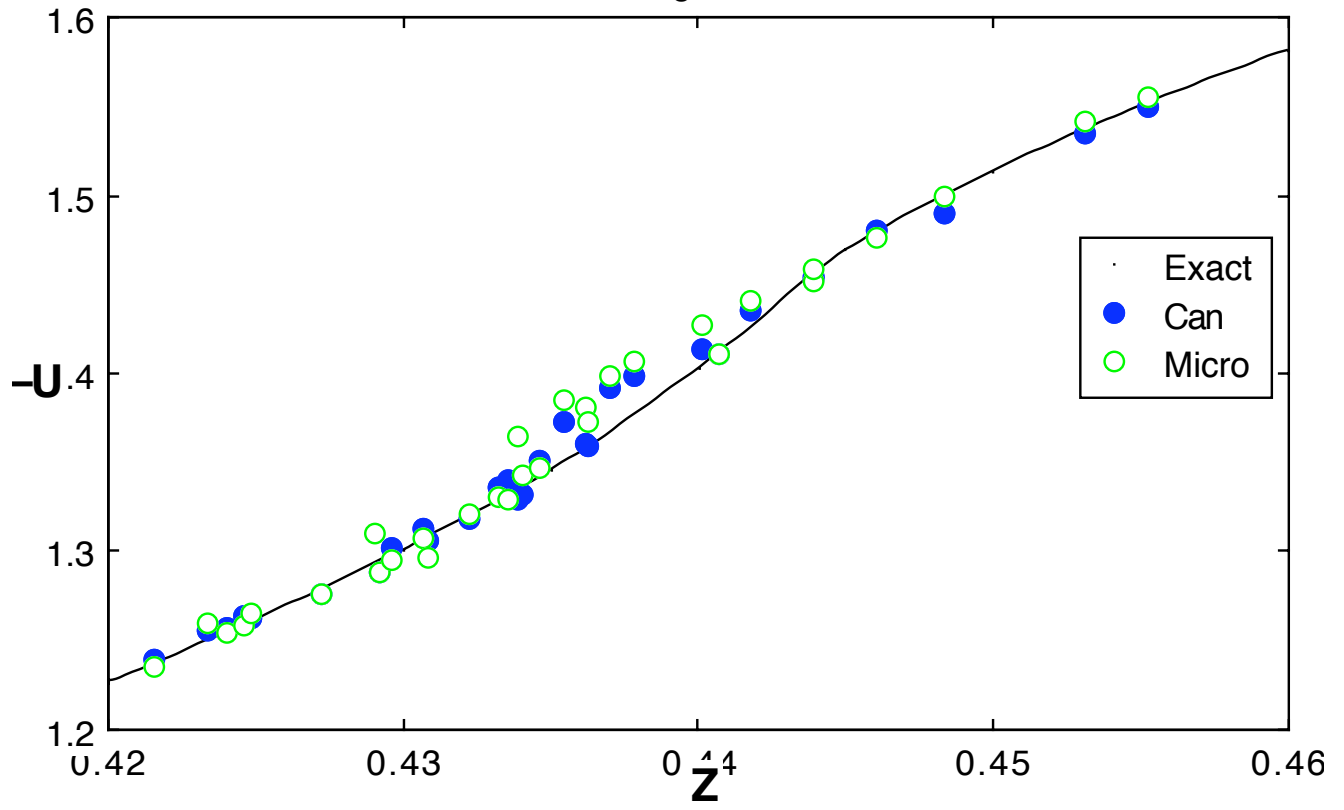


Fig. 3.

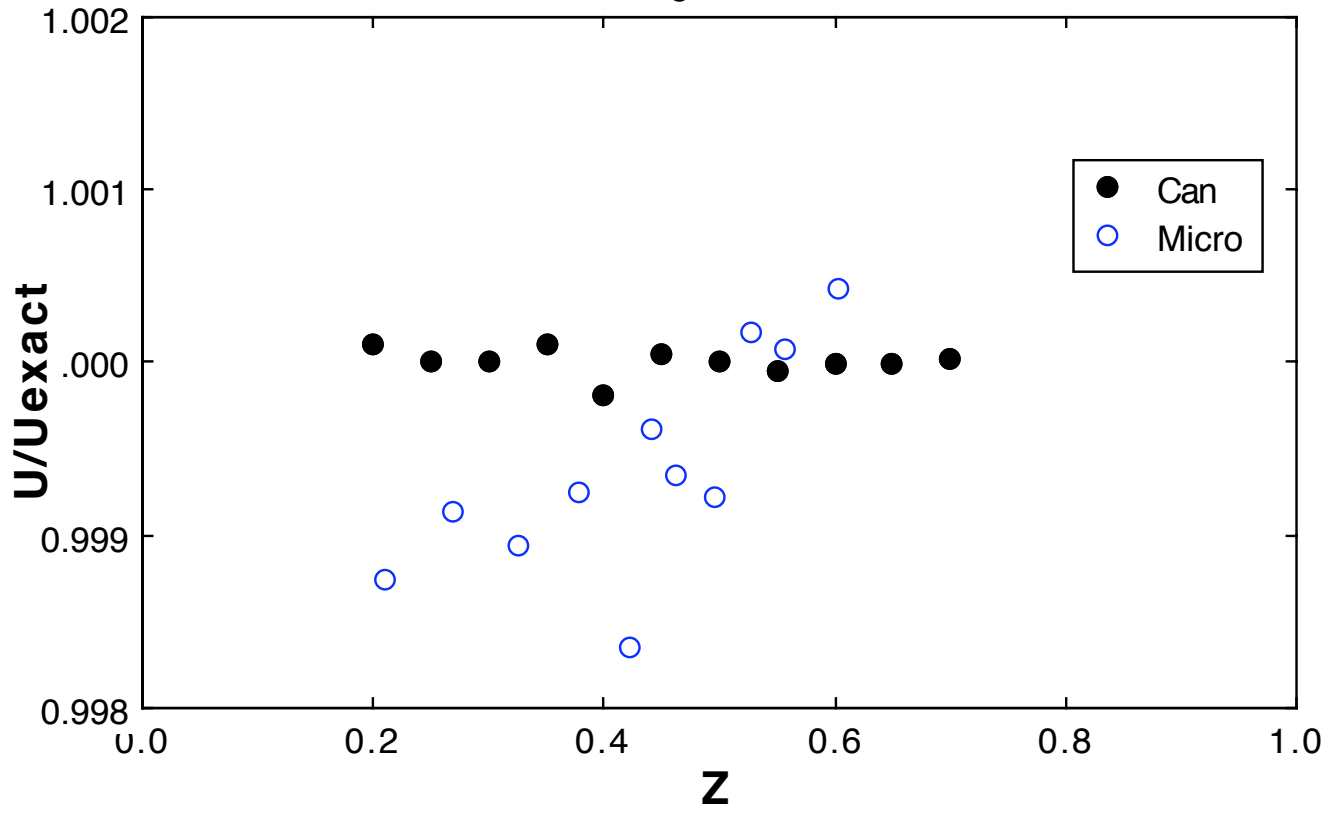


Fig. 4a.

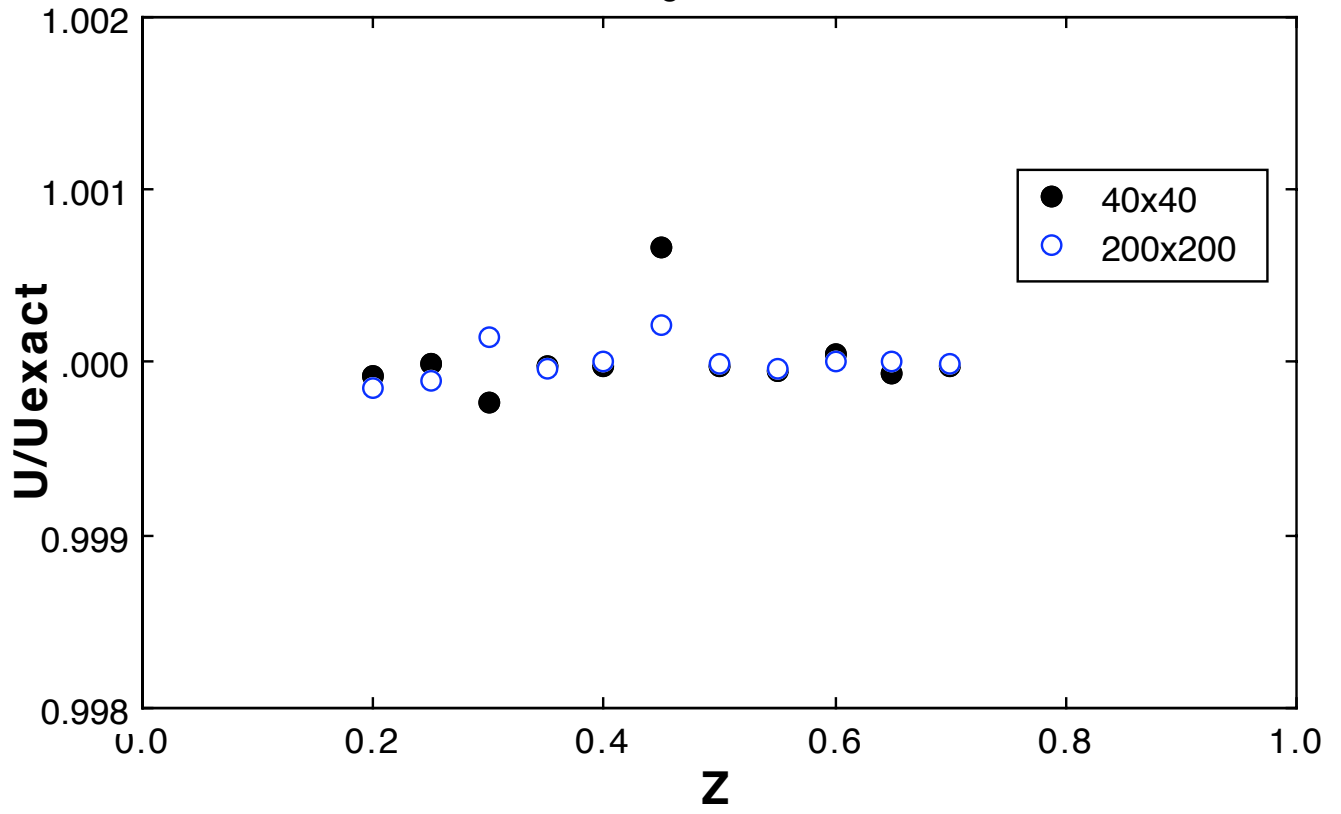


Fig. 4b.

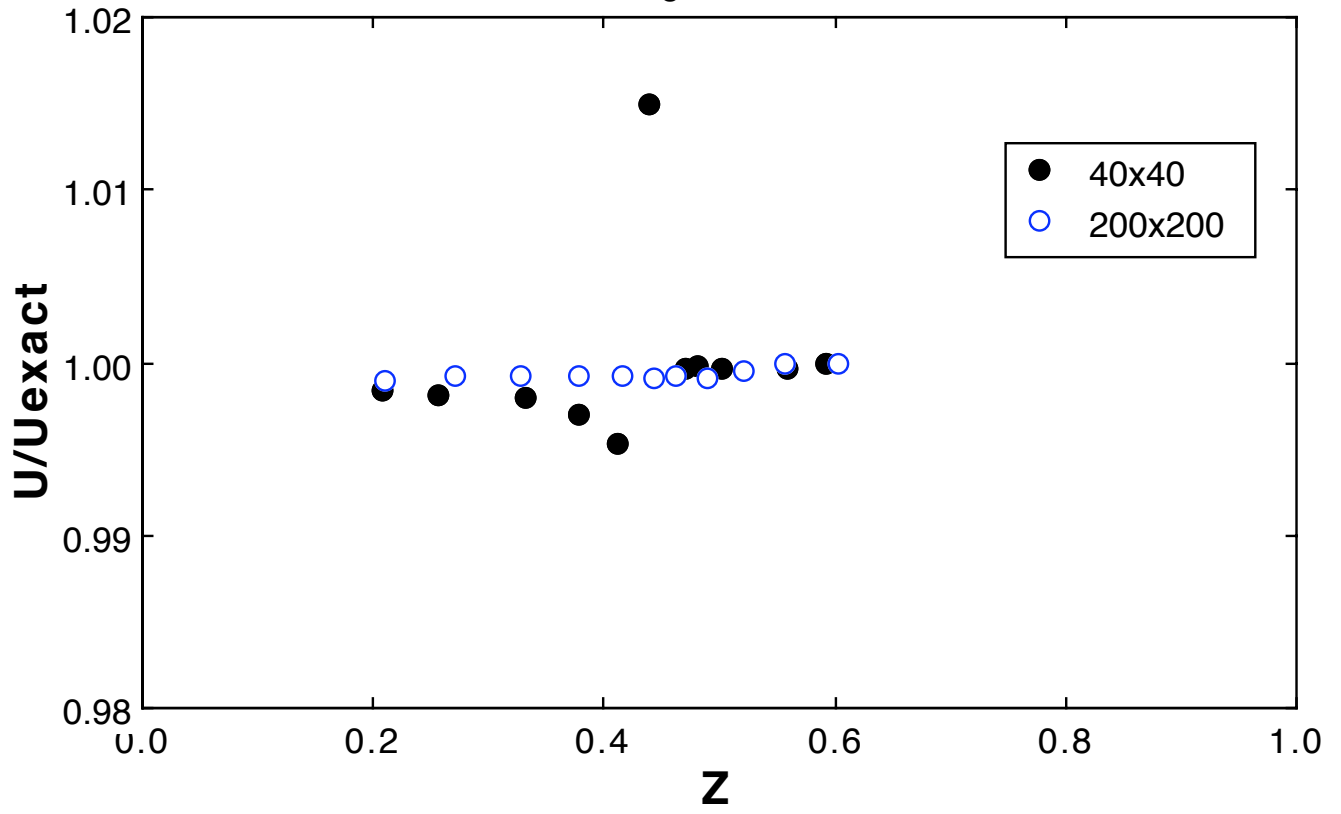


Fig. 5.

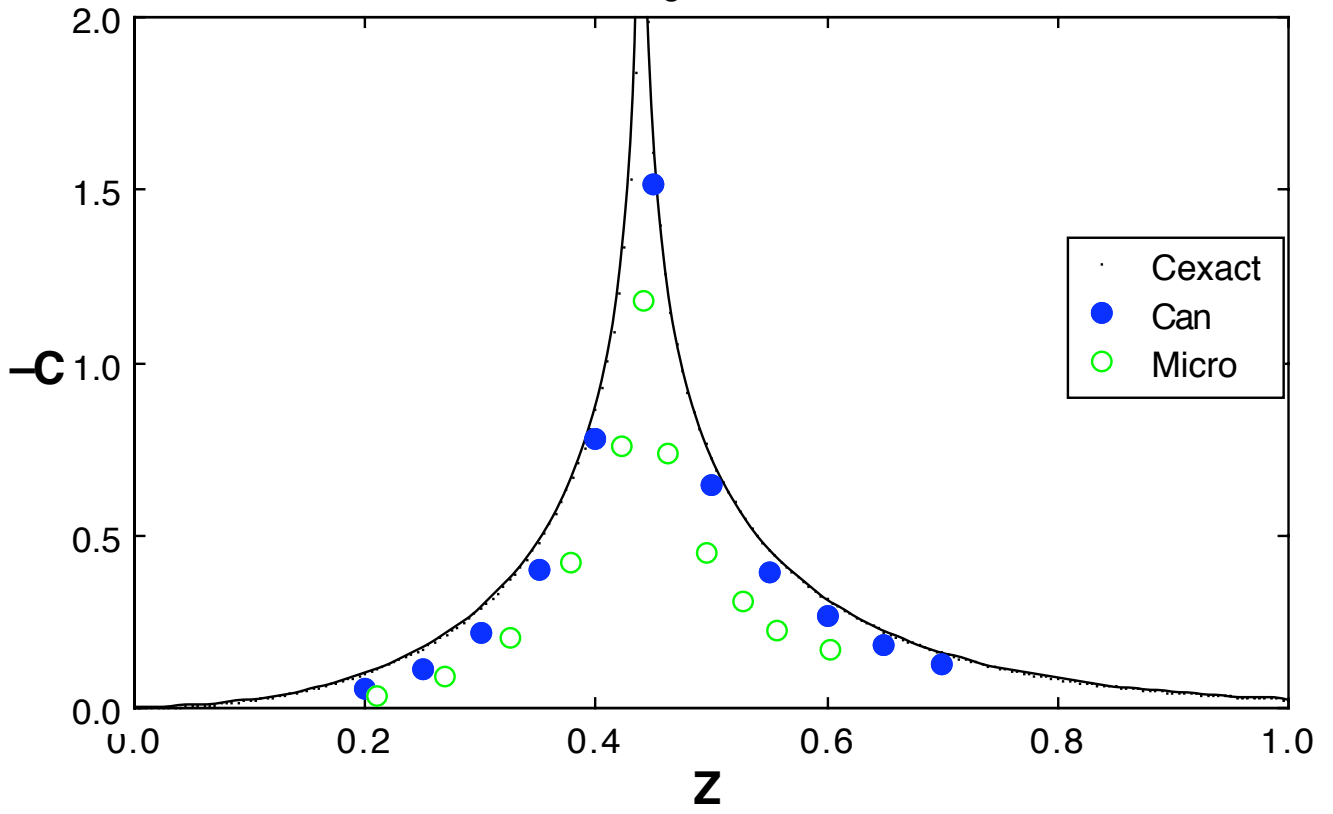


Fig. 6.

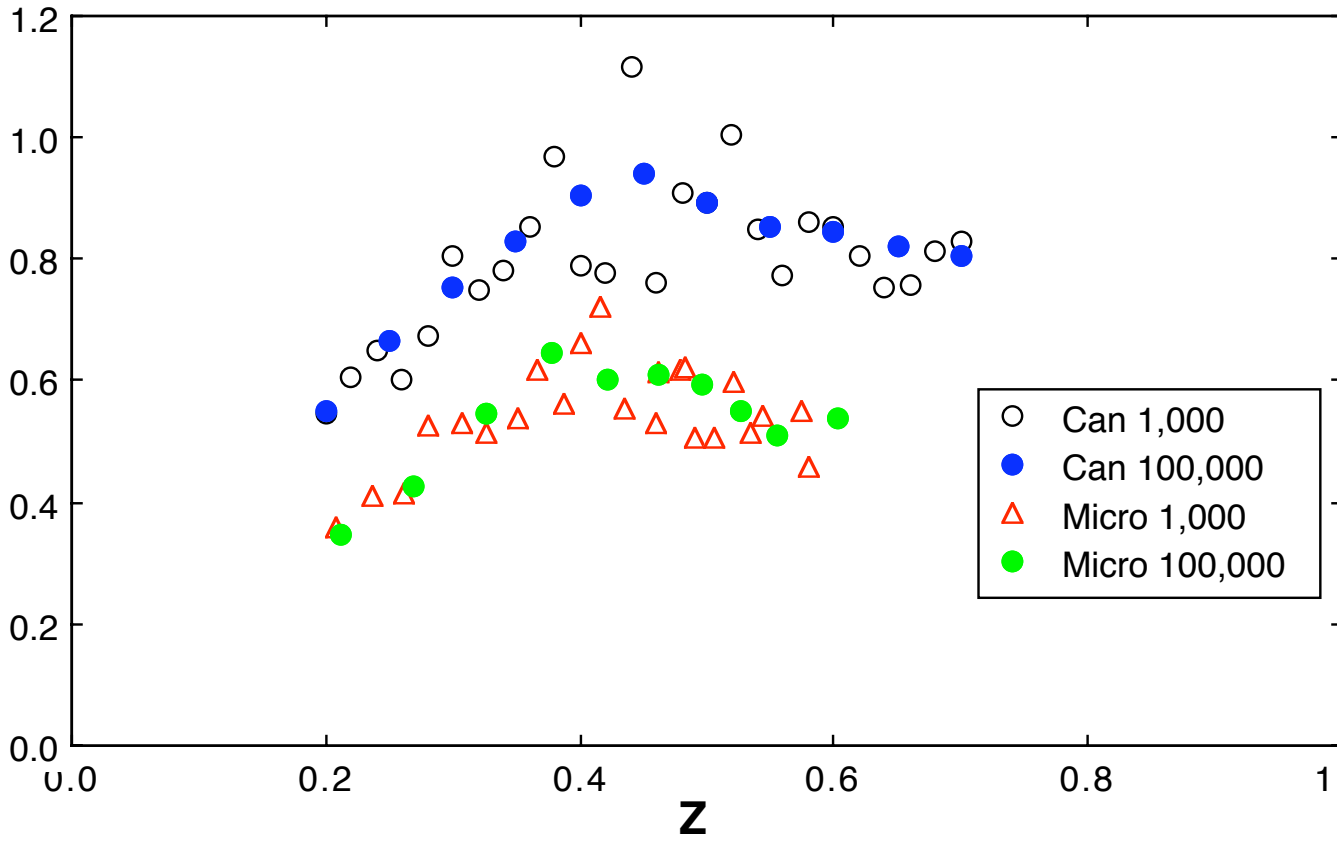


TABLE I

Some numerical values of the internal energy calculated from the canonical and micro-canonical algorithms of the 2D Ising model. Programs were run for 1200 iterations on a 100×100 lattice. The first 200 iterations were discarded. "-" indicates that the algorithm did not yield consistent results. D_{\max} is the largest a demon could become for the given micro-canonical run.

Z	U				D_{\max}
	Exact	Can	Micro		
0	0	-	-	-	-
0.1064	0.2169	0.2497	0.2174		14
0.2040	0.4381	0.4422	0.4381		8
0.3091	0.7339	0.7330	0.7324		5
0.4033	1.1240	1.1223	1.1215		4
0.4370	1.3653	1.3916	1.3987		4
0.4407	1.4151	1.4113	1.4114		4
0.5142	1.7829	1.7801	1.7808		3
0.6733	1.9540	1.9522	1.9455		2
1	1.9972	1.9955	-		-

TABLE II
 Numerical values used to generate Fig. 3 and Fig. 5.
 Data obtained from runs using $N = 100 \times 100$, $t_f = 100,000$, and $t_i = 25,000$.

Z	Canonical			Micro-Canonical				
	U	NG_{U^2}	U/U_{ex}	Z	NG_Z^2	U	NG_{U^2}	U/U_{ex}
0.20	0.42827	1.34756	1.00010	0.21099	0.00700	0.45479	1.16199	0.99875
0.25	0.55728	1.82468	1.00001	0.26849	0.01626	0.60867	1.45837	0.99914
0.30	0.70450	2.39080	1.00000	0.32558	0.03862	0.78891	1.70429	0.99894
0.35	0.87990	3.23888	1.00011	0.37865	0.08173	0.99968	1.95769	0.99925
0.40	1.10587	4.87621	0.99981	0.42220	0.14297	1.23924	2.23533	0.99835
0.45	1.51312	7.47434	1.00005	0.44118	0.19915	1.42264	2.61784	0.99961
0.50	1.74558	2.58469	1.00001	0.46171	0.18690	1.59006	1.82139	0.99934
0.55	1.85104	1.29418	0.99995	0.49603	0.18469	1.73236	1.20608	0.99922
0.60	1.90906	0.73575	0.99999	0.52703	0.18775	1.81125	0.86258	1.00017
0.65	1.94306	0.43015	0.99999	0.55614	0.18912	1.86026	0.65435	1.00007
0.70	1.96380	0.26043	1.00001	0.60289	0.21157	1.91239	0.47006	1.00043

APPENDIX A

In this appendix the equation for the canonical specific heat is derived. From Eq.(9) it is apparent that

$$\frac{\partial U}{\partial Z} = N\sigma_U^2$$

is all that needs to be shown. First note:

$$\sigma_U^2 = \langle (\langle U \rangle - U)^2 \rangle = \langle U^2 \rangle - \langle U \rangle^2 .$$

Let,

$$Z = \sum_{\mu} \exp[-ZE_{\mu}]$$

and

$$\langle U \rangle = \frac{1}{Z} \sum_{\mu} E_{\mu} \exp[-ZE_{\mu}]$$

be the partition function and the average internal energy of a thermodynamic system respectively [12]. $\langle U \rangle$ and $\langle U^2 \rangle$ can be re-written in terms of partial derivatives

$$\langle U \rangle = -\frac{1}{Z} \frac{\partial Z}{\partial Z} \Rightarrow \langle U \rangle^2 = \frac{1}{Z^2} \left(\frac{\partial Z}{\partial Z} \right)^2$$

$$\langle U^2 \rangle = \frac{1}{Z} \sum_{\mu} E_{\mu}^2 \exp[-ZE_{\mu}] = \frac{1}{Z} \frac{\partial^2 Z}{\partial Z^2} .$$

Thus,

$$\sigma_U^2 = \frac{1}{Z} \frac{\partial^2 Z}{\partial Z^2} - \frac{1}{Z^2} \left(\frac{\partial Z}{\partial Z} \right)^2 = \frac{\partial}{\partial Z} \left(\frac{1}{Z} \frac{\partial Z}{\partial Z} \right) .$$

Substituting in for the definition of $\langle U \rangle$ gives

$$\sigma_U^2 = \frac{\partial \bullet U^{\circledast}}{\partial Z} = \left(\frac{\partial U}{\partial Z} \right)_{U = \bullet U^{\circledast}} .$$

In the finite 2D Ising model [13]

$$U \rightarrow -\frac{\partial}{\partial Z} \left(\frac{1}{N} \log(Z_N) \right) ,$$

which has the necessary factor of N, resulting in

$$\frac{1}{N} \frac{\partial U}{\partial Z} = \sigma_U^2$$

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APPENDIX B

Listing of the Fortran program used in these experiments. Note that the first section is the common block, which is inserted by the "include" command at the beginning of each subroutine.

```

c      ***** BEGIN COMMON BLOCK *****
c
c      calculation variables
c      302*302 = 91204
c      integer gspin1(302,302), gdemarr1(302,302)
c      integer gspin2(302,302), gdemarr2(302,302)
c      integer gmap(91204,6)
c
c      gspin1 = SPIN array 1; gdemarr1 = DEMON ARRAY 1
c      gspin1 = SPIN array 2; gdemarr1 = DEMON ARRAY 2
c      gmap = MAP array
c
c      common gspin1, gdemarr1
c      common gspin2, gdemarr2
c      common gmap
c
c      calculation parameters
c      logical gdovarb
c      integer gmethod, gdemoff
c      integer gmaxbins, gminbins, gmaxdem
c      integer gbinht, gdemonht
c      real gvarbwt, gspinwt, gdemonwt
c
c      gdovarb = DO VARIABLE Bins
c      gmethod = sampling METHOD; gdemoff = DEMON array OFFSET
c      gmaxbins = MAXIMUM demon BIN; gminbins = MINIMUM demon BIN;
c      gmaxdem = MAXIMUM DEMON value
c      gbinht = demon BIN Height; gdemonht = DEMON value Height
c      gvarbwt = VARIABLE Bin Weight; gspinwt = SPIN Weight;
c      gdemonwt = DEMON Weight
c
c      common gdovarb
c      common gmethod, gdemoff
c      common gmaxbins, gminbins, gmaxdem
c      common gbinht, gdemonht
c      common gvarbwt, gspinwt, gdemonwt
c
c      canonical globals
c      real gzinput, gboltzar(5)
c
c      gzinput = Z Input; gboltzar = BOLTzman ARray
c
c      common gzinput, gboltzar
c
c      calculation outputs
c      integer glastbin

```

```

real gavgbin, gavgham, gz, gu

c      glastbin = LAST demon BIN
c      gavgbin = AVeraGe demon BIN; gavgham = AVeraGe spin
HAMiltonian;
c      gz = Z (inverse temperature); gu = U (internal energy)

common glastbin
common gavgbin, gavgham, gz, gu

c      running outputs
integer gstep
real gztot, gutot
real gzsqrd, gusqrd

c      gstep = current time STEP
c      gztot = Z TOTAl; gutot = U TOTAl
c      gzsqrd = total Z SQuaReD; gusqrd = total U SQuaReD

common gstep
common gztot, gutot
common gzsqrd, gusqrd

c      running paramters
integer gxsize, gysize, gtotal, gsteps
integer gavgit, gfullu

c      gxsize = X SIZE; gysize = Y SIZE;
c      gtotal = TOTAL array elements; gsteps = total time STEPS
c      gavgit = time steps before calling AVeraGe IT;
c      gfullu = FULL output file Unit

common gxsize, gysize, gtotal, gsteps
common gavgit, gfullu

character*8 gfullf
c      gfullf = FULL output Filename
c      Cray insists that all string variables be placed
c      in a separate common block.
common /string/gfullf

c      ***** END COMMON BLOCK *****

program ising
c      load common block
include 'vectb.f'

c      global/common block variables are denoted by a "g"
c      Declare local variables.
c      nstep is the size of the lattice, zstep is
c      the temperature, and zscale converts
c      zstep into a usable real number.

integer nstep,zstep
real zscale
character*16 title1,title2

```



```

c      call dropfile(0)

c      Set default values.

      call setdefs
      zscale = 0.001

c      Set up output file.
c      Since we are using status='old', a file
c      called gfile (see defaults) must already exist.

      title1 = 'n      avgz  sigz  uex  '
      title2 = 'avgu  sigu  cex'
      open(unit=gfullu,file=gfullf,status='old')
      write(gfullu,*) title1,title2

c      This is where the user can change values
c      e.g. time step, sampling method, ...
c      Vary the constants in the zstep and nstep
c      do loops to change the temperature and
c      lattice size.  These loops are there to make
c      it convenient to do surveys over a range of
c      temperatures and lattice sizes.

      gsteps = 40
      gmethod = 1
      gdovarb = .true.
      gavgit = gsteps/4
      do 90 zstep = 200,200,100
         gzinput = zscale * zstep
         if (gmethod .eq. 1) then

c            Approximate imperical formula that
c            sets the initial demon lattice so that the
c            equilibrium temperature will be approximately
c            equal to gzinput.  This is only relavent
c            in the micro-canonical (gmethod = 1).

            gdemonwt = ((1.0/gzinput) - 1.0)/7.0

            gdemoff = 3
            endif

         do 80 nstep = 40,40,20

c            Although have seperate variables for the
c            X and Y array limits, this is only there
c            if one day someone wants to do rectagular
c            arrays.

            gxsize = nstep
            gysize = gxsize
            gtotal = gxsize * gysize
            print*, 'z = ',gzinput, ' n = ',gxsize
            call initit

c            Begin main loop.

```

```

do 70 gstep = 1, gsteps
c      Choose between micro-canonical
c      and canonical approaches

      if (gmethod .eq. 1) then
        call calcmic
        call evaluate
        if (gdemoff .gt. 0) call randemon
      elseif (gmethod .eq. 2) then
        call calccan
        call evaluate
      endif
      if (gstep .ge. gavgit) call avgit
70    continue
      call stats
80    continue
90    continue
      close(gfullu)
end

c      Converts bins to demons.
function bindem(bins)
  integer bins
  bindem = 4 * (bins - 1)
return
end

c      Converts demons to bins.
function dembin(demon)
  integer demon
  dembin = (demon/4) + 1
return
end

c      Sets the default values of many of
c      the variables in the common block.
subroutine setdefs
c      load common block
      include 'vectb.f'

      gmethod = 2
      gzinput = 0.4
      gdemoff = 0
      gdovarb = .true.
      gvarbwt = 0.001
      gmaxbins = 5
      gminbins = 3
      gmaxdem = bindem(gmaxbins)
      gspinwt = 0.0
      gdemonwt = 0.0
      gbinht = 3
      gdemonht = bindem(gbinht)

      gxsize = 100

```

```

    gysize = gxsize
    gtotal = gxsize * gysize
    gsteps = 100000
    gavgit = 200
    gfullf = 'fullld'
    gfullu = 21

return
end

c      INITIALIZE ARRAYS
c      Initialize the lattice in accordance with
c      the values set at the beginning of the main
c      loop. The function rand(0) returns a random
c      real number between 0.0 and 1.0 with uniform
c      distribution.

subroutine initit
c      load common block
      include 'vectb.f'
      integer i,j,k,l,s,d,ip,im,jp,jm

c      INIT BOLTZMAN TABLE
c      No need to call exp() all the time
c      since there are only five different
c      values in the canonical method, so we put
c      them in a lookup table.

      do 10 i = 1, 5
10      gboltzar(i) = exp(4*(3-i)*gzinput)
      continue

c      INITMAP
c      In order to use checkerboard updating need
c      to create a list of x and y lattice locations
c      so that one can simply step through the list
c      and hit the right points. NOTE, this requires
c      that gxsize and gysize be even.
c      Stepping through the first half of the map
c      gives the first color, the second half
c      gives the second color.

      k = 0
      l = gtotal/2
      do 30 i = 1, gxsize - 1, 2
      do 20 j = 1, gysize - 1, 2
          k = k + 1
          gmap(k,1) = i
          gmap(k,2) = j
          k = k + 1
          gmap(k,1) = i + 1
          gmap(k,2) = j + 1
          l = l + 1
          gmap(l,1) = i

```

```

        gmap(1,2) = j + 1
        l = l + 1
        gmap(1,1) = i + 1
        gmap(1,2) = j
20     continue
30     continue

c     INIT SPINS
c     Sets initial configuration of the spin lattice.
c     Lowest energy is when spins are
c     either all up, 1, or all down, -1,
c     which corresponds to gspinwt of 1 and 0
c     respectively. The highest energy state
c     corresponds to gspinwt = 0.5.

        do 40 k = 1, gtotal
            i = gmap(k,1)
            j = gmap(k,2)

c         weights spins according to gspinwt
            s = -1
            if (rand(0) .lt. gspinwt) s = 1
            gspin1(i,j) = s
40     continue

c     INIT DEMONS
c     Sets initial configuration of demon lattice.
c     All demons are set to either 0 or gdemonht in
c     praportion to gdemonwt. Thus the highest
c     energy is gdemonwt = 1.0

        do 50 k = 1, gtotal
            i = gmap(k,1)
            j = gmap(k,2)

c         weights demons according to gdemonwt
            d = 0
            if (rand(0) .lt. gdemonwt) d = gdemonht
            gdemarr1(i,j) = d
50     continue

c     INIT COPIES
c     In order to vectorize, need to have copies
c     of the arrays. So, we need to copy the
c     initial values of the arrays to their
c     corresponding copies.
        do 60 k = 1, gtotal
            i = gmap(k,1)
            j = gmap(k,2)
            gspin2(i,j) = gspin1(i,j)
            gdemarr2(i,j) = gdemarr1(i,j)
60     continue

c     PERIODIC BOUNDARY CONDITIONS
c     Called "torroidal" or "doubly periodic".
c     For a given lattice size these conditions

```

```

c      are constant and can be calculated in
c      advance and put into the map, so that
c      they only need be looked up.  In theory
c      it is the fastest approach.
      do 70 k = 1, gtotal
          i = gmap(k,1)
          j = gmap(k,2)

          ip=i+1
          im=i-1
          jp=j+1
          jm=j-1
          if (im .lt. 1) im = gxsize
          if (ip .gt. gxsize) ip = 1
          if (jm .lt. 1) jm = gysize
          if (jp .gt. gysize) jp = 1
          gmap(k,3) = ip
          gmap(k,4) = im
          gmap(k,5) = jp
          gmap(k,6) = jm
70      continue

      return
      end

c      CYCLE DEMONS
c      To speed up the relaxation time of
c      the micro-canonical approach, the demons
c      are cycled so as to increase the rate at
c      which energy is transferred around the lattice.
c      Without it, oscillations between the spin
c      lattice and the demon lattice can occur.

      subroutine randemon
c      load common block
      include 'vectb.f'
      integer i,j,xoffset,yoffset,xmoveto,ymoveto

c      Get x and y positions from map, no implicit
c      need to, but helps vectorization.
c      Offset demon and move into the copy, then copy
c      back into demon array.  In this instance the
c      copy, gdemarr2, just acts as a convenient
c      storage space.

      xoffset = gdemoff
      yoffset = gdemoff
      if (gdemoff .gt. 0) then
          do 10 k = 1, gtotal
              i = gmap(k,1)
              j = gmap(k,2)
              xmoveto = i + xoffset
              ymoveto = j + yoffset
              if (xmoveto .gt. gxsize) xmoveto = xmoveto - gxsize
              if (ymoveto .gt. gysize) ymoveto = ymoveto - gysize
              gdemarr2(xmoveto,ymoveto) = gdemarr1(i,j)
10          continue

```

```

        do 20 k = 1, gtotal
            i = gmap(k,1)
            j = gmap(k,2)
            gdemarr1(i,j) = gdemarr2(i,j)
20      continue
        endif
    return
end

c      MICRO-CANONICAL
c      Main subroutine for micro-canonical.
c      Jump through quite a few hoops to get
c      vectorization. 1) Update gspin1
c      and gdemarr1 from gspin2 and gdemarr2 for
c      first color of the checkerboard. 2) Copy
c      spin1 and gdemarr1 back into gspin2
c      and gdemarr2. 3) Repeat calculations for
c      the second color of the checkerboard.
c      WARNING: Updating all spins at once causes the
c      algorithm to fail, which is why we use the
c      checkerboard updating scheme.

subroutine calcmic
c      load common block
        include 'vectb.f'
        integer i,j,k,l,lo,hi,isum
        integer newdemon,delh,demsum,hamsum
        logical test

c      glastbin is used to vary bins.
        glastbin = 0
        demsum = 0
        hamsum = 0

        do 30 l = 1,2

            if (l .eq. 1) then
                lo = 1
                hi = gtotal/2
            elseif (l .eq. 2) then
                lo = 1 + gtotal/2
                hi = gtotal
            endif

            do 10 k = lo,hi
                i = gmap(k,1)
                j = gmap(k,2)
                isum = gspin2(gmap(k,3),j) + gspin2(gmap(k,4),j)
a          + gspin2(i,gmap(k,5)) + gspin2(i,gmap(k,6))
                delh = 2 * gspin2(i,j) * isum
                newdemon = gdemarr2(i,j) - delh
                test = ((newdemon.ge.0).and.(newdemon.le.gmaxdem))
                if (test) gdemarr1(i,j) = newdemon
                if (test) gspin1(i,j) = -gspin2(i,j)
                hamsum = hamsum + (gspin2(i,j) * isum)
10          continue

```

```

do 20 k = lo,hi
  i = gmap(k,1)
  j = gmap(k,2)
  gspin2(i,j) = gspin1(i,j)
  gdemarr2(i,j) = gdemarr1(i,j)
  if (gdemarr1(i,j) .eq. gmaxdem) glastbin = glastbin + 1
  demsum = demsum + gdemarr1(i,j)
20  continue

30  continue
  gavgbin = demsum/(4.0*gtotal)
  gavgham = hamsum/(1.0*gtotal)
return
end

```

```

c  CANONICAL
c  Main subroutine for canonical.
c  Jump through quite a few hoops to get
c  vectorization. 1) Update gspin1
c  from gspin2 for
c  first color of the checkerboard. 2) Copy
c  spin1 back into gspin2.
c  3) Repeat calculations for
c  the second color of the checkerboard.
c  WARNING: Updating all spins at once causes the
c  algorithm to fail, which is why we use the
c  checkerboard updating scheme.

```

```

subroutine calccan
c  load common block
  include 'vectb.f'
  integer k,l,i,j,isum,lo,hi
  integer delh, aboltz, hamsum
  logical test

  hamsum = 0
  do 30 l = 1, 2
    if (l .eq. 1) then
      lo = 1
      hi = gtotal/2
    elseif (l .eq. 2) then
      lo = 1 + gtotal/2
      hi = gtotal
    endif
    do 10 k = lo,hi
      i = gmap(k,1)
      j = gmap(k,2)
      isum = gspin2(gmap(k,3),j) + gspin2(gmap(k,4),j)
a      + gspin2(i,gmap(k,5)) + gspin2(i,gmap(k,6))
      delh = 2 * gspin2(i,j) * isum
      aboltz = 3 + (delh/4)
      test = rand(0) .lt. gboltzar(aboltz)
      if (test) gspin1(i,j) = -gspin2(i,j)
      hamsum = hamsum + (gspin2(i,j) * isum)
10    continue

    do 20 k = lo,hi

```

```

        i = gmap(k,1)
        j = gmap(k,2)
        gspin2(i,j) = gspin1(i,j)
20    continue
30    continue
    gavgham = hamsum/(1.0*gtotal)
return
end

c    Takes values calculated from the main
c    loop and acts on them. Finds the energy
c    and calculates the proper temperature
c    depending upon which sampling method
c    is being used. Also, the variable
c    bin algorithm is implemented here.

subroutine evaluate
c    load common block
    include 'vectb.f'
    logical lolim, hilim, lobin, hibin
    real eps

    gu = (gavgham/2.0)

    if (gmethod .eq. 1) then
        gz = findz(gavgbin,gmaxbins)
    elseif (gmethod .eq. 2) then
        gz = gzinput
    endif

c    Want to make sure gmaxdem is neither too
c    large nor too small. glastbin tells us
c    how many demons are in the highest energy
c    level. The number we are aiming for is
c    gvarbwt * gtotal. NOTE: that there are
c    bounds below (gminbins), and above (32).
c    NOTE2: that there is a region, 0.5 to 1.5,
c    times the target, in which no change
c    occurs. This helps prevent oscillations.

    if ((gdovarb).and.(gmethod.eq.1)) then
        eps = gvarbwt * gtotal
        lolim = gmaxbins .gt. gminbins
        hilim = gmaxbins .lt. 32
        lobin = glastbin .lt. (0.5 * eps)
        hibin = glastbin .gt. (1.5 * eps)
        if ((lolim) .and. (lobin)) then
            gmaxbins = gmaxbins - 1
            gmaxdem = bindem(gmaxbins)
        elseif ((hilim) .and. (hibin)) then
            gmaxbins = gmaxbins + 1
            gmaxdem = bindem(gmaxbins)
        endif
    endif
return
end

```



```

c      Keeps track of values needed to
c      calculate the mean and standard
c      deviation of Z and U.

      subroutine avgit
c      load common block
      include 'vectb.f'
      character tab
      tab = ' '
c      initialize avg counters first time through
      if (gstep .le. gavgit) then
          gutot = 0.0
          gusqrd = 0.0
          gztot = 0.0
          gzsqrd = 0.0
      elseif (gstep .gt. gavgit) then
          gutot = gutot + gu
          gusqrd = gusqrd + ((gu)**2)
          if (gmethod .eq. 1) then
              gztot = gztot + gz
              gzsqrd = gzsqrd + ((gz)**2)
          endif
      endif
      return
      end

c      Calculates mean and standard deviation
c      of Z and U from the values calculated
c      in the subroutine avgit. Also computes
c      the exact values of U and the specific
c      heat, C, from Z; writes these values
c      into the output file.

      subroutine stats
c      load common block
      include 'vectb.f'
      integer effsteps
      real totz, totu
      real avgz, sigz, uex, avgu, sigu, cex
      character t
      t = ' '

      effsteps = gsteps - gavgit
      avgz = gztot/effsteps
      avgu = gutot/effsteps
      totz = gzsqrd - ((gztot)**2)/effsteps
      totu = gusqrd - ((gutot)**2)/effsteps
      sigz = sqrt(toz/(effsteps - 1))
      sigu = sqrt(totu/(effsteps - 1))
      if (gmethod .eq. 2) then
          avgz = gzinput
          sigz = 0.0
      endif

      uex = -uint(avgz)
      cex = cap(avgz)

```

```

    write(gfullu,*) gxsize,t,avgz,t,sigz,t,uex,t,avgu,t,sigu,t,cex
return
end

```

c Uses Newton's method to calculate the
c inverse temperature from the avg demon
c value.

```

function findz(avgen,noofbins)
  real avgen,x0,xn,temp1,temp2,temp3,temp4,fx0,fprimex0
  integer noofbins,i,j
  x0 = 0.5
  epsilon = 0.00005
  do 20 i = 1,100

    temp1 = 0.0
    temp2 = 0.0
    temp3 = 0.0
    temp4 = 0.0

    do 10 j = 0,noofbins-1
      temp1 = exp(-4 * j * x0)
      temp2 = temp2 + temp1
      temp3 = temp3 + (j * temp1)
      temp4 = temp4 + (j * j * temp1)
10    continue

    fx0 = (temp3/temp2) - avgen
    fprimex0 = (1 - (16 * temp4 * temp2))/(temp2 * temp2)

    xn = x0 - (fx0/fprimex0)
    if (abs(xn - x0) .lt. epsilon) goto 100
    x0 = xn

20  continue

100  findz = xn
    return
    end

```

c Calculates the exact value of the
c internal energy, U, for a given Z.

```

function uint(v)
  real v
  integer n,l
  if (v .le. 5.0) then
    n = 5
    temp1 = u(2.0*v,n)
    do 10 l = 1,12
      n = 2*n
      temp2 = u(2.0*v,n)
      if (abs(temp1-temp2) .lt. 0.00005) goto 100
      if (l .ne. 12) temp1 = temp2
10    continue

```

```

100   uint = -temp2
      else
        uint = -2.0
      endif
      return
    end

```

c Function called by uint(v).

```

function u(w,n)
  real k,k1,pi,sum,h,t1
  integer ctn,i
  if (w .gt. 0) then
    pi = 3.1415926
    sum = 0.0
    ctn=2*n
    h = pi/ctn
    k1 = 2*sinh(w)/(cosh(w)**2)
    do 10 i = 1,n-1
      sum = sum + 1.0/sqrt(1.0 - (k1**2*(sin(i*h)**2)))
10    continue
    sum = sum + 0.5*(1 + 1./sqrt(1-k1**2))
    k= h*sum
    t1 = 1 + (2*tanh(w)**2 - 1)*(2./pi)*k
    u = t1/tanh(w)
  else
    u = 0
  endif
  return
end

```

c Calculates the exact value of the
c specific heat, C, for a given Z.

```

function cap(v)
  integer n,l
  real v,temp1,temp2
  n = 20
  temp1 = C(2.*v,n)
  do 20 l = 1,12
    n = 2*n
    temp2 = C(2.*v,n)
    if (abs(temp1-temp2) .lt. .00005) then
      goto 10
    end if
    if (l .ne. 12) temp1 = temp2
20  continue
10  cap=temp2
  return
end

```

c Function called by cap(v).

```

function C(w,n)
  real w,K,E,k1,pi,sum1,sum2,h,t1,t2

```

```

integer n,i
  if (w .eq. 0) then
    c = 0
    return
  end if
  pi = 3.1415926
  k1 = 2*sinh(w)/(cosh(w)**2)
  sum1 = 0.0
  sum2 = 0.0
  h = pi/(2*n)
  do 10, i = 1,n-1
    sum1 = sum1 + 1.0/sqrt(1. - (k1**2*(sin(i*h)**2)))
    sum2 = sum2 + sqrt(1. - (k1**2*(sin(i*h)**2)))
10  continue
  sum1 = sum1 + .5*(1 + 1./sqrt(1-k1**2))
  sum2 = sum2 + .5*(1 + sqrt(1-k1**2))
  K = h*sum1
  E = h*sum2
  t1 = 1 + (2*tanh(w)**2 - 1)*(2./pi)*K
  t2 = 2*(K-E-0.5*pi*(1-tanh(w)**2)*t1)
  C = (.5/pi)*(w/tanh(w))**2*t2
return
end

```