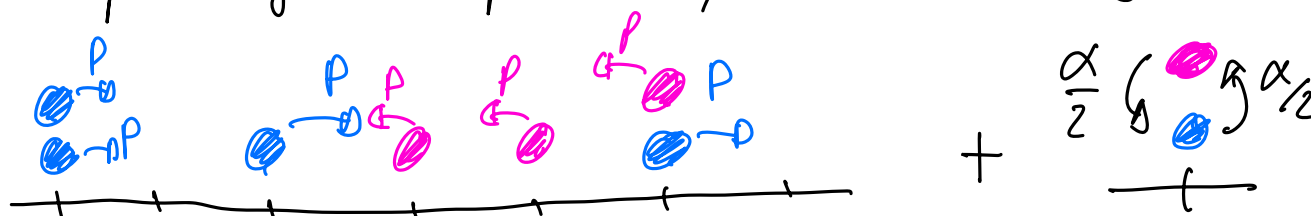


IV) MIPS on lattice

(51)

More general results on the phase-separation, surface tension and how to compute the phase diagram in off-lattice models can be found in: [Solon et al, New Journal of Physics 20, 075001 (2018)]

Here, we focus on the simpler case of α -lattice RTPs in 1D. (inspired by [Thompson et al, J. Stat. Mech 2011]).



Lattice gas model of non-interacting un- and-bidirectional bacteria.

Configurations $\mathcal{Q} \leftrightarrow$ occupancies (n_i^+, n_i^-) which describe the number of particles hopping to the right or to the left at site i .

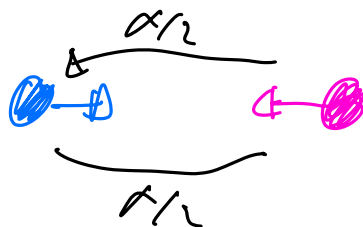
Add excluded volume interaction: partial exclusion

Hopping $i \rightarrow i+1$ for a right going particle p $\left(1 - \frac{n_{i+1}}{n_m}\right)$
 $i \rightarrow i-1$ — left — p $\left(1 - \frac{n_{i-1}}{n_m}\right)$

$n_i = n_i^+ + n_i^-$ is the total occupancy.

n_m is the maximal occupancy allowed on a lattice site

Tumbling rate



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Idea: Describe the dynamics of $g_i^+ = \langle m_i^+(x) \rangle$ and show that homogeneous profiles are unstable.

Master equation: $\partial_t P(\mathcal{Q}) = \sum_{\mathcal{Q}' \neq \mathcal{Q}} W(\mathcal{Q}' \rightarrow \mathcal{Q}) P(\mathcal{Q}') - W(\mathcal{Q} \rightarrow \mathcal{Q}') P(\mathcal{Q})$

Here $\mathcal{Q} = \{m_i^+, m_i^-\} = \{m_1^+, m_1^-, m_2^+, m_2^-, \dots, m_L^+, m_L^-\}$

① $\mathcal{Q}'$ such that $W(\mathcal{Q}' \rightarrow \mathcal{Q}) \neq 0$

* $\mathcal{Q}' = \{m_1^+, m_1^-, \dots, m_{i-1}^+, m_{i-1}^-, m_i^+ + 1, m_i^- - 1, m_{i+1}^+, m_{i+1}^-, \dots, m_L^+, m_L^-\} \equiv \{m_{i-1}^+ + 1, m_i^+ - 1\}$

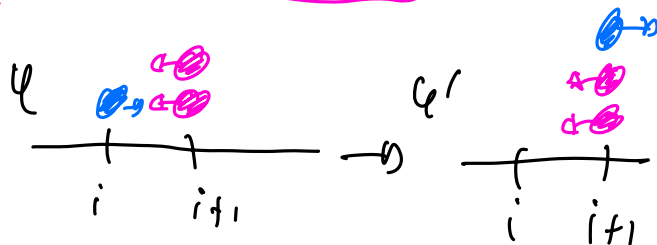
$\mathcal{Q}' = m_{i-1}^+ + 1, m_i^+ - 1 \rightarrow \mathcal{Q}$ at rate $W = p(m_{i-1}^+ + 1) \left(1 - \frac{m_i^-}{m_\mu}\right)$
and $m_j^{\pm} \neq i$ same as in $\mathcal{Q}$

* $\mathcal{Q}'$ as $\mathcal{Q}$ but with $m_{i+1}^- + 1, m_i^- - 1 \rightarrow \mathcal{Q}$ at rate $W(\mathcal{Q}' \rightarrow \mathcal{Q}) = p(m_{i+1}^- + 1) \left(1 - \frac{m_i^+}{m_\mu}\right)$

* $\mathcal{Q}'$ as $\mathcal{Q}$ but with $m_i^+ + 1, m_i^- - 1$; then $W(\mathcal{Q}' \rightarrow \mathcal{Q}) = \frac{\alpha}{2} (m_i^+ + 1)$

* $\mathcal{Q}'$ as $\mathcal{Q}$ but with $m_i^- + 1, m_i^+ - 1$; then $W(\mathcal{Q}' \rightarrow \mathcal{Q}) = \frac{\alpha}{2} (m_i^- + 1)$

② $\mathcal{Q}'$ such that $W(\mathcal{Q} \rightarrow \mathcal{Q}') \neq 0$, e.g.



* $\mathcal{Q}'$ as $\mathcal{Q}$ but with $\{m_i^+ - 1, m_{i+1}^+ + 1\}$, $W(\mathcal{Q} \rightarrow \mathcal{Q}') = p m_i^+ \left(1 - \frac{m_{i+1}^-}{m_\mu}\right)$

* $\mathcal{Q}'$ as $\mathcal{Q}$ but with $\{m_{i+1}^- - 1, m_i^- + 1\}$, $W(\mathcal{Q} \rightarrow \mathcal{Q}') = p m_{i+1}^- \left(1 - \frac{m_i^+}{m_\mu}\right)$

$$* \text{ ————— } \{ \mu_i^+ - 1, \mu_i^- + 1 \}, \boxed{W(\varphi \rightarrow \varphi') = \frac{\alpha}{2} \mu_i^+}$$

$$* \text{ ————— } \{ \mu_i^- - 1, \mu_i^+ + 1 \}, \boxed{W(\varphi \rightarrow \varphi') = \frac{\alpha}{2} \mu_i^-}$$

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Master eq:

$$\begin{aligned} \partial_t P(\{\mu_j^+, \mu_j^-\}) = & \sum_i p(\mu_{i-1}^+ + 1) \left(1 - \frac{\mu_{i-1}^+}{\mu_{\mu}}\right) P(\{\mu_{i-1}^+ + 1, \mu_i^+ - 1\}) \\ & + p(\mu_{i+1}^- + 1) \left(1 - \frac{\mu_{i+1}^-}{\mu_{\mu}}\right) P(\{\mu_{i+1}^- + 1, \mu_i^- - 1\}) \\ & + \frac{\alpha}{2} (\mu_i^+ + 1) P(\{\mu_i^+ + 1, \mu_i^- - 1\}) + \frac{\alpha}{2} (\mu_i^- + 1) P(\{\mu_i^- + 1, \mu_i^+ - 1\}) \\ & - \left[p \mu_i^+ \left(1 - \frac{\mu_{i-1}^+}{\mu_{\mu}}\right) + p \mu_i^- \left(1 - \frac{\mu_{i+1}^-}{\mu_{\mu}}\right) + \frac{\alpha}{2} \mu_i^+ + \frac{\alpha}{2} \mu_i^- \right] P(\{\mu_i^+, \mu_i^-\}) \end{aligned}$$

where $P(\{\mu_i^+ + 1, \mu_j^+ - 1\}) = P(\varphi' = \varphi \text{ with } \mu_i^+ \text{ replaced by } \mu_i^+ + 1 \text{ and } \mu_j^+ \text{ replaced by } \mu_j^+ - 1)$

From there, use $\langle \mu_i^+ \rangle = \sum_{\{\mu_j^+\}} \mu_i^+ P(\{\mu_j^+\})$ to get $\partial_t \langle \mu_i^+ \rangle$ from the master equation $\Rightarrow$ good luck!

Evolution of observable: $\langle \mathcal{O}(\varphi) \rangle = \sum_{\varphi} \mathcal{O}(\varphi) P(\varphi, t) = \langle \mathcal{O} \rangle_{\varphi}$

$$\partial_t \langle \mathcal{O} \rangle_{\varphi} = \sum_{\varphi} \mathcal{O}(\varphi) \partial_t P(\varphi, t) \rightarrow \text{Master equation}$$

$$= \sum_{\varphi, \varphi'} \mathcal{O}(\varphi) [W(\varphi' \rightarrow \varphi) P(\varphi') - W(\varphi \rightarrow \varphi') P(\varphi)]$$

$\varphi \leftrightarrow \varphi'$

$$= \sum_{\varphi, \varphi'} \mathcal{O}(\varphi') W(\varphi \rightarrow \varphi') P(\varphi) - \mathcal{O}(\varphi) W(\varphi \rightarrow \varphi') P(\varphi)$$

$$= \sum_{\varphi} \left[\sum_{\varphi'} (\mathcal{O}(\varphi') - \mathcal{O}(\varphi)) W(\varphi \rightarrow \varphi') \right] P(\varphi)$$

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$$\partial_t \langle \mathcal{O} \rangle_{\varphi} = \left\langle \underbrace{\sum_{\varphi'} (\mathcal{O}(\varphi') - \mathcal{O}(\varphi))}_{\Delta \mathcal{O}(\varphi \rightarrow \varphi')} \underbrace{W(\varphi \rightarrow \varphi')}_{\text{rate at which this change occurs}} \right\rangle_{\varphi}$$

change in $\mathcal{O}$ from φ to φ'

Dynamics of the average occupancies: $\partial_t \langle n_i^{\pm} \rangle = ?$

Consider φ' that can be reached from $\varphi = \{n_i^{\pm}, n_{i+1}^{\pm}\}$
and compute $n_i^{\pm}(\varphi') - n_i^{\pm}(\varphi) = \Delta n_i^{\pm}$

Moves that impact $n_i^{\pm}$ are: $\therefore$ hops into or out of site i
• tumble at site i

$$\begin{aligned} \partial_t \langle n_i^+ \rangle = & \left\langle \overbrace{(+1) \times p n_{i-1}^+ (1 - \frac{n_i}{n_m})}^{\Delta n_i^+} \right\rangle + \left\langle \overbrace{(-1) \times p n_i^+ (1 - \frac{n_{i+1}}{n_m})}^{\Delta n_i^+} \right\rangle \\ & + \left\langle \overbrace{(-1) \times \frac{\alpha}{2} n_i^+}^{\Delta n_i^+} \right\rangle + \left\langle \overbrace{(+1) \times \frac{\alpha}{2} n_i^-}^{\Delta n_i^+} \right\rangle \end{aligned}$$

tumble + - - *tumble - - +*

$$\partial_t \langle n_i^+ \rangle = p \langle n_{i-1}^+ (1 - \frac{n_i}{n_m}) \rangle - p \langle n_i^+ (1 - \frac{n_{i+1}}{n_m}) \rangle - \frac{\alpha}{2} \langle n_i^+ \rangle + \frac{\alpha}{2} \langle n_i^- \rangle$$

$$\partial_t \langle n_i^- \rangle = p \langle n_{i+1}^- (1 - \frac{n_i}{n_m}) \rangle - p \langle n_i^- (1 - \frac{n_{i-1}}{n_m}) \rangle + \frac{\alpha}{2} \langle n_i^+ \rangle - \frac{\alpha}{2} \langle n_i^- \rangle$$

Comment: These equations involve $\langle n_{i-1}^{\pm}, n_i^{\pm} \rangle$, $\langle n_i^{\pm} n_{i+1}^{\pm} \rangle$, etc
 $\Rightarrow$ not closed equations for $\langle n_i^{\pm} \rangle$.

In practice N -point functions will involve $m+1$ point functions in their dynamics. We need approximations to get a solvable system. SS

Mean-field approximation: $\langle m_i^+ m_j^+ \rangle \simeq \langle m_i^+ \rangle \langle m_j^+ \rangle$

In general, this is quantitatively wrong, but often qualitatively right.

$$s_i^\pm = \langle m_i^\pm \rangle; \quad s_i = \langle m_i \rangle; \quad s_m = m$$

$$\text{Dynamics: } \partial_t s_i^+ = p \left[s_{i-1}^+ \left(1 - \frac{s_i}{s_m} \right) - s_i^+ \left(1 - \frac{s_{i+1}}{s_m} \right) \right] - \frac{\alpha}{2} s_i^+ + \frac{\alpha}{2} s_i^- \quad (1)$$

$$\partial_t s_i^- = p \left[s_{i+1}^- \left(1 - \frac{s_i}{s_m} \right) - s_i^- \left(1 - \frac{s_{i-1}}{s_m} \right) \right] + \frac{\alpha}{2} s_i^+ - \frac{\alpha}{2} s_i^- \quad (2)$$

Typical microscopic length $d_p = \frac{p}{\alpha} \Rightarrow$ expect variations of $s_i^\pm$ on this scale. If $\frac{p}{\alpha} \gg 1$, little differences between $s_i^\pm$ and $s_{i\pm 1}^\pm$.

$$\Rightarrow \text{Taylor expand } O_{i\pm 1} \simeq O(x) \pm \frac{1}{L} \nabla O(x) + \frac{1}{2L^2} \Delta O(x); \quad x = \frac{i}{L} \in [0, 1]$$

Carrying out this expansion in (1) & (2) leads to $\nabla = \partial_x; \Delta = \partial_{xx}$

$$\partial_t s^+(x) = -\frac{p}{L} (\partial_x s^+) \left(1 - \frac{s}{s_m} \right) + \frac{p}{L} s^+ \frac{\nabla s}{s_m} + \frac{p}{2L^2} \Delta s^+ \left(1 - \frac{s}{s_m} \right) + \frac{p s^+}{2L^2} \frac{\Delta s}{s_m} - \frac{\alpha}{2} s^+ + \frac{\alpha}{2} s^- \quad (3)$$

$$\partial_t s^-(x) = \frac{p}{L} (\partial_x s^-) \left(1 - \frac{s}{s_m} \right) - \frac{p}{L} s^- \frac{\partial_x s}{s_m} + \frac{p}{2L^2} (\partial_{xx} s^-) \left(1 - \frac{s}{s_m} \right) + \frac{p}{2L^2} s^- \frac{\partial_{xx} s}{s_m} + \frac{\alpha}{2} s^+ - \frac{\alpha}{2} s^- \quad (4)$$

$$s(x) = s^+(x) + s^-(x); \quad m(x) = s^+(x) - s^-(x)$$

$$(3) + (4) \Rightarrow \partial_t s(x) = -\partial_x \left[\frac{p}{L} m \left(1 - \frac{s}{s_m} \right) - \frac{p}{2L^2} \partial_x s \right] \quad (5)$$

$$(3) - (4) \Rightarrow \partial_t m(x) = -\alpha m(x) - \partial_x \left[\frac{p}{L} s \left(1 - \frac{s}{s_m} \right) \right] + \frac{p}{2L^2} (\partial_{xx} m) \left(1 - \frac{s}{s_m} \right) + \frac{p}{2L^2} m \left(\frac{\partial_{xx} s}{s_m} \right) \quad (6)$$

Analysis of (5) - (6) in the large L limit:

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$L \rightarrow \infty$ (5): $\partial_t s = 0 \Rightarrow$ Nothing happens in a time of order 1 for a conserved field in the large size limit.

Speed up time $t = L\tau$

$$(5) \Rightarrow \frac{ds}{d\tau} = -\partial_x \left[\rho m(x) \left(1 - \frac{s(x)}{s_m}\right) - \frac{P}{2L} \partial_x s \right] \quad (5)'$$

$$(6) \quad m(x) = -\alpha L m - P \partial_x \left[s \left(1 - \frac{s}{s_m}\right) \right] + \frac{P}{2L} (\partial_{xx} m) \left(1 - \frac{s}{s_m}\right) + \frac{P}{2L} m \partial_{xx} s$$

If $\partial_{xx} s$ & $\partial_{xx} m$ are finite, then the last two terms are negligible.

$$m(x) = -\alpha L m(x) - P \partial_x \left[s \left(1 - \frac{s}{s_m}\right) \right]$$

exponential
relaxation
in affine scale
 $\tau \sim \frac{1}{\alpha L}$

external
source

$$\Rightarrow m(x) = -\frac{P}{\alpha L} \partial_x \left[s \left(1 - \frac{s}{s_m}\right) \right] \quad \text{for } \tau \sim O(1)$$

Injecting $m(x)$ back into (5)' then leads to

$$\dot{s} = \partial_x \left[\frac{P^2}{\alpha L} \left(1 - \frac{s(x)}{s_m}\right) \partial_x \left[s \left(1 - \frac{s}{s_m}\right) \right] + \frac{P}{2L} \partial_x s \right]$$

Again $\dot{s} \sim 0$ for $\tau \sim O(1) \Rightarrow \tau = L \tilde{\tau} \Rightarrow t = L^2 \tilde{\tau}$ (diffusive scaling)

$$\frac{ds(x)}{d\tilde{\tau}} = \partial_x \left[\left(\frac{P}{2} + \frac{P^2}{\alpha} \left(1 - \frac{s}{s_m}\right) \left(1 - \frac{2s}{s_m}\right) \right) \partial_x s \right]$$

$$\equiv \partial_x \left[D_{eff}(s(x)) \partial_x (s) \right]$$

At the macroscopic $x = \frac{\bar{c}}{L}$; $\bar{c} = \frac{c}{L}$; we obtain an effective dynamics for the density field which is a non-linear diffusion equation.

If $D_{eff}(s_0) > 0 \Rightarrow$ small fluctuations around s_0 relax to 0.

— $D_{eff}(s_0) < 0 \Rightarrow$ ————— get amplified

$$(\dot{s} = D \Delta s \xrightarrow{\epsilon \rightarrow 0, \epsilon} \dot{s} = (-D) \Delta s)$$

$\Rightarrow$ linear instability

$$D_{eff} < 0 \Leftrightarrow \left(\frac{2s}{s_m} - 1\right) \left(1 - \frac{s}{s_m}\right) \geq \frac{\alpha}{2\rho} = \frac{1}{2\ell_p} \Rightarrow \text{persistence length}$$

$$\ell_p \gg 1 \Rightarrow \text{instability for } s \geq \frac{s_m}{2}$$

Comment: hopping rate $\Leftrightarrow v(s) = \rho \left(1 - \frac{s}{s_m}\right)$ } the result of our computation is consistent with the head-waving argument.

$$\frac{v'}{v} \leq -\frac{1}{s} \Leftrightarrow s \geq \frac{s_m}{2}$$

What remains is to characterize the phase coexistence emerging from this instability $\Rightarrow$ Derive the master eq. & look for effective free energy.

IV Population dynamics & pattern formation

Time scale:

- ① R&T dynamics $\sim 1s$
- ② diffusion approximation $\sim 1min$
- ③ bacterial division $\sim 1hour$ (20' for e.coli in good conditions)

To describe experiments on time scale of days:

- $\rightarrow$ approximate ① by ②
- $\rightarrow$ model ③

IV.1) The logistic growth

Model: bacteria divide at rate $\tilde{b}(s) \approx \tilde{b}_0 - \tilde{b}_1 s + O(s^2)$
competition for food

bacteria "die" at rate $\tilde{d}(s) \approx \tilde{d}_0 + \tilde{d}_1 s$

Comment death is a very complicated process for bacteria: stop growing, stop running, cell lysis $\Rightarrow$ many different time-scale.
 Here $\Rightarrow$ assume $s(\vec{r}, t)$ fraction "healthy" bacteria

Mean-field dynamics: $\frac{d}{dt} s = \nabla[\dots] + s b(s) - s d(s)$
 $= \nabla[\dots] + \mu s (1 - \frac{s}{s_0})$

$\begin{aligned} b &= \tilde{b}_0 \ln 2 \\ s(t+1) &= 2^{\tilde{b}_1 t} s_0 = e^{\tilde{b}_1 t + \ln 2} s_0 \end{aligned}$

with $\mu = b_0 - d_0$ and $s_0 = \frac{\mu}{b_1 + d_1}$ $\hookrightarrow$ logistic term

homogeneous dynamics: $\frac{d}{dt} s = \mu s (1 - \frac{s}{s_0})$
 * two fixed points $s=0$ & $s=s_0 \Rightarrow$ stability?

$$p = 0 + \delta p \Rightarrow \frac{d}{dt} \delta p = \mu \delta p \Rightarrow \delta p \sim e^{\mu t} \Rightarrow p = 0 \text{ unstable}$$

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$$p = p_0 + \delta p \Rightarrow \frac{d}{dt} \delta p = -\mu \delta p \Rightarrow \delta p \sim e^{-\mu t} \Rightarrow p = p_0 \text{ stable}$$

* How does $g(t)$ relax towards $g = p_0$?

$$\Rightarrow \text{Solve through separation of variables} \quad \frac{dg}{g(1-\frac{g}{p_0})} = \mu dt$$

$$\left[\phi = \frac{g}{p_0} \Rightarrow \frac{d\phi}{\phi} + \frac{d\phi}{1-\phi} = \mu dt \Rightarrow \ln \frac{\phi}{1-\phi} = \tilde{k} + \mu t \right.$$

$$\left. \Rightarrow \frac{\phi}{1-\phi} = k e^{\mu t} = \frac{g(t)}{p_0 - g(t)} \right.$$

$$\Rightarrow g(t) = \frac{p_0 k e^{\mu t}}{1 + k e^{\mu t}}$$

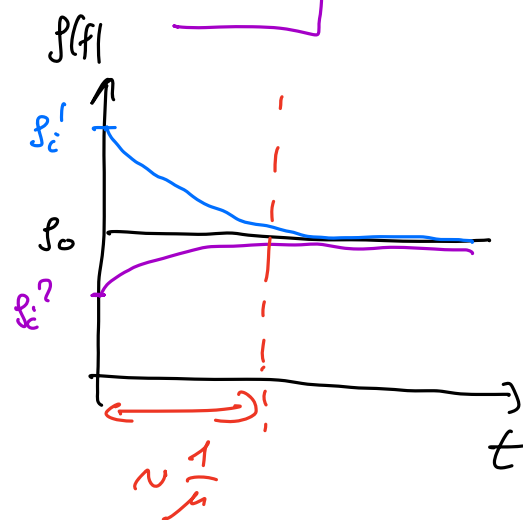
$$t=0 \quad g(t) = p_i = \frac{p_0 k}{1+k} \Rightarrow k = \frac{p_i/p_0}{1 - p_i/p_0}$$

$$\Rightarrow g(t) = \frac{p_i}{1 - \frac{p_i}{p_0}} \cdot \frac{1}{e^{-\mu t} + \frac{p_i/p_0}{1 - \frac{p_i}{p_0}}} = \frac{p_i}{1 - \frac{p_i}{p_0}} \cdot \frac{1 - \frac{p_i}{p_0}}{\frac{p_i}{p_0} + e^{-\mu t} (1 - \frac{p_i}{p_0})}$$

$$g(t) = \frac{p_i p_0}{p_i + (p_0 - p_i) e^{-\mu t}}$$

$$t=0 \quad g(t) = p_i$$

$$t \rightarrow \infty \quad g(t) = p_0$$



$\Rightarrow$ exponential relaxation towards $g(t) = p_0$

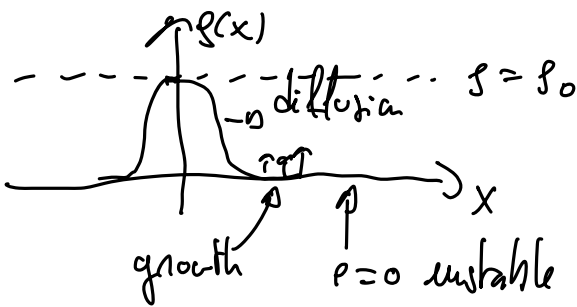
IV. 2) Colony spreading & Fisher waves

60

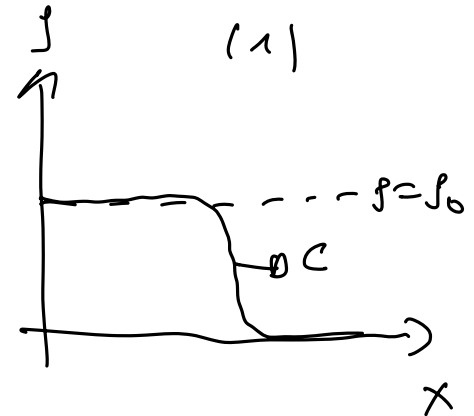
diffusion + logistic growth

$$\dot{f} = D \Delta f + \alpha f \left(1 - \frac{f}{f_0}\right) \quad (1)$$

Initial condition



diffusion + growth $\Rightarrow$ steady wave



existence of travelling wave

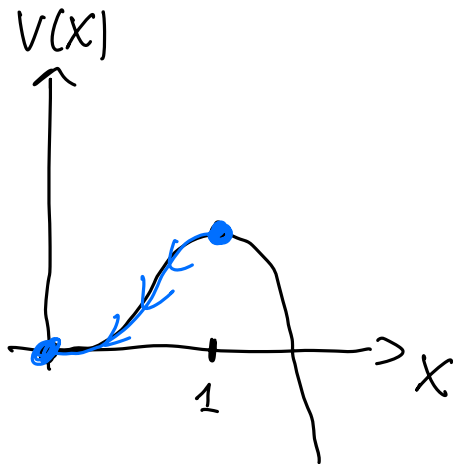
$f(x,t) \equiv X(x-ct)$ for some function $X(\tau)$ when $\tau = x-ct$

$$(1) \Leftrightarrow D X'' + \alpha X(1-X) = -c X'$$

$$\Leftrightarrow D \frac{d^2}{d\tau^2} X(\tau) = -c \frac{dX}{d\tau} - \frac{d}{dX} V(X) ; V(X) = -\alpha \frac{X^3}{3} + \alpha \frac{X^2}{2}$$

No oscillation in $X < 0$ region!

(1) $\Leftrightarrow$



(1) $\Leftrightarrow$ over damped relaxation in the potential well

linear stab of: $\begin{cases} \dot{X} = v \\ D \dot{v} = -c v - \alpha X(1-X) \end{cases}$ close to $(0,0)$

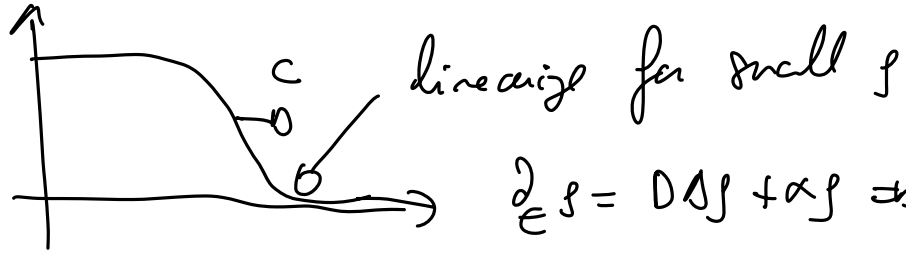
$$\frac{d}{d\epsilon} \begin{pmatrix} \delta x \\ \delta v \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -\frac{\alpha}{D} & -\frac{c}{D} \end{pmatrix} \begin{pmatrix} \delta x \\ \delta v \end{pmatrix}$$

$$M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$\lambda_{\pm} = \frac{a+d}{2} \pm \frac{1}{2} \sqrt{(a-d)^2 + 4bc}$$

$$\lambda_{\pm}^{\pm} = -\frac{c}{2D} \pm \frac{1}{2} \sqrt{\frac{c^2}{D^2} - 4\frac{\alpha}{D}} \Rightarrow \boxed{c^2 > 4\alpha D}$$

Selection principle: pulled wave



$$\partial_t g = D \partial_x^2 g + \alpha g \Rightarrow \partial_t \hat{g}(q) = (\alpha - Dq^2) \hat{g}(q)$$

$$\Rightarrow \hat{g}(q) = \hat{g}_i(q) e^{(\alpha - Dq^2)t}$$

$$\Rightarrow g(\underbrace{x-ct}_z) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dq \hat{g}_i(q) e^{(\alpha - Dq^2)t} e^{iq(\underbrace{x-ct+ct}_z)}$$

$$g(z) = \int_{-\infty}^{\infty} \frac{dq}{2\pi} e^{iqz + t[\alpha - Dq^2 + iqc]}$$

$$\text{large } t \Rightarrow \text{saddle point } \frac{d}{dq} [\alpha - Dq^2 + iqc] = 0 \Rightarrow \boxed{c = -2iq^*}$$

$$q^* = q_n + iq_i \Rightarrow q_n = 0 \text{ \& } \boxed{c = 2Dq_i}$$

$$\text{Steady solution} \Rightarrow \text{Re} [\alpha - Dq^{*2} + iq^*c] = 0 = \alpha + Dq_i^2 - cq_i = 0$$

$$\Rightarrow \alpha = Dq_i^2 \Rightarrow q_i = \sqrt{\frac{\alpha}{D}} \Rightarrow \boxed{c = 2\sqrt{D\alpha}}$$

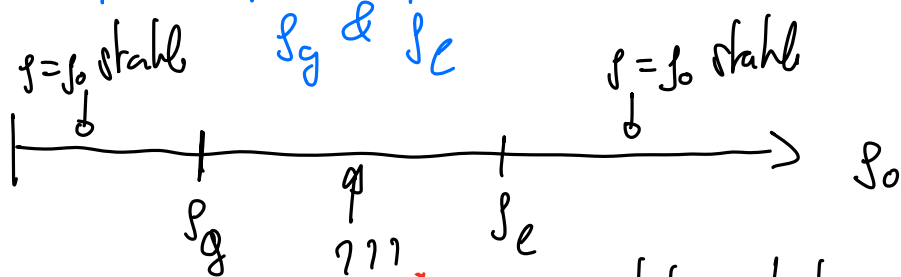
The slowest speed is selected.

IV.3 Mobility-induced pattern formation

IV.3.1 From MIPS to finite-size patterns

Long-time dynamics

$$\partial_t s = \underbrace{\partial_x \left\{ s D \partial_x \left[\ln s + \ln v(s) + \frac{\sigma^2 v'}{v} \partial_x s \right] \right\}}_{\text{monoton phase-separation between } s_g \text{ \& \; } s_e} + \underbrace{\alpha s \left(1 - \frac{s}{s_0} \right)}_{\text{monote } s \approx s_0}$$



competition between MIPS & population dynamics

$$s(x) = s_0 + \delta s(x)$$

$$\Rightarrow \partial_t \delta s(x) = \partial_x \left\{ s_0 D(s_0) \partial_x \left[\frac{\delta s}{s_0} + \frac{v'(s_0)}{v(s_0)} \delta s + \frac{\sigma^2 v'(s_0)}{v(s_0)} \partial_x \delta s \right] \right\} - \alpha \delta s$$

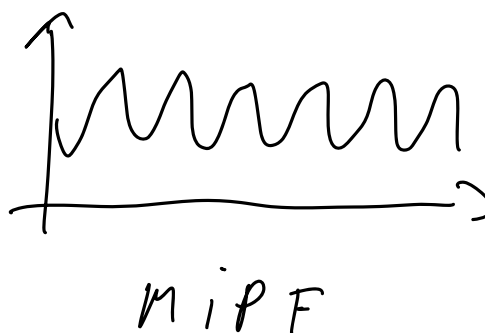
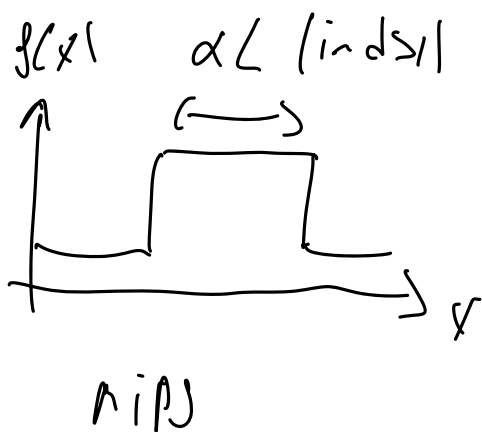
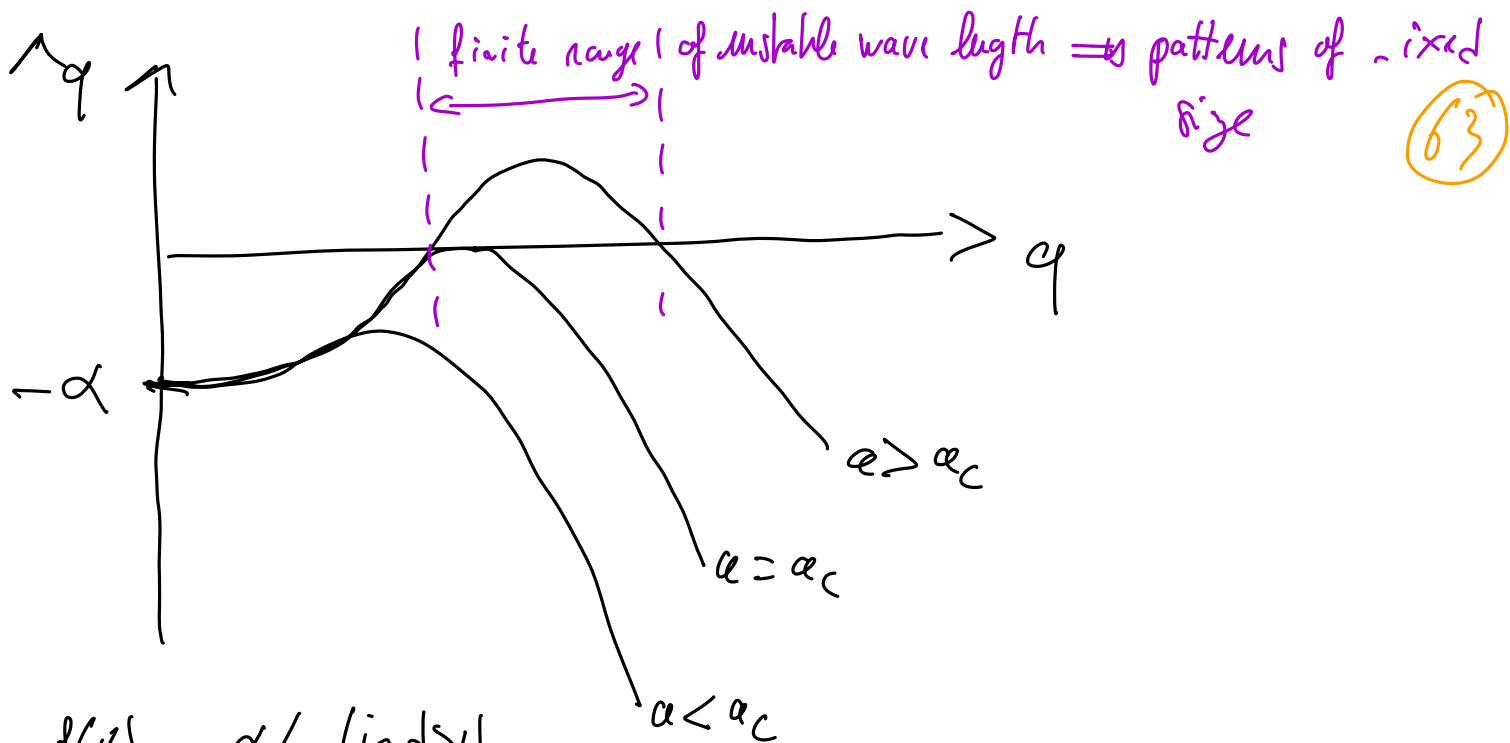
Fourier transform $\delta s(x) \rightarrow \delta s(q)$ $\partial_x \rightarrow iq$

$$\begin{aligned} \partial_t \delta s(q) &= -q^2 s_0 D(s_0) \left[\frac{1}{s_0} + \frac{v'(s_0)}{v(s_0)} \right] \delta s_q + \frac{\sigma^2 v'(s_0)}{v(s_0)} q^4 \delta s_q - \alpha \delta s_q \\ &= \Lambda_q \delta s_q \end{aligned}$$

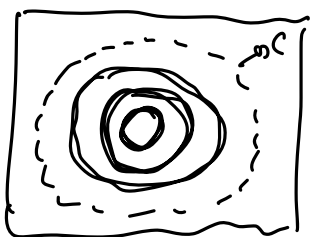
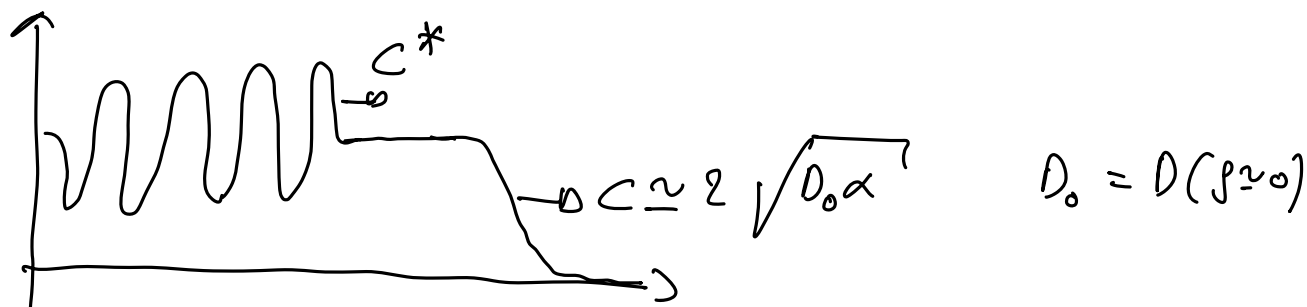
$$\Lambda_q = -\alpha - q^2 s_0 D(s_0) \left[\frac{1}{s_0} + \frac{v'(s_0)}{v(s_0)} \right] + \frac{\sigma^2 v'(s_0)}{v(s_0)} q^4$$

$$\text{MIPS: } \frac{v'(s_0)}{v(s_0)} < 0 \Rightarrow \Lambda_q = -\alpha + a q^2 - b q^4 \quad ; a, b > 0$$

$$\begin{aligned} \Lambda_q = 0 &\Leftrightarrow a^2 - 4\alpha b > 0 \\ a_c &= 2\sqrt{\alpha b} \end{aligned}$$



(V.3.2) Colony growth & MIPF



c^* can also be computed
and can be larger or smaller
than c .

This can be extended to active mixtures and complex ecosystems.

Refs: Cates et al, PNAS 107, 11715-11720, (2010)

Lin et al, Science 334, 238 (2011)

Curatolo et al, Nat. Phys. 16, 1152 (2020)