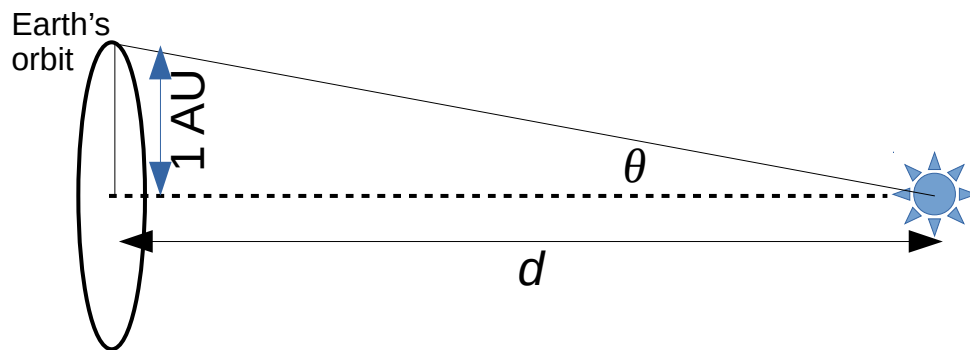


## Lecture 2

- Space is Big.
- Last time we talked about mass scales; today we'll talk about **size scales**:
  - Bohr radius  $\rightarrow p^2/2m \sim \hbar^2 / (2 m a^2) \sim e^2/a \rightarrow 5.3e-9$  cm
  - Rearth =  $6.3e8$  cm = (20000 / pi) km
  - R<sub>sun</sub> =  $7e10$  cm
  - 1 AU =  $1.5e13$  cm  $\sim 8$  light-seconds
  - 1 parsec = 1 pc =  $3e18$  cm = 3.26 light years (note that l.y. are  $\sim$ never used in astrophysics)
- **Parsec** is the fundamental unit of distance; it is  $\sim$ the typical distance between stars (though that's just a coincidence). It is observationally defined:

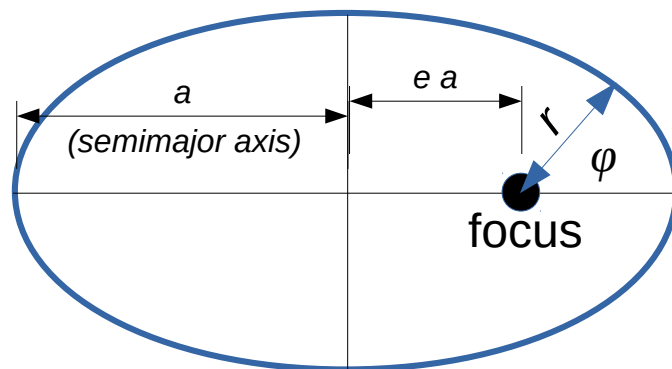


- Over one year, the Earth's displacement is 2 AU and an object at distance  $d$  changes apparent position by  $2\theta$ , where
 
$$\tan \theta = 1 \text{ AU} / d, \text{ or}$$

$$d = 1 \text{ AU} / \theta, \text{ or}$$

$$d / 1 \text{ pc} = 1 \text{ arcsec} / \theta$$
- Nearest star: 1.3 pc  
To our galactic center: 8 kpc (kiloparsecs)  
To the nearest big galaxy: 620 kpc !!
- **Cosmic Distance Ladder:**
  - Distance is a key concept in astrophysics – e.g. the revolution currently underway thanks to ESA's Gaia mission (measuring parallax for billions of objects with sub-milliarcsec precision)
  - “Distance ladder” refers to the bootstrapping of distance measurements, from nearby stars to the furthest edges of the observable universe.
  - Within solar system: light travel time. Radar, spacecraft communication, etc.
  - Parallax: the first rung outside the Solar system. Measured by Gaia (2<sup>nd</sup> data release) for  $\sim 1$  billion stars across  $\sim$ half of the Galaxy. A revolution is underway!

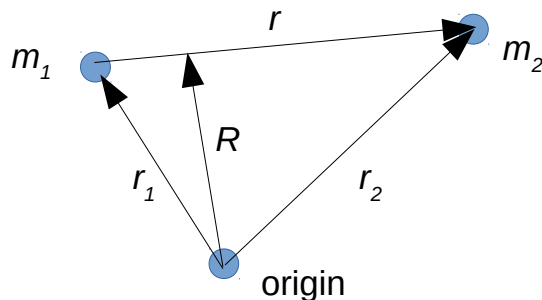
- Standard candles: if Luminosity  $L$  is known, then observed flux  $F$  gives distance:  
 $F = L / 4 \pi d^2 \quad \rightarrow \quad d = (L / 4 \pi F)^{1/2}$   
 Most important types:
  - Cepheid variables - giant pulsating stars, period varies with absolute magnitude
  - Type Ia Supernovae – exploding stars (probably white dwarf)
  - Neither of these are truly standard – only “standardizable” (which is almost as good)
  - Other types (for other galaxies):
    - Tully-Fischer:  $L \sim V^2$  (rotational velocity of spiral galaxies)
    - Faber-Jackson:  $L \sim \sigma^2$  (velocity dispersion of elliptical galaxies)
- Hubble’s Law – for very distant Galaxies.
  - The universe is expanding at a nearly-constant rate (more on that in 8.902). Roughly, it expands evenly everywhere, so a distant galaxy’s apparent velocity is  $v = H_0 d$ . So,  $d = v / H_0$ .
  - Note that this doesn’t work for nearby galaxies like Andromeda (which is moving toward us due to gravity dominating over cosmic expansion).
- **The two-body problem** ← see Ch. 2 of Murray & Dermott
  - The motion of two bodies about one another due to their mutual gravity.
    - Planets orbiting stars
    - Stars orbiting each other
    - Objects orbiting white dwarf; neutron star; black hole
  - Certain quantities can be measured very precisely, enabling precise measurements of masses and sizes of bodies. E.g., binary pulsars (neutron stars): masses measured to within  $10^{-3} M_{sun}$  ( $\sim 0.1\%$ )
  - Goal here: Go through the gravitational two-body problem with an eye on features that are observationally testable, and on features specific to the  $1/r^2$  nature of gravity. Many “details” of the real world push us away from exact  $1/r^2$  – e.g. physical sizes, non-spherical shapes, general relativity
  - Key behavior we will use:
    - (1) Bodies move in elliptical trajectories (**Kepler’s 1<sup>st</sup> Law**)



$$r(\varphi) = \frac{a(1-e^2)}{1+e \cos \varphi}$$

- **2<sup>nd</sup> Law:** Motion sweeps out equal areas in equal times:  $dA/dt = \frac{1}{2} r^2 d\varphi/dt = \text{constant}$
- **3<sup>rd</sup> Law:**  $a^3/P^2 \sim (M_{tot})$  ← our eventual goal.  $P$ =orbital period,  $M_{tot}$  = total system mass

- To fully describe two pointlike bodies in 3D, we need 6 position components and 6 velocity components. (If they are not pointlike we need even more – in this case we use, e.g., Euler angles to define bodies' orientations.) Regardless, we need to reduce this to make things tractable!
- FIRST, go from 2 bodies to 1 ... we can do this for any central force (not just  $1/r^2$ ). This means converting potential:  $V(r_1, r_2) = V(|r_2 - r_1|)$  ← since potential depends only on relative position



- $\vec{r} = \vec{r}_2 - \vec{r}_1$  (eq 1)  
 $\vec{R} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2}$  (position of center of mass)  
 $\ddot{\vec{R}} = 0$  IF no external forces operate on the system.
- We can always set  $\dot{\vec{R}} = 0$  by choosing an inertial reference frame, and we can choose our origin so that  $\vec{R} = 0$  too.  
 That means that  $m_1 \vec{r}_1 + m_2 \vec{r}_2 = 0$  – combining with (eq 1) above shows that  

$$\vec{r}_2 = \frac{\vec{r}}{1 + m_2/m_1} \quad \text{and} \quad \vec{r}_1 = -\frac{m_2}{m_1} \vec{r}_2$$
- ... Which gives us the motions and velocities of both bodies in terms of the single variable  $r$ . So, we've reduced the 2-body problem to a one-body problem.