

Ilker Yildirim
ilkery@mit.edu

Positions

Massachusetts Institute of Technology
Department of Brain & Cognitive Sciences
Research Scientist, 2016-present.

Massachusetts Institute of Technology
Department of Brain & Cognitive Sciences
The Rockefeller University
Laboratory of Neural Systems (joint)
Postdoctoral fellow, 2014-2016.

Education

2014, Ph.D., Brain & Cognitive Sciences and Computer Science (joint), University of Rochester.

Thesis: From Perception to Conception: Learning Multisensory Representations
2011, M.A., Brain & Cognitive Sciences, University of Rochester.

2009, M.S., Computer Science, Bogazici University, Istanbul, Turkey.

2007, B.S., Computer Science, Bogazici University, Istanbul, Turkey.

Publications

(Rigorously & competitively peer-reviewed. * indicates equal contribution.)

- Yildirim, I., Freiwald, W. F., & Tenenbaum, J.B. (under revision). Efficient inverse graphics in biological face processing. *bioRxiv* 282798.
- Yildirim, I., Wu, J., Kanwisher, N., & Tenenbaum, J.B. (submitted). An integrative computational architecture for object-driven cortex.
- Yildirim, I., Siegel, M., & Tenenbaum, J.B. (to appear). Physical object representations for perception and cognition. *The Cognitive Neurosciences, 6th edition*, Gazzaniga, Mangun, Poeppel (Editors).
- Bates, C.J., Yildirim, I., Battaglia, P.W., & Tenenbaum, J.B. (revised & resubmitted). Modeling human intuitions about liquid flow with particle-based simulation *arXiv:1809.01524*
- Yildirim, I.*, Smith, K.*, Belledonne, M.*, Wu, J., & Tenenbaum, J.B. (2018). Neurocomputational modeling of human physical scene understanding. *In 2nd Cognitive Computational Neuroscience Conference (CCN)*. [Selected as a talk.]
- Yildirim, I.*, Gerstenberg, T.*, Saeed, B., Toussaint, M., & Tenenbaum, J.B. (2017). Physical problem solving: Joint planning with symbolic, geometric, and dynamic constraints. *In 39th Annual Conference of the Cognitive Science Society (CogSci)*.
- Janner, M., Wu, J., Kulkarni, T., Yildirim, I., Tenenbaum, & J.B. (2017). Self-supervised intrinsic image decomposition. *Neural Information Processing Systems (NIPS)*.
- Yildirim, I.*, Janner M.*, Belledonne, M., Wallraven, C., Freiwald, W., & Tenenbaum, J.B. (2017). Causal and compositional generative models in online perception. *In 39th Annual Conference of the Cognitive Science Society (CogSci)*.
- Yildirim, I.*, Siegel, M.*, & Tenenbaum, J.B. (2016). Perceiving Fully Occluded Objects via Physical Simulation. *In 38th Annual Conference of the Cognitive Science Society (CogSci)*.
- Allen, K.R., Yildirim, I., & Tenenbaum, J.B. (2016). Integrating Identification and

Perception: A case study of familiar and unfamiliar face processing. *In 38th Annual Conference of the Cognitive Science Society (CogSci)*.

- Yildirim, I.*, Wu, J.*, Lim, J., Freeman, W.T., & Tenenbaum, J.B. (2015). Galileo: Perceiving physical object properties by integrating a physics engine with deep learning. *Neural Information Processing Systems (NIPS)*.
- Erdogan, G., Yildirim, I., & Jacobs, R. A. (2015). From Sensory Signals to Modality-Independent Conceptual Representations: A Probabilistic Language of Thought Approach. *PLoS Computational Biology*.
- Yildirim, I., Kulkarni, T.D., Freiwald, W.A., & Tenenbaum, J.B. (2015). Efficient analysis-by-synthesis in vision: A computational framework, behavioral tests, and comparison with neuronal representations. *In 37th Annual Conference of the Cognitive Science Society (CogSci)*.
- Bates, C. J., Yildirim, I., Tenenbaum, J.B., & Battaglia, P.W. (2015). Humans predict liquid dynamics using probabilistic simulation. *In 37th Annual Conference of the Cognitive Science Society (CogSci)*.
- Yildirim, I. & Jacobs, R.A. (2015). Learning Multisensory Representations for Auditory-Visual Transfer of Sequence Category Knowledge: A Probabilistic Language of Thought Approach. *Psychonomic Bulletin & Review*.
- Yildirim, I., Degen, J., Tanenhaus, M. K., & Jaeger, T. F. (2015). Talker-specificity and adaptation in quantifier interpretation. *Journal of Memory and Language*.
- Erdogan, G., Yildirim, I., & Jacobs, R. A. (2014). Transfer of object shape knowledge across visual and haptic modalities. *In 36th Annual Conference of the Cognitive Science Society (CogSci)*.
- Transfer of Object Category Knowledge Across Visual and Haptic Modalities: Experimental and Computational Studies. Yildirim, I. & Jacobs, R. A. (2013). *Cognition*.
- Yildirim, I. & Jacobs, R.A. (2012). A Rational Approach to the Acquisition of Multisensory Representations. *Cognitive Science*.
- Yildirim, I. & Jacobs, R.A. (2010). A Bayesian Nonparametric Approach to Multisensory Perception. *In 32nd Annual Conference of the Cognitive Science Society (CogSci)*.
- Yildirim, I. & Yolum, P. (2009). Hybrid Models for Achieving and Maintaining Cooperative Symbiotic Groups. *Mind & Society*.
- Yildirim, I., Aran, O., Yolum, P., & Akarun, L. (2009). Cooperative Sign Language Tutoring: A Multiagent Approach. *In Proceedings of Engineering Societies in Agents' World X*.
- Yildirim, I. & Yolum, P. (2008). Hybrid Models for Achieving and Maintaining Collaborative Symbiotic Groups. *In 5th European Social Simulation Association Conference*.

Invited talks

- Dagstuhl Seminar in “3D Morphable Models”, Leibniz-Zentrum für Informatik, March 03-08, 2019.
- Columbia University, Center for Theoretical Neuroscience Seminar Series. New York, February 2018.

- Cognitive Neuroscience Society (CNS) Invited Symposium, Boston, March 2018.
- Hierarchical Multisensory Integration Workshop, Barcelona, June 2017.
- University of Toronto, Department of Computer Science Seminar, April 2017.
- Vision seminar, MIT, March 2017.
- Brown University, Perception and Action Seminar Series, December 2016.
- Physical and Social Scene Understanding Workshop, CogSci Conference, August 2016.
- University Electro-Communications, Tokyo; Workshop on Object vision, November 2015.
- RIKEN Institute, Tokyo; Special seminar, November 2015.
- Face ID Challenge Workshop, MIT, September 2015.
- Tong lab, Vanderbilt University, February 2014.
- Saxe Lab, MIT, January 2014.

Students

(+ indicates
co-authored at least
one paper)

- Mario Belledonne⁺. BCS post-bach research assistant. 2016-present.
- Amir Soltani. BCS post-bach research assistant. 2016-present.
- Basil Saeed⁺. EECS & BCS undergraduate. 2016-present.
- Kate Lin. Wellesley Uni. Neuroscience and Psychology undergraduate. 2018-present.
- Sualeh Asif. MIT undergraduate. 2018-present.
- Michael Janner⁺. EECS undergraduate. 2015-2018.
- Shraman Chaudhuri. EECS MSc. 2016-2018.
- Aaditya Singh. EECS & BCS undergraduate. 2017-2018.
- Skylar Sutherland. BCS & Math undergraduate. 2018 summer.
- Pallavi Mishra. EECS MSc. 2016-2017.
- Wendy Wei. BCS undergraduate. 2015-2016.

Teaching

Guest lecturer

- Neurally Inspired Models of Information Processing (Fall 2011, Summer 2012, Fall 2012, Summer 2013). University of Rochester.
 - Dynamical Systems (Fall 2011). University of Rochester.
 - Motor Control (Fall 2010). University of Rochester.

Teaching Assistant

- Cognition, Spring 2011. University of Rochester.
- Foundations of Cognitive Science, Fall 2011; University of Rochester.
- Neural Foundations of Behavior, Fall 2012. University of Rochester.

Service **Organizer**, *Deep Learning in Computational Cognitive Science*, CogSci conference, July 2017.

Reviewer for *Psychological Review*, *Proceedings of the National Academy of Sciences*, *Attention, Perception & Psychophysics*, *IEEE PAMI*, *IET Computer Vision*, *Annual Conference of the Cognitive Science Society (CogSci)*, *Cognitive Computational Neuroscience Conference (CCN)*.

Press coverage WIRED magazine, “MIT Researchers Want to Teach Robots How to Wash Dishes”, 2015.

VICE magazine, “How to Teach a Robot to Build a Rube Goldberg Machine”, 2015.

Boston globe, “MIT system makes human-like predictions about how objects move through the world”, 2015.

Awards Schloss Dagstuhl - NSF Support Grant. 2018.

Outstanding dissertation prize, University of Rochester. 2015.

Best paper award, Engineering Societies in the Agents’ World X, 2009, for “Cooperative sign language tutoring: A multiagent approach.”