New constructions of RIP matrices
with fast multiplication and fewer rows

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Abstract

In this paper, we present novel constructions of matrices with the restricted isometry property (RIP) that support fast matrix-vector multiplication. Our guarantees are the best known, and can also be used to obtain the best known guarantees for fast Johnson Lindenstrauss transforms.

In compressed sensing, the *restricted isometry property* is a sufficient condition for the efficient reconstruction of a nearly k-sparse vector $x \in \mathbb{C}^d$ from m linear measurements Φx. It is desirable for m to be small, and further it is desirable for Φ to support fast matrix-vector multiplication. Among other applications, fast multiplication improves the runtime of iterative recovery algorithms which repeatedly multiply by Φ or Φ^*.

The main contribution of this work is a novel randomized construction of RIP matrices $\Phi \in \mathbb{C}^{m \times d}$, preserving the ℓ_2 norms of all k-sparse vectors with distortion $1+\varepsilon$, where the matrix-vector multiply Φx can be computed in nearly linear time. The number of rows m is on the order of $\varepsilon^{-2} k \log d \log^2(k \log d)$, an improvement on previous analyses by a logarithmic factor. Our construction, together with a connection between RIP matrices and the Johnson-Lindenstrauss lemma in [Krahmer-Ward, SIAM. J. Math. Anal. 2011], also implies fast Johnson-Lindenstrauss embeddings with asymptotically fewer rows than previously known.

Our construction is actually a recipe for improving any existing family of RIP matrices. Briefly, we apply an appropriate sparse hash matrix with sign flips to any suitable family of RIP matrices. We show that the embedding properties of the original family are maintained, while at the same time improving the number of rows. The main tool in our analysis is a recent bound for the supremum of certain types of Rademacher chaos processes in [Krahmer-Mendelson-Rauhut, Comm. Pure Appl. Math. to appear].

1   Introduction

The goal of *compressed sensing* [CRT06a,Don06] is to efficiently reconstruct sparse, high-dimensional signals from a small set of linear measurements. The idea is that if a signal $x \in \mathbb{C}^d$ has at most $k \ll d$ "large" entries (i.e. is "nearly k-sparse"), then we should be able to recover it with far fewer than d measurements.

Organizing the m measurements as the rows of a matrix $\Phi \in \mathbb{C}^{m \times d}$, one wants an efficient recovery algorithm $\mathcal{R}$ which approximately recovers x from Φx. Subject to the requirement that the recovery algorithm work—that is, $\mathcal{R}(\Phi x)$ should approximate x—there are two primary goals in the design of Φ and $\mathcal{R}$. First, we would like the number of measurements m to be as small as possible. Second, we would like for the recovery algorithm $\mathcal{R}$ be as efficient as possible.

In this paper, we improve the trade-off between these goals, by constructing matrices Φ which allow for very efficient recovery, and which use asymptotically fewer measurements than existing constructions with the same recovery properties. Our results (which will be explained in more detail below) are summarized in Figure 1.

Our work also implies more efficient dimension reducing maps. A *Johnson Lindenstrauss (JL) embedding* is a linear map that approximately preserves the geometry of a fixed set of points. JL embeddings have important algorithmic applications, where it is desirable that they be efficient to apply; if this is the case, they are known as *fast JL transforms* (FJLTs). Exploiting a connection of Krahmer and Ward [KW11] between compressed sensing and JL transforms, our results for compressed sensing matrices also imply improved FJLTs, resulting in the best known constructions. Further, recent work [YWR12] has established a similar connection to efficient *stable manifold embeddings,* and our constructions also give the best known embeddings in this setting.

1.1   The Restricted Isometry Property

In this paper, we construct matrices Φ which satisfy the *restricted isometry property* (RIP), support fast matrix-vector multiplication, and which require fewer measurements than previous analyses. The RIP is a popular way to obtain recovery guarantees in compressed sensing. We say that a matrix $\Phi \in \mathbb{C}^{m \times d}$ has the (ε, k)-RIP if for all k-sparse $x \in \mathbb{C}^d$,

$$(1 - \varepsilon)\|x\|_2^2 \leq \|\Phi x\|_2^2 \leq (1 + \varepsilon)\|x\|_2^2. \tag{1}$$

It is known that if Φ satisfies the (ε, k)-RIP for appropriately small ε, then it is possible to recover x from Φx [Can08, CRT06b, CT05]. Furthermore, the recovery can be done efficiently by solving a linear program [CRT06b, CDS01, DET06], or by one of several iterative recovery algorithms, for example those in [BD08, GK09, NT09, Fou11, TG07, DTDS12, NV09, NV10].

It is important for the measurement matrix Φ to allow for fast matrix-vector multiplication—ideally, in time nearly linear in d—because most of the algorithms above multiply repeatedly by either Φ or Φ^*. Usually, this multiplication is the bottleneck in the running time of the recovery algorithm.

There is a gap of several logarithmic factors between what one can do quickly and what one can do slowly, and our work shrinks this gap. If fast matrix-vector multiplication is not required, then RIP matrices exist with $m = \Theta(k \log(d/k))$, and this is known to be optimal [Kaš77, GG84]. On the other hand, if fast multiplication is required, the best constructions require polylogarithmically more measurements. A series of important contributions—discussed in detail in Section 1.3—have removed several successive log factors from this gap, and our work continues in this tradition. The

state-of-the-art constructions [RV08, KMR13] require three extraneous logarithmic factors. In this paper, we remove one log factor, leaving only two between our construction and the lower bounds. Moreover, the two remaining log factors come from a single source of slackness in our proof that also appears in both [RV08, KMR13]. Thus it seems likely that any future improvement would achieve an optimal result.

1.2 Johnson-Lindenstrauss embeddings

As mentioned above, our improved RIP matrices also imply the best known *fast Johnson-Lindenstrauss transforms.* The Johnson-Lindenstrauss (JL) lemma of [JL84] states that one can embed N points in ℓ_2^d into a linear subspace of dimension approximately $\log N$, with very little distortion.[1]

Lemma 1. *For any $0 < \varepsilon < 1/2$ and any $x_1, \ldots, x_N \in \mathbb{R}^d$, there exists a linear map $A \in \mathbb{R}^{m \times d}$ for $m = O(\varepsilon^{-2} \log N)$ such that for all $1 \le i < j \le N$,*

$$(1 - \varepsilon)\|x_i - x_j\|_2 \le \|Ax_i - Ax_j\|_2 \le (1 + \varepsilon)\|x_i - x_j\|_2. \tag{2}$$

This guarantee is nearly optimal, in the sense that there are sets of N vectors for which $m = \Omega((\varepsilon^{-2}/\log(1/\varepsilon))\log N)$ is required [Alo03].

The JL lemma is a useful tool for speeding up solutions to several problems in high-dimensional computational geometry; see for example [Ind01, Vem04]. Often, one has an algorithm which is fast in terms of the number of points but slow as a function of dimension; a good strategy to approximate a solution quickly is to first reduce the input dimension via the JL lemma before running the algorithm. This strategy has recently found applications in approximate numerical algebra problems such as linear regression and low-rank approximation [Sar06, CW09, CW12, MM12, NN12a], and for the k-means clustering problem [BZMD11]. Going back to our original problem, the JL lemma also implies the existence of (ε, k)-RIP matrices with $O(\varepsilon^{-2} k \log(d/k))$ rows [BDDW08].

Due to its algorithmic importance, it is of interest to obtain JL matrices (that is, matrices which satisfy (2)), which allow for fast embedding time. Ideally, the matrix-vector product Ax should be computed in time nearly linear in d.

As with the RIP, when a fast embedding time is required, there is a gap of several logarithmic factors between the upper and lower bounds on the target dimension m; a second contribution of this paper is to reduce this gap. If the embedding time may be slow, there are many constructions of dense JL matrices with $m = \Theta(\varepsilon^{-2} \log(N))$ [Ach03, AV06, DG03, FM88, IM98, JL84, Mat08]. On the other hand, there has been extensive work (discussed in detail below in Section 1.3) constructing JL matrices with fast embedding time and a small target dimension. One line of work demands an optimal number of measurements and has been improving the runtime; another line of work demands a fast runtime and has been improving the required number of measurements. In this paper, we add to the second line of work, removing a logarithmic factor in the number of measurements, while offering near-linear runtime. After our work, there are only three extraneous logarithmic factors remaining.

1.3 Previous Work on Fast RIP/JL

Above, we saw the importance of constructing RIP and JL matrices which not only have few rows but also support fast matrix-vector multiplication. Below, we review previous work in this direction.

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[1]The JL lemma is most commonly stated over $\mathbb{R}$, so we state it this way here. However, as in [KW11], all of our results extend to complex vectors and complex matrices.

We then state our contributions and improvements, which are summarized in Figure 1.

We stress that in this work, we are primarily interested in the case that the sparsity parameter k is large, for example $k > \sqrt{d}$. This is the regime most of interest to compressed sensing, as we see from the theoretical attention paid to $\log d$ vs $\log(d/k)$ [CRT06b, BDDW08] and from the experimental regimes generally studied [DT09, LDSP08]. It is also the regime where the problem remains open: the case when $k < \sqrt{d}$ was solved optimally in [AC09, AL09], with recent improvements by [AR13], and in fact follows easily from [RV08] by considering the matrix $G \cdot \Phi$, where G is a dense JL matrix (e.g., a Gaussian) with $O(k \log d)$ rows and Φ is a subsampled Fourier matrix that satisfies the RIP and has $k \log^c d$ rows.[2] Finally, the large k regime is of interest for applications to JL: when constructing JL matrices from RIP matrices via the aforementioned connection of Krahmer and Ward [KW11], constructions which restrict to small k result in JL matrices which restrict the size N of the set of vectors which is preserved, and this is undesirable in applications.

The best known construction of RIP matrices with fast multiplication (which work for large k) come from either subsampled Fourier matrices (or related constructions) or from partial circulant matrices. Candès and Tao showed in [CT06] that a matrix whose rows are $m = O(k \log^6 d)$ random rows from the Fourier matrix satisfies the $(O(1), k)$-RIP with positive probability. The analysis of Rudelson and Vershynin [RV08] and an optimization of it by Cheraghchi, Guruswami, and Velingker [CGV13] improved the number of rows required for the (ε, k)-RIP to $m = O(\varepsilon^{-2} k \log d \log^3 k)$. For circulant matrices, initial works required $m \gg k^{3/2}$ to obtain the (ε, k)-RIP [HBRN10, RRT12]; Krahmer, Mendelson and Rauhut [KMR13] recently improved the number of rows required to $m = O(\varepsilon^{-2} k \log^2 d \log^2 k)$.

The first work on JL matrices with fast multiplication was by Ailon and Chazelle [AC09], which had $m = O(\varepsilon^{-2} \log N)$ rows and embedding time $O(d \log d + m^3)$. In certain applications N can be exponentially large in a parameter of interest, e.g. when one wants to preserve the geometry of an entire subspace for numerical linear algebra [CW09, Sar06] or k-means clustering [BZMD11], or the set of all sparse vectors in compressed sensing [BDDW08]. Thus, while the number of rows in this construction is optimal, for some applications it is important to improve the dependence on m in the running time. Ailon and Liberty [AL09] improved the running time to $O(d \log m + m^{2+\gamma})$ for any desired $\gamma > 0$ (with the same number of rows). More recently the same authors gave a construction with $m = O(\varepsilon^{-4} \log N \log^4 d)$ supporting matrix-vector multiplies in time $O(d \log d)$ [AL11]. Krahmer and Ward [KW11] improved the target dimension to $m = O(\varepsilon^{-2} \log N \log^4 d)$.

As mentioned above, this last improvement of [KW11] is actually a more general result, which constructs a fast JL matrix from an RIP matrix which supports fast multiplication. The reported bound on m is the result of applying their theorem to subsampled Fourier matrices and using the result of [RV08] cited above. We will use the same machinery to obtain improved JL matrices, from our improved construction of RIP matrices.

Another way to obtain JL matrices which support fast matrix-vector multiplication is to construct sparse JL matrices [WDL+09, DKS10, KN10, BOR10, KN12]. These constructions allow for very fast multiplication Ax when the vector x is itself sparse. However, these constructions have an $\Omega(\varepsilon)$ fraction of nonzero entries, and it is known that any JL transform with $O(\varepsilon^{-2} \log N)$ rows requires an $\Omega(\varepsilon/\log(1/\varepsilon))$ fraction of nonzero entries [NN12b]. Thus, for constant ε and dense x,

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[2]Indeed, this matrix satisfies the RIP with optimal $O(k \log d)$ rows by [BDDW08]. Further, it supports $O(d \log d + k^2 \log^{c+1} d)$ matrix-vector multiplication time, which is nearly linear since $k \leq \sqrt{d}$. The only caveat is that the running time has a sub-optimal dependence on ε, at ε^{-4} rather than ε^{-2}; in the standard compressed sensing regime of constant ε this is irrelevant.

multiplication still requires time $\Theta(dm)$.

1.4   Our contributions

In this work we propose and analyze a new method for constructing RIP matrices that support fast matrix-vector multiplication. Loosely speaking, our method takes any "good" ensemble of RIP matrices, and produces an ensemble of RIP matrices with fewer rows by multiplying by a suitable hash matrix. We can apply our method to either subsampled Fourier matrices or partial circulant matrices to obtain our improved RIP matrices.

Our construction follows a natural intuition. For example, let A be the discrete Fourier matrix, and suppose that S is an $m \times d$ matrix with i.i.d. Rademacher (± 1) entries, appropriately renormalized. If $m = \Theta(\varepsilon^{-2} k \log(d/k))$, then SA satisfies the (ε, k)-RIP with high probability, because S has the RIP, and A is an isometry. Unfortunately, this construction has slow matrix-vector multiplication time. On the other hand, if S' is an extremely sparse random sign matrix, with only one non-zero per row, then $S'A$ is a subsampled Fourier matrix, supporting fast multiplication. Unfortunately, in order to show that $S'A$ satisfies the RIP with high probability, m must be increased by $\text{polylog}(k)$ factors. This raises the question: can we get the best of both worlds? How sparse must the sign matrix S be to ensure RIP with few rows, and can it be sparse enough to maintain fast matrix-vector multiplication? In some sense, this question, and our results, connects the two lines of research—structured matrices and sparse matrices—on fast JL matrices mentioned above. Our results imply we can improve the number of rows over previous work by using such a sparse sign matrix with only $\text{polylog}(d)$ non-zeroes per row.

Our Main Contribution: We give randomized constructions of (ε, k)-RIP matrices with

$$m = O(\varepsilon^{-2} k \log d \log^2(k \log d))$$

and which support matrix-vector multiplication in time $O(d \log d) + m \cdot \log^{O(1)} d$. When combined with [KW11], we obtain a JL matrix with a number of rows

$$m = O(\varepsilon^{-2} \log N \log d \log^2((\log N) \log d)) = O(\varepsilon^{-2} \log N \log^3 d)$$

and same embedding time. Thus for both RIP and JL, our constructions support fast matrix-vector multiply using the fewest rows known.

Our RIP and JL matrices have multiplication time at most $d \cdot \log^{O(1)} d$ for any value of k, and further maintain the $O(d \log d)$ running time of the sampled discrete Fourier matrix as long as $k < d/\text{polylog}\, d$. Our results are given in Figure 1.

1.5   Notation and Preliminaries

We set some notation. We use $[n]$ to denote the set $\{1, \ldots, n\}$. We use $\|\cdot\|_2$ denote the ℓ_2 norm of a vector, and $\|\cdot\|$, $\|\cdot\|_F$ to denote the operator and Frobenius norms of a matrix, respectively. For a set $\mathcal{S}$ and a norm $\|\cdot\|_X$, $d_{\|\cdot\|_X}(\mathcal{S})$ denotes the diameter of $\mathcal{S}$ with respect to $\|\cdot\|_X$. We say that $x \in \mathbb{C}^d$ is *k-sparse* if $\|x\|_0 \leq k$, where $\|x\|_0$ denotes the number of non-zero entries. The set of k-sparse vectors $x \in \mathbb{C}^d$ with $\|x\|_2 \leq 1$ is denoted T_k. In addition to $O(\cdot)$ notation, for two functions f, g, we use the shorthand $f \lesssim g$ (resp. $\gtrsim$) to indicate that $f \leq Cg$ (resp. $\geq$) for some

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Ensemble	# rows m needed for RIP	Matrix-vector multiplication time	Reference
Partial Fourier	$O(\varepsilon^{-2}k\log d\log^3 k)$	$O(d\log d)$	[RV08, CGV13]
Partial Circulant	$O(\varepsilon^{-2}k\log^2 d\log^2 k)$	$O(d\log m)$	[KMR13]
Hash × Partial Fourier	$O(\varepsilon^{-2}k\log d\log^2 k)$	$O(d\log d) + m\operatorname{polylog} d$	this work
Hash × Partial Circulant	$O(\varepsilon^{-2}k\log d\log^2 k)$	$O(d\log m) + m\operatorname{polylog} d$	this work

Figure 1: Table of results. The results above assume $k \geq \operatorname{polylog}(d)$; as discussed in Section 1.3, we are interested in the case of large k, so this restriction is innocuous.

absolute constant C. We use $f \approx g$ to mean $cf \leq g \leq Cf$ for some constants c, C. For clarity, we have made no attempt to optimize the values of the constants in our analyses.

Once we define the randomized construction of our RIP matrix Φ, we will control $|\|\Phi x\|_2^2 - \|x\|_2^2|$ uniformly over T_k, and thus will need some tools for controlling the supremum of a stochastic process on a compact set. For a metric space (T, d), the δ-covering number $\mathcal{N}(T, d, \delta)$ is the size of the smallest δ-net of T with respect to the metric d. One way to control a stochastic process on T is simply to union bound over a sufficiently fine net of T; a more powerful way to control stochastic processes, due to Talagrand, is through the γ_2 functional [Tal05].

Definition 2. *For a metric space (T, d), an* admissible sequence *of T is a sequence of nets $A_0, A_1, A_2, \ldots$ of T so that $|A_0| = 1$ and $|A_n| \leq 2^{2^n}$ for $n \geq 1$. Then*

$$\gamma_2(T, d) := \inf \sup_{t \in T} \sum_{n=1}^{\infty} 2^{n/2} d(A_n, t),$$

where the infimum is taken over all admissible sequences $\{A_n\}$.

Intuitively, $\gamma_2(T, d)$ measures how "clustered" T is with respect to d: if T is very clustered, then the union bound over nets above can be improved by a chaining argument. A similar idea is used in Dudley's integral inequality [LT91, Theorem 11.1], and indeed they are related (see [Tal05], Section 1.2) by

$$\gamma_2(T, d) \lesssim \int_0^{\operatorname{diam}_d(T)} \sqrt{\log \mathcal{N}(T, d, u)} \, du. \tag{3}$$

It is this latter form that will be useful to us.

1.6   Organization

In Section 2 we define our construction and give an overview of our techniques. We also state our most general theorem, Theorem 6, which gives a recipe for turning a "good" ensemble of RIP matrices into an ensemble of RIP matrices with fewer rows. In Section 3, we apply Theorem 6 to obtain the results listed in Figure 1. Finally, we prove Theorem 6 in Appendices A and B.

2 Technical Overview

Our construction is actually a general method for turning any "good" RIP matrix with a suboptimal number of rows into an RIP matrix with fewer rows. Many previous constructions of RIP matrices involve beginning with an appropriately structured matrix (a DFT or Hadamard matrix, or a circulant matrix, for example), and keeping only a subset of the rows. In this work we propose a simple twist on this idea: each row of our new matrix is a linear combination of a small number of rows from the original matrix, with random sign flips as the coefficients. Formally, we define our construction as follows.

Let $\mathcal{A}_M$ be a distribution on $M \times d$ matrices, defined for all M, and fix parameters m and B. Define the injective function $h : [m] \times [B] \to [mB]$ as $h(b, i) = B(b-1) + i$ to partition $[mB]$ into m buckets of size B, so $h(b, i)$ denotes the ith element in bucket b. We draw a matrix A from $\mathcal{A}_{mB}$, and then construct our $m \times d$ matrix $\Phi(A)$ by using h to hash the rows of A into m buckets of size B.

Definition 3 (Our construction). *Let $\mathcal{A}_M$ be as above, and fix parameters m and B. Define a new distribution on $m \times d$ matrices by constructing a matrix $\Phi \in \mathbb{C}^{m \times d}$ as follows.*

1. *Draw $A \sim \mathcal{A}_{mB}$, and let a_i denote the rows of A.*

2. *For each $(b, i) \in [m] \times [B]$, choose a sign $\sigma_{b,i} \in \{\pm 1\}$ independently, uniformly at random.*

3. *For $b = 1, \ldots, m$ let*

$$\varphi_b = \sum_{i \in [B]} \sigma_{b,i} a_{h(b,i)},$$

   and let $\Phi = \Phi(A, \sigma)$ be the matrix with rows φ_b.

We use A_b to denote the $B \times d$ matrix with rows $a_{h(b,i)}$ for $i \in [B]$.

Equivalently, Φ may be obtained by writing $\Phi = HA$, where $A \sim \mathcal{A}_{mB}$, and H is the $m \times mB$ random matrix with columns indexed by $(b, i) \in [m] \times [B]$, so that

$$H_{j,(b,i)} = \begin{cases} \sigma_{b,i} & b = j \\ 0 & b \neq j \end{cases}.$$

Note that there are two sources of randomness in the construction of Φ: there is the choice of $A \sim \mathcal{A}_{mB}$, and also the choice of the sign flips which determine the matrix H. Our RIP matrix will be the appropriately normalized matrix $\Phi/\sqrt{mB}$.

We consider two example distributions for $\mathcal{A}_M$. First, we consider a bounded orthogonal ensemble.

Definition 4 (Bounded orthogonal ensembles). *Let $\frac{1}{\sqrt{d}}U \in \mathbb{C}^{d \times d}$ be any unitary matrix with $|U_{ij}| \leq 1$ for all entries U_{ij} of U. Let u_i denote the ith row of U. A matrix $A \in \mathbb{C}^{M \times d}$ is drawn from the* bounded orthogonal ensemble *associated with U as follows. Select, independently and uniformly at random, a multi-set $\Omega = \{t_1, \ldots, t_M\}$ with $t_i \in [d]$. Then let $A \in \mathbb{C}^{M \times d}$ be the matrix with rows $u_{t_1}, \ldots, u_{t_M}$.*

Popular choices (and our choices) for U include the d-dimensional discrete Fourier transform (resulting in the *Fourier ensemble*), or the $d \times d$ Hadamard matrix, both of which support $O(d \log d)$ time matrix-vector multiplication.

The second family we consider is the partial circulant ensemble.

Definition 5 (Partial Circulant Ensemble). *For $z \in \mathbb{C}^d$, the* circulant matrix $H_z \in \mathbb{C}^{d \times d}$ *is given by* $H_z x = z * x$, *where $*$ denotes convolution. Fix $\Omega \subset [d]$ of size M arbitrarily. A matrix A is drawn from the* partial circulant ensemble *as follows. Choose $\varepsilon \in \{\pm 1\}^d$ uniformly at random, and let A be the rows of H_ε indexed by Ω.*

As long as the original matrix ensemble $\mathcal{A}$ supports fast matrix-vector multiplication, so does the resulting matrix Φ. Indeed, writing $\Phi x = H A x$ as above, we observe that there are mB nonzero entries in H, so computing the product $H A x$ takes time $O(mB)$, plus the time it takes to compute Ax. When A is drawn from the partial Fourier ensemble, Ax may be computed in time $O(d \log d)$ via the fast Fourier transform. We will choose $B = \text{polylog}(d)$, and so Φx may be computed in time $O(d \log d + m \, \text{polylog} \, d)$. When A is the partial circulant ensemble, Ax may be computed in time $d \log(mB)$ by breaking it up into $d/(mB)$ blocks, each of which is a $mB \times mB$ Toeplitz matrix supporting matrix-vector multiplication in time $O(mB \log(mB))$. Thus, in this case Φx may be computed in time $O(d \log(mB) + mB) = O(d \log m) + m \, \text{polylog} \, d$.

Having established the "multiplication time" column of Figure 1, we turn to the more difficult task of establishing the bounds on m, the number of rows. We note that $\Phi/\sqrt{mB}$ has the (ε, k)-RIP if and only if

$$\sup_{x \in T_k} \left| \frac{1}{mB} \|\Phi x\|_2^2 - \|x\|_2^2 \right| \leq \varepsilon,$$

and so our goal will be to establish bounds on $\sup_{x \in T_k} \left| \|\Phi x\|_2^2 / (mB) - \|x\|_2^2 \right|$. We will show that if $\mathcal{A}$ satisfies certain properties, then in expectation this quantity is small. Specifically we require the following two conditions. First, we require a random matrix from $\mathcal{A}$ to have the RIP with a reasonable, though perhaps suboptimal, number of rows:

$$\mathbb{E}_{A \sim \mathcal{A}} \sup_{x \in T_k} \left| \frac{1}{M} \|Ax\|_2^2 - \|x\|_2^2 \right| \lesssim \sqrt{\frac{L}{M}} \tag{$\star$}$$

for some quantity L, for suitably large $M > M_0$. Recall T_k is the set of unit-norm k-sparse vectors.

Second, the matrices A_b whose rows are the rows of A indexed by $h(b, i)$ for $i \in [B]$ should be well-behaved. Define ($\dagger$) to be the event that

$$\max_{b \in [m]} \sup_{x \in T_s} \|A_b x\|_2 \leq \ell(s) \tag{$\dagger$}$$

for some function $\ell(s)$ and all $s \leq 2k$. We require that ($\dagger$) happen with constant probability:

$$\mathbb{P}_{A \sim \mathcal{A}} [(\dagger) \text{ holds}] \geq 7/8. \tag{$\star\star$}$$

for some sufficiently small function ℓ.

As long as these two requirements on $\mathcal{A}$ are satisfied, and all matrices in the support of $\mathcal{A}$ have entries of bounded magnitude, the construction of Definition 3 yields a RIP matrix, with appropriate parameters. The following is our most general theorem.

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Theorem 6. *Fix $\varepsilon \in (0,1)$, and fix integers m and B. Let $\mathcal{A} = \mathcal{A}_{mB}$ be a distribution on $mB \times d$ matrices so that $\|a_i\|_\infty \leq 1$ almost surely for all rows a_i of $A \sim \mathcal{A}$. Suppose that $(\star)$ holds with*

$$L \leq mB\varepsilon^2,$$

and $M = mB > M_0$. Suppose further that $(\star\star)$ holds, with

$$\ell(s) \leq Q_1\sqrt{B} + Q_2\sqrt{s}$$

and that

$$B \geq \max\{Q_2^2 \log^2 m, Q_1^2 \log m \log k\}, \;\; and \;\; k \geq Q_1^2 \log^2 m.$$

Finally, suppose that $m > m_0$, for

$$m_0 = \frac{k \log d \log^2(Bk)}{\varepsilon^2}.$$

Let Φ be drawn from the distribution of Definition 3. Then

$$\sup_{x \in T_k} \left| \frac{1}{mB} \|\Phi x\|_2^2 - \|x\|_2^2 \right| \lesssim \varepsilon,$$

that is, $\frac{1}{\sqrt{mB}}\Phi$ satisfies the $(O(\varepsilon), k)$-RIP, with $3/4$ probability.

In Section 3, we will show how to use Theorem 6 to prove the results reported in Figure 1, but first we will outline the intuition of the proof of Theorem 6 (which is fleshed out in Appendix A).

By construction, the expectation of $\|\Phi x\|_2^2$ over the sign flips σ is simply $\|Ax\|_2^2$, and $(\star)$ guarantees that this expectation is under control, uniformly over $x \in T_k$. The trick is that A has mB rows, rather than m, and this provides slack to handle the fact that the guarantee $(\star)$ is not optimal.

The problem is then to argue that for all $x \in T_k$, $\|\Phi x\|_2^2$ is close to its expectation. The proof of Theorem 6 proceeds in two steps. First, we condition on A and control the deviation

$$\mathbb{E}_\sigma \sup_{x \in T_k} \left| \|\Phi x\|_2^2 - \mathbb{E}_\sigma \|\Phi x\|_2^2 \right|. \tag{4}$$

Second, we take the expectation with respect to $A \sim \mathcal{A}_{mB}$.

In Theorem 11 we carry out the first step and bound the deviation (4) by Talagrand's γ_2 functional $\gamma_2(T_k, \|\cdot\|_X)$, where $\|x\|_X := \max_b \|A_b x\|_2$ is a norm which measures the contribution to $\|\Phi x\|_2$ of the worst bucket b of the partition function h. Our strategy is to write $\|\Phi x\|_2^2$ as $\|X(x)\sigma\|_2^2$, for an appropriate matrix $X(x)$ that depends on A. Finally we use a result of Krahmer, Mendelson, and Rauhut [KMR13] to control the Rademacher chaos, obtaining an expression in terms of $\gamma_2(T_k, \|\cdot\|_X)$.

In the second step, we unfix A, and $\gamma_2(T_k, \|\cdot\|_X)$ becomes a random variable. In Theorem 12, we show that, as long as $(\star\star)$ holds, $\gamma_2(T_k, \|\cdot\|_X)$ is small with high probability over the choice of $A \sim \mathcal{A}_{mB}$. By (3), it is sufficient to bound the covering numbers $\mathcal{N}(T_k, \|\cdot\|_X, u)$. This is similar to [RV08], which must bound the same $\mathcal{N}(T_k, \|\cdot\|_X, u)$ but in a setting where $B = 1$. Both papers use Maurey's empirical method to relate the covering number to $\mathbb{E}[\max_b \|A_b g\|_2]$ for a Gaussian process g. But while [RV08] loses a $\sqrt{\log m}$ factor in a union bound over b, we only lose a constant factor as long as $B \geq \text{polylog}\, d$. This difference is what gives our $\log k$ improvement in m. It is also the most technical piece of our proof, and is presented in Appendix B.

Finally, we put all of the pieces together. As long as mB is large enough and the condition $(\star)$ holds, $\mathbb{E}_\sigma \|\Phi x\|_2 / \sqrt{mB}$ will be close to $\|x\|_2$ in expectation over A. At the same time as long as the condition $(\star\star)$ holds, the deviation (4) is small in expectation over $A \sim \mathcal{A}_{mB}$. Choosing B appropriately controls the restricted isometry constant of Φ.

3   Main Results

Due to space constraints, we defer the proof of Theorem 6 to Appendix A. In the meantime, let us show how we may use it to conclude the results in Figure 1. To do this, we must compute L and $\ell(s)$ from the conditions $(\star)$ and $(\star\star)$, when $\mathcal{A}$ is the Fourier ensemble (or any bounded orthogonal ensemble), and when $\mathcal{A}$ is the partial circulant ensemble.

3.1   Bounded orthogonal ensembles

Suppose $\mathcal{A}$ is a bounded orthogonal ensemble. The RIP analysis of $[\mathrm{RV08}, \mathrm{CGV13}]$ shows

$$\mathop{\mathbb{E}}_{A\sim\mathcal{A}} \sup_{x\in T_k} \left| \frac{1}{M} \|Ax\|_2^2 - \|x\|_2^2 \right| \lesssim \sqrt{\frac{k\log^3 k \log d}{M}},$$

provided that $M \gtrsim k\log^3 k\log d$, so we may take $L \lesssim k\log^3 k\log d$. Further, the analysis of $[\mathrm{RV08}]$ (see Lemma 17 in the Appendix) implies that

$$\mathbb{P}_{A\sim\mathcal{A}} \left[\exists s\in[2k] : \max_{b\in[m]} \sup_{x\in T_s} \|A_b x\|_2 \geq \ell(s) \right] \leq 2km \max_{s\in[2k]} \mathbb{P}_{A\sim\mathcal{A}} \left[\sup_{x\in T_s} \|A_1 x\|_2 \geq \ell(s) \right] \leq 1/8$$

when

$$\ell(s) \asymp (\log m)^{1/4}\sqrt{B} + (\log m)^{1/4}\sqrt{s\log^2 k\log d\log B}.$$

Thus, we may take $Q_1 \lesssim \log^{1/4} m$ and

$$Q_2 \lesssim (\log m)^{1/4}\log k\sqrt{\log d\log B} \lesssim \log^{2.5} d.$$

With these parameter settings, Theorem 6 implies the following theorem.

Theorem 7. *Let $\varepsilon \in (0,1)$. Let $\mathcal{A}$ be a bounded orthogonal ensemble (for example, the Fourier ensemble), and suppose that Φ is as in Definition 3. Further suppose $B \geq \log^7 d$ and $k \geq \log^{2.5} m$. Then for some value*

$$m = O\left(\frac{k\log d\log^2(k\log d)}{\varepsilon^2} \right),$$

we have that

$$\sup_{x\in T_k} \left| \|\Phi x\|_2^2 - \|x\|_2^2 \right| \leq \varepsilon$$

with $3/4$ probability.

3.2   Circulant Matrices

Suppose that $\mathcal{A}$ is the partial circulant ensemble. By the analysis in $[\mathrm{KMR13}]$,

$$\mathop{\mathbb{E}}_{A\sim\mathcal{A}} \sup_{x\in T_k} \left| \frac{1}{M} \|Ax\|_2^2 - \|x\|_2^2 \right| \lesssim \sqrt{\frac{k\log^2 k\log^2 d}{M}},$$

for $M \gtrsim k\log^2 k\log^2 d$. Concentration also follows from the analysis in $[\mathrm{KMR13}]$, as a corollary of Theorem 10 (see $[\mathrm{KMR13}, \text{Theorem 4.1}]$).

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Lemma 8. *(Implicit in [KMR13])*

$$\mathbb{P}_{A\sim\mathcal{A}}\left[\exists s \in [2k] : \max_{b\in[m]} \sup_{x\in T_s} \|A_b x\|_2 \geq \ell(s)\right] \leq \frac{1}{8}$$

when

$$\ell(s) \eqsim \sqrt{B} + \sqrt{s}\log k \log d.$$

Thus, we may take $Q_1 \lesssim 1$ and $Q_2 \lesssim \log k \log d$. Then Theorem 6 implies the following theorem.

Theorem 9. *Let $\varepsilon \in (0,1)$. Let $\mathcal{A}$ be the partial circulant ensemble, and suppose Φ is constructed as in Definition 3. Further suppose $B \geq \log^2 m \log^2 k \log^2 d$ and $k \geq \log^2 m$. Then, for some value*

$$m = O\left(\frac{k\log d \log^2(k\log d)}{\varepsilon^2}\right),$$

we have that, as long as $m < d/B$,

$$\sup_{x\in T_k} \left|\|\Phi x\|_2^2 - \|x\|_2^2\right| \leq \varepsilon$$

with $3/4$ probability.

We remark that the condition $m \leq d/B$ does not actually affect the results reported in Figure 1. Indeed, if $mB > d$, we may artificially increase d to $d' = mB$ by embedding T_k in $\mathbb{C}^{d'}$ by zero-padding. Applying Theorem 9 with $d = d'$ implies an RIP matrix with $O(\varepsilon^{-2}k\log d' \log^2(k\log d))$ rows and embedding time $O(d'\log d') + m\operatorname{polylog} d'$. Because $B = \operatorname{polylog} d$, we have $d' = d\operatorname{polylog} d$, and there is no asymptotic loss in m by extending d to d'. Further, in this parameter regime, $d'\log d' = mB\log d' = m\operatorname{polylog} d$.

4 Conclusion

In compressed sensing, it is of interest to obtain RIP matrices Φ supporting fast (i.e. nearly linear time) matrix-vector multiplication, with as few rows as possible, since doing so speeds up many iterative recovery algorithms, which are based on repeatedly multiplying by Φ or Φ^*. Similarly, because of applications in computational geometry, numerical linear algebra, and others, one wants to obtain JL matrices with few rows and fast matrix-vector multiplication. In this work, we have shown how to construct RIP matrices supporting fast matrix-vector multiplication, with fewer rows than was previously known. Combined with the work of [KW11], this also implies improved constructions of fast JL matrices.

Our work leaves the obvious open question of removing the two $O(\log(k\log d))$ factors separating our constructions from the lower bounds. It seems that both logarithmic factors come from the estimation (3). It would be interesting to see if they could be removed by more sophisticated chaining techniques such as majorizing measures.

Acknowledgments

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A Proof of Theorem 6

We will use the following theorem from [KMR13].

Theorem 10. *[KMR13, Theorem 1.4] Let $\mathcal{S} \subset \mathbb{C}^{m \times M}$ be a symmetric set of matrices, $\mathcal{S} = -\mathcal{S}$. Let $\sigma \in \{\pm 1\}^M$ uniformly at random. Then*

$$\mathbb{E} \sup_{X \in \mathcal{S}} \left| \|X\sigma\|_2^2 - \mathbb{E} \|X\sigma\|_2^2 \right| \lesssim \left(d_F(\mathcal{S}) \gamma_2(\mathcal{S}, \|\cdot\|) + \gamma_2^2(\mathcal{S}, \|\cdot\|) \right) =: E'.$$

Furthermore, for all $t > 0$,

$$\mathbb{P} \left[\sup_{X \in \mathcal{S}} \left| \|X\sigma\|_2^2 - \mathbb{E} \|X\sigma\|_2^2 \right| > C_1 E' + t \right] \leq 2 \exp \left(-C_2 \min \left\{ \frac{t^2}{V^2}, \frac{t}{U} \right\} \right),$$

where C_1 and C_2 are constants,

$$V = d_{2 \to 2}(\mathcal{S})(\gamma_2(\mathcal{S}, \|\cdot\|) + d_F(\mathcal{S})),$$

and

$$U = d_{2 \to 2}^2(\mathcal{S}).$$

The first step in proving Theorem 6 is to bound the restricted isometry constant of Φ in terms of the γ_2 functional, removing the dependence on σ.

Theorem 11. *Suppose $\mathcal{A} = \mathcal{A}_M$ is a distribution on $M \times d$ matrices so that $(\star)$ holds, and let Φ be as in Definition 3. Then*

$$\mathbb{E} \sup_{x \in T_k} \left| \frac{1}{mB} \|\Phi x\|_2^2 - \|x\|_2^2 \right|$$

$$\lesssim \frac{1}{mB} \left(\mathbb{E}_A \sup_{x \in T_k} \|Ax\|_2 \, \gamma_2(T_k, \|\cdot\|_X) + \mathbb{E}_A \gamma_2^2(T_k, \|\cdot\|_X) \right) + \sqrt{\frac{L}{mB}}.$$

where

$$\|x\|_X := \max_{b \in [m]} \|A_b x\|_2 .$$

Proof. Let $H(b) = \{ h(b,i) : i \in [B] \}$ be the multiset of indices of the rows of A in bucket b, and as above let A_b denote the $B \times d$ matrix whose rows are indexed by $H(b)$. Let $\sigma_b = \sum_{i=1}^B \sigma_{b,i} e_i$ denote the vector of sign flips associated with bucket b. Notice that, by construction, conditioning on $A \sim \mathcal{A}$, we have

$$\mathbb{E}_{\sigma} \|\Phi x\|_2^2 = \|Ax\|_2^2, \tag{5}$$

and so

$$\mathbb{E} \sup_{x \in T_k} \left| \frac{1}{mB} \|\Phi x\|_2^2 - \|x\|^2 \right|$$

$$\leq \mathbb{E}_A \left[\frac{1}{mB} \mathbb{E}_{\sigma} \sup_{x \in T_k} \left| \|\Phi x\|_2^2 - \mathbb{E}_{\sigma} \|\Phi x\|_2^2 \right| + \sup_{x \in T_k} \left| \frac{1}{mB} \mathbb{E}_{\sigma} \|\Phi x\|_2^2 - \|x\|_2^2 \right| \right]$$

$$= \frac{1}{mB} \mathbb{E}_A \mathbb{E}_{\sigma} \sup_{x \in T_k} \left| \|\Phi x\|_2^2 - \|Ax\|_2^2 \right| + \mathbb{E}_A \sup_{x \in T_k} \left| \frac{1}{mB} \|Ax\|_2^2 - \|x\|_2^2 \right|$$

$$\lesssim \frac{1}{mB} \mathbb{E}_A \mathbb{E}_{\sigma} \sup_{x \in T_k} \left| \|\Phi x\|_2^2 - \|Ax\|_2^2 \right| + \sqrt{\frac{L}{mB}}, \tag{6}$$

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where we have used $(\star)$ in the last line and (5) in the penultimate line.

Condition on the choice of A until further notice, and consider the first term. We may write

$$E := \mathbb{E} \sup_{\sigma} \sup_{x \in T_k} \left| \|\Phi x\|_2^2 - \mathbb{E} \|\Phi x\|_2^2 \right| = \mathbb{E} \sup_{\sigma} \sup_{x \in T_k} \left| \sum_b |\langle \sigma_b, A_b x \rangle|^2 - \mathbb{E} \sum_b |\langle \sigma_b, A_b x \rangle|^2 \right|.$$

Now, we apply Theorem 10 to $\mathcal{S} = \{X(x) \in \mathbb{C}^{m \times mB} \mid x \in T_k\}$, where $X(x)$ is defined as follows:

$$X(x) = \begin{bmatrix} -(A_1 x)^* - & 0 & 0 & \cdots & 0 \\ 0 & -(A_2 x)^* - & 0 & \cdots & 0 \\ 0 & 0 & -(A_3 x)^* - & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & -(A_m x)^* - \end{bmatrix}.$$

Let σ be the vector in $\{-1, 1\}^M$ defined as $(\sigma_1^*, \ldots, \sigma_m^*)^*$. By construction, $\|X(x)\sigma\|_2^2 = \sum_b |\langle \sigma_b, A_b x \rangle|^2$, and so by Theorem 10, it suffices to control $d_F(\mathcal{S})$ and $\gamma_2(\mathcal{S}, \|\cdot\|)$. The Frobenius norm of $X(x)$ is

$$\|X(x)\|_F^2 = \sum_{b \in [m]} \|A_b x\|_2^2 = \|Ax\|_2^2.$$

For the γ_2 term, notice that for any $x, y \in T_k$,

$$\|X(x) - X(y)\| = \max_{b \in [m]} \|A_b(x - y)\|_2 = \|x - y\|_X.$$

Thus, $\gamma_2(\mathcal{S}, \|\cdot\|) = \gamma_2(T_k, \|\cdot\|_X)$. Then Theorem 10 implies that

$$E \lesssim \max_{x \in T_k} \|Ax\|_2 \, \gamma_2(T_k, \|\cdot\|_X) + \gamma_2^2(T_k, \|\cdot\|_X).$$

Plugging this into (6), we conclude

$$\mathbb{E} \sup_{x \in T_k} \left| \frac{1}{mB} \|\Phi x\|_2^2 - \|x\|_2^2 \right| \lesssim \frac{1}{mB} \left(\mathbb{E}_A \sup_{x \in T_k} \|Ax\|_2 \, \gamma_2(T_k, \|\cdot\|_X) + \mathbb{E}_A \gamma_2^2(T_k, \|\cdot\|_X) \right) + \sqrt{\frac{L}{mB}}. \quad (7)$$

$\blacksquare$

Theorem 11 leaves us with the task of controlling $\gamma_2(T_k, \|\cdot\|_X)$, which we do in the following theorem.

Theorem 12. *Suppose that A is a matrix such that (†) holds, with*

$$\ell(s) \leq Q_1 \sqrt{B} + Q_2 \sqrt{s}.$$

Suppose further that $\|a_i\|_\infty \leq 1$ for all i, and suppose that

$$B \geq \max\{Q_2^2 \log^2 m, Q_1^2 \log m \log k\}, \text{ and } k \geq Q_1^2 \log^2 m.$$

Then

$$\gamma_2(T_k, \|\cdot\|_X) \lesssim \sqrt{kB \log d} \cdot \log(Bk).$$

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Proof. By (3),

$$\gamma_2(T_k, \|\cdot\|_X) \lesssim \int_{u=0}^{Q} \sqrt{\log \mathcal{N}(T_k, \|\cdot\|_X, u)}\, du, \tag{8}$$

where $Q = \sup_{x \in T_k} \|x\|_X$. Notice that we can bound

$$Q^2 = \sup_{x \in T_k} \max_b \|A_b x\|_2^2 = \sup_{x \in T_k} \max_b \sum_{i \in [B]} \left|\langle a_{h(b,i)}, x \rangle\right|^2 \le B \sup_{x \in T_k} \|x\|_1^2 \le Bk$$

using the fact that each entry of $a_{h(b,i)}$ has magnitude at most 1. We follow the approach of [RV08] and estimate the covering number using two nets, one for small u and one for large u.

For small u, we use a standard ℓ_2 net of B_2: we have

$$\|x\|_X \le Q \|x\|_2$$

so $\mathcal{N}(T_k, \|\cdot\|_X, u) \le \mathcal{N}(T_k, \|\cdot\|_2, u/Q)$. Observing that T_k is the union of $\binom{d}{k} = \left(\frac{d}{k}\right)^{O(k)}$ copies of B_2^k (the unit ℓ_2-ball of dimension k), we may cover T_k by covering cover each copy of B_2^k with a net of width u/Q. By a standard volume estimate [Pis89, Eqn. (5.7)], the size of each such net is $(1 + 2Q/u)^k$, and so

$$\sqrt{\log \mathcal{N}(T_k, \|\cdot\|_X, u)} \lesssim \sqrt{k \log(d/k) + k \log(1 + 2Q/u)} \lesssim \sqrt{k \log(dQ/u)}.$$

For large u the situation is not as simple. We show in Lemma 13 that, as long as (†) holds,

$$\sqrt{\log \mathcal{N}(T_k, \|\cdot\|_X, u)} \lesssim \frac{\sqrt{kB \log d}}{u}.$$

We plug these bounds into (8) and integrate, using the first net for $u \in (0,1)$ and the second for $u > 1$. We find

$$\begin{aligned}
\int_{u=0}^{Q} \sqrt{\log \mathcal{N}(T_k, \max_b \|F_b \cdot \|, u)}\, du &\lesssim \int_{u=0}^{1} \sqrt{k \log(dQ/u)}\, du + \int_{u=1}^{Q} \frac{\sqrt{kB \log d}}{u}\, du \\
&\lesssim \sqrt{k \log(dQ)} + \sqrt{kB \log d} \log Q \\
&\lesssim \sqrt{kB \log d} \log Q \\
&\le \sqrt{kB \log d} \log(Bk)
\end{aligned}$$

as claimed. ∎

It remains to put Theorem 11 and Theorem 12 together to prove Theorem 6.

Proof. (Proof of Theorem 6.) We need to show that

$$\Delta := \sup_{x \in T_k} \left| \frac{1}{mB} \|\Phi x\|_2^2 - \|x\|_2^2 \right| \lesssim \varepsilon$$

with 3/4 probability. We have by (⋆⋆) that (†) holds with 7/8 probability over $\mathcal{A}$, and we will show that $\Delta \lesssim \varepsilon$ with 7/8 probability when A is drawn from the distribution $\mathcal{A}' = (\mathcal{A} \mid (\dagger) \text{ holds})$. Together, this will imply the conclusion of Theorem 6.

Note that as long as (⋆) holds for $\mathcal{A}$, (⋆) holds for $\mathcal{A}'$ as well. Indeed,

$$\mathop{\mathbb{E}}_{A\sim\mathcal{A}'}\sup_{x\in T_k}\left|\frac{1}{mB}\|Ax\|_2^2 - \|x\|_2^2\right| \leq \left(\frac{8}{7}\right)\mathop{\mathbb{E}}_{A\sim\mathcal{A}}\sup_{x\in T_k}\left|\frac{1}{mB}\|Ax\|_2^2 - \|x\|_2^2\right| \lesssim \varepsilon,$$

so (⋆) holds for $\mathcal{A}'$. For the rest of the proof, we consider $A\sim\mathcal{A}'$, so we have

$$\frac{1}{\sqrt{mB}}\mathop{\mathbb{E}}_{A}\sup_{x\in T_k}\|Ax\|_2 \leq \sqrt{1+O(\varepsilon)} \lesssim 1.$$

Under the parameters of Theorem 6 and because (†) holds for all $A\sim\mathcal{A}'$, Theorem (12) implies

$$\gamma_2(T_k, \|\cdot\|_X) \leq \sqrt{kB\log d}\cdot\log(Bk).$$

Then

$$\frac{1}{mB}\mathop{\mathbb{E}}_{A}\left[\sup_{x\in T_k}\|Ax\|_2\cdot\gamma_2(T_k,\|\cdot\|_X)\right] \lesssim \frac{\sqrt{k\log(d)}\cdot\log(Bk)}{\sqrt{m}} \leq \varepsilon.$$

Similarly,

$$\frac{1}{mB}\mathop{\mathbb{E}}_{A}\gamma_2^2(T_k,\|\cdot\|_X) \lesssim \frac{k\log(d)\log^2(Bk)}{m} \leq \varepsilon^2.$$

By Theorem 11, and using the above bounds,

$$\begin{aligned}
\mathop{\mathbb{E}}_{A}[\Delta] &\lesssim \frac{1}{mB}\left(\mathop{\mathbb{E}}_{A}\sup_{x\in T_k}\|Ax\|_2\,\gamma_2(T_k,\|\cdot\|_X) + \mathop{\mathbb{E}}_{A}\gamma_2^2(T_k,\|\cdot\|_X)\right) + \sqrt{\frac{L}{mB}} \\
&\lesssim \varepsilon + \varepsilon^2 + \varepsilon \\
&\lesssim \varepsilon.
\end{aligned}$$

Therefore by Markov's inequality, we have $\Delta \lesssim \varepsilon$ with arbitrarily high constant probability over $A\sim\mathcal{A}'$. In particular, we may adjust the constants so that $\Delta \lesssim \varepsilon$ with probability at least $7/8$ over $A\sim\mathcal{A}'$, which was our goal. ∎

B Covering number bound

In this section, we prove the covering number lemma needed for the proof of Theorem 12. Recall the definition $\|x\|_X = \max_{b\in[m]}\|A_b x\|_2$, and that T_k is the set of k-sparse vectors in $\mathbb{C}^d$ with ℓ_2 norm at most 1.

Lemma 13. *Suppose that the conditions of Theorem 12 hold. Then*

$$\mathcal{N}(T_k/\sqrt{k}, \|\cdot\|_X, u) \leq (2d+1)^{O(B/u^2)}.$$

We will prove this under the assumption that $x\in T_k$ is real, using only that (†) holds for $s \leq k$ and that A has bounded entries. The extension to complex vectors follows from a simple transformation: by Proposition 16 in the Appendix, we have $\mathcal{N}(T_k/\sqrt{k}, \|\cdot\|_X, u)$ over the complex

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numbers is less than $\mathcal{N}(T_{2k}/\sqrt{2k}, \|\cdot\|_{\tilde{X}}, u)$ over the reals, where $\|\cdot\|_{\tilde{X}}$ denotes a version of the $\|\cdot\|_X$ for a real matrix $\tilde{A}$ of bounded entries that satisfies (†) for $s \leq 2k$. Adjusting the constants by a factor of 2 gives the final result.

As in [RV08], we use Maurey's empirical method (see [Car85]). Consider $x \in T_k/\sqrt{k}$, and choose a parameter s. For $i \in [s]$, define a random variable Z_i, so that $Z_i = e_j \text{sign}(x_j)$ with probability $|x_j|$ for all $j \in [d]$, and 0 with probability $1 - \|x\|_1$. Notice that by the assumption that x is real, $\text{sign}(x_j)$ is well defined. Further, because $T_k/\sqrt{k} \subset B_1$, this is a valid probability distribution. We want to show for every x that

$$\mathbb{E} \left\| x - \frac{1}{s} \sum Z_i \right\|_X \lesssim \sqrt{\frac{B}{s}}. \tag{9}$$

This would imply that the right hand side is at most u for $s \lesssim B/u^2$. If this holds, then the set of all possible $\frac{1}{s} \sum Z_i$ forms a u-covering. As there are only $2d+1$ choices for each Z_i, there are only $(2d+1)^s$ different vectors of the form $\frac{1}{s} \sum_{i=1}^s Z_i$. These form a u-covering, so Eq. (9) will imply

$$\mathcal{N}(T_k, \|\cdot\|_X, u) \leq (2d+1)^{O(B/u^2)}.$$

We now show Eq. (9). Draw a Gaussian vector $g \sim N(0, I_s)$, and define

$$\mathcal{G}(x) = \mathop{\mathbb{E}}_{g,Z} \left\| \sum Z_i g_i \right\|_X$$

By a standard symmetrization argument followed by a comparison principle (Lemma 6.3 and Eq. (4.8) in [LT91] respectively, or the proof of Lemma 3.9 in [RV08]),

$$\mathbb{E} \left\| x - \frac{1}{s} \sum Z_i \right\|_X \lesssim \frac{1}{s} \mathcal{G}(x),$$

so it suffices to bound $\mathcal{G}(x)$ by $O(\sqrt{Bs})$.

Let $L = \{i : |x_i| > \frac{\log m}{k}\}$ be the set of coordinates of x with "large" value in magnitude. Then

$$\mathcal{G}(x) \leq \mathcal{G}(x_L) + \mathcal{G}(x_{\overline{L}})$$

by partitioning the Z_i into those from L and those from $\overline{L}$ and applying the triangle inequality. Notice that x_L is "spiky" and $x_{\overline{L}}$ is "flat:" more precisely, we have

$$\|x_L\|_1 \leq \frac{1}{\log m} \qquad \text{and} \qquad \|x_{\overline{L}}\|_\infty \leq \frac{\log m}{k}, \tag{10}$$

using Cauchy-Schwarz to bound the ℓ_1 norm. To bound $\mathcal{G}(x_L)$ and $\mathcal{G}(x_{\overline{L}})$ we use the following lemma.

Lemma 14. *Suppose that* (†) *holds. Then the following inequalities hold for all x:*

$$\mathcal{G}(x) \lesssim \sqrt{Bs \|x\|_1 \log m} \tag{11}$$

$$\mathcal{G}(x) \lesssim \sqrt{Bs} + \sqrt{\log m} \left(Q_1 \sqrt{B} + Q_2 \sqrt{\min(k,s)} \right) \sqrt{s\|x\|_\infty + \log k} \tag{12}$$

Proof. Let $\mathbf{Z} \in \{-1, 0, 1\}^{d \times s}$ have columns Z_i, and $Z = \sum_i Z_i$. Then

$$\mathcal{G}(x) = \mathbb{E} \max_{b \in [m]} \|A_b \mathbf{Z} g\|_2$$

Consider $\|A_b \mathbf{Z} g\|_2$ for a single $b \in [m]$. This is a C-Lipschitz function of a Gaussian for $C = \|A_b \mathbf{Z}\|_{2 \to 2}$. Therefore [LT91, Eq. (1.4)],

$$\mathbb{P}_g[\|A_b \mathbf{Z} g\|_2 > \mathbb{E}_g \|A_b \mathbf{Z} g\|_2 + t \|A_b \mathbf{Z}\|_{2 \to 2}] < e^{-\Omega(t^2)}.$$

Hence by a standard computation for subgaussian random variables [LT91, Eq. (3.13)]),

$$\mathcal{G}(x) \lesssim \mathbb{E} \max_{Z} \max_{b \in [m]} \mathbb{E}_g \|A_b \mathbf{Z} g\|_2 + \sqrt{\log m} \|A_b \mathbf{Z}\|_{2 \to 2}.$$

Now,

$$\mathbb{E}_g \|A_b \mathbf{Z} g\|_2 \leq \sqrt{\mathbb{E}_g \|A_b \mathbf{Z} g\|_2^2} = \|A_b \mathbf{Z}\|_F = \sqrt{B \|Z\|_1} \tag{13}$$

and

$$\mathbb{E}_Z \sqrt{B \|Z\|_1} \leq \sqrt{B \mathbb{E}_Z \|Z\|_1} = \sqrt{Bs \|x\|_1} \leq \sqrt{Bs}. \tag{14}$$

Thus

$$\mathcal{G}(x) \leq \sqrt{Bs \|x\|_1} + O\left(\mathbb{E} \max_{Z} \max_{b \in [m]} \sqrt{\log m} \|A_b \mathbf{Z}\|_{2 \to 2}\right). \tag{15}$$

Thus it suffices to bound $\|A_b \mathbf{Z}\|_{2 \to 2}$ in terms of $\|x\|_1$ and $\|x\|_\infty$. First, we have

$$\|A_b \mathbf{Z}\|_{2 \to 2} \leq \|A_b \mathbf{Z}\|_F$$

and so by Equations (13) and (14) we have

$$\mathcal{G}(x) \leq \sqrt{Bs \|x\|_1 \log m},$$

as desired for Equation (11).

Second, we turn to Equation (12). For a matrix $A \in m \times d$ and a set $S \subset [d]$, let $A|_S$ denote the $m \times d$ matrix with all the columns not indexed by S set to zero. Then, we have

$$\|A_b \mathbf{Z}\|_{2 \to 2} \leq \left\| A_b|_{\mathrm{supp}(Z)} \right\|_{2 \to 2} \|\mathbf{Z}\|_{2 \to 2} \leq \max_{|S| \leq \min(k,s)} \|A_b|_S\|_{2 \to 2} \|Z\|_\infty^{1/2}. \tag{16}$$

In the final step, we used the fact that for any matrix A, $\|A\|_{2 \to 2} \leq \sqrt{\|A\|_{1 \to 1} \|A\|_{\infty \to \infty}}$ (see Lemma 15 in the Appendix). By the assumption (†) and the choice of ℓ,

$$\max_{b \in [m]} \sup_{x \in T_{\min(k,s)}} \|A_b x\|_2 \leq Q_1 \sqrt{B} + Q_2 \sqrt{\min(k,s)},$$

so

$$\max_{b \in [m]} \|A_b \mathbf{Z}\|_{2 \to 2} \leq \|Z\|_\infty^{1/2} \left(Q_1 \sqrt{B} + Q_2 \sqrt{\min(k,s)}\right).$$

Finally, we bound $\mathbb{E}_Z \|Z\|_\infty$. By a Chernoff bound, for any $j \in \text{supp}(x)$, we have

$$\mathbb{P}\left[\left|\left(\sum Z_i\right)_j\right| > s\,|x_j| + t\right] \leq e^{-\Omega(t)}.$$

Integrating, we have

$$\mathbb{E}\,\|Z\|_\infty \lesssim s\,\|x\|_\infty + \log k.$$

Thus

$$\mathbb{E}\,\max_{\substack{Z \\ b\in[m]}} \|A_b \mathbf{Z}\|_{2\to 2} \lesssim (s\,\|x\|_\infty + \log k)^{1/2}\left(Q_1\sqrt{B} + Q_2\sqrt{\min(k,s)}\right).$$

Combining this with Equation (15) gives (12). ∎

We return to the proof of Lemma 13. Recall that the goal was to bound

$$\mathcal{G}(x_L) + \mathcal{G}(x_{\overline{L}}) \lesssim \sqrt{Bs}.$$

By (10) and (11), $\mathcal{G}(x_L) \lesssim \sqrt{Bs}$. Furthermore,

$$\mathcal{G}(x_{\overline{L}}) \lesssim \sqrt{Bs} + \sqrt{\log m}\left(Q_1\sqrt{B} + Q_2\sqrt{\min(k,s)}\right)\sqrt{s\|x_{\overline{L}}\|_\infty + \log k}$$

$$\leq \sqrt{Bs} + \sqrt{\log m}\left(Q_1\sqrt{B} + Q_2\sqrt{\min(k,s)}\right)\left(\sqrt{\frac{s\log m}{k}} + \sqrt{\log k}\right)$$

$$= \sqrt{Bs}\left(1 + Q_1\left(\frac{\log m}{\sqrt{k}} + \sqrt{\frac{\log m \log k}{s}}\right) + Q_2\left(\frac{\sqrt{\min(k,s)}\log m}{\sqrt{kB}} + \sqrt{\frac{\log m \log k}{B}\frac{\min(k,s)}{s}}\right)\right).$$

Since we have assumed $B \gtrsim Q_2^2 \log^2 m$, the Q_2 term is bounded by a constant. Further, $k \gtrsim Q_1^2 \log^2 m$, and $s \geq B \gtrsim Q_1^2 \log m \log k$, and so the Q_1 term is also constant. Thus, we conclude

$$\mathcal{G}(x) \leq \mathcal{G}(x_L) + \mathcal{G}(x_{\overline{L}}) \lesssim \sqrt{Bs},$$

which was our goal.

C Minor Technical Lemmata

Lemma 15. *For any complex matrix A, $\|A\|_{2\to 2}^2 \leq \|A\|_{1\to 1} \cdot \|A\|_{\infty\to\infty}$.*

Proof. First we consider the case of Hermitian A, then arbitrary A. For Hermitian A, let λ be the largest (in magnitude) eigenvalue of A and v be the associated eigenvector. We have

$$\|A\|_{1\to 1} \geq \frac{\|Av\|_1}{\|v\|_1} = \frac{\|\lambda v\|_1}{\|v\|_1} = |\lambda| = \|A\|_{2\to 2}.$$

For arbitrary A,

$$\|A\|_{2\to 2}^2 = \|A^*A\|_{2\to 2} \leq \|A^*A\|_{1\to 1} \leq \|A^*\|_{1\to 1}\cdot\|A\|_{1\to 1} = \|A\|_{\infty\to\infty}\cdot\|A\|_{1\to 1}$$

as desired. In the last inequality we used the fact that $\|\cdot\|_{\infty\to\infty}$ is equal to the largest ℓ_1 norm of any row, and $\|\cdot\|_{1\to 1}$ is equal to the largest ℓ_1 norm of any column. ∎

Proposition 16. *Let $f : \mathbb{C}^d \to \mathbb{R}^{2d}$ act entrywise by replacing $a + b\mathbf{i}$ with (a, b). For any integer r, define $F : \mathbb{C}^{r \times d} \to \mathbb{R}^{2r \times 2d}$ to act entrywise by replacing an entry $a + b\mathbf{i}$ by the 2×2 matrix*

$$
\begin{bmatrix} a & -b \\ b & a \end{bmatrix}.
$$

Recall that $T_k \subset \mathbb{C}^d$ is the set of unit norm k-sparse complex vectors, and let $S_s \subset \mathbb{R}^s$ be the set of unit norm s-sparse real vectors. Recall that $\|\cdot\|_X$ is a norm on $\mathbb{C}^d$ given by $\|x\|_X = \max_b \|A_b x\|_2$, and let $\|\cdot\|_{\tilde{X}}$ be a norm on $\mathbb{R}^{2d}$ given by $\|x\|_{\tilde{X}} = \max_b \|F(A_b)x\|_2$. Then

1. *If (†) holds, then $\max_b \sup_{x \in S_s} \|F(A_b)x\|_2 \leq \ell(s)$ for $s \leq 2k$.*

2. *With $\|\cdot\|_{\tilde{X}}$ as above, we have*

$$
\mathcal{N}(T_k, \|\cdot\|_X, u) \leq \mathcal{N}(S_{2k}, \|\cdot\|_{\tilde{X}}, u).
$$

Proof. By construction, we have $f(Ax) = F(A)f(x)$, and also $\|f(x)\|_2 = \|x\|_2$. Further, $f(T_k) \subset S_{2k}$ and $f^{-1}(S_s) \subset T_s$. Thus, item 1 follows because

$$
\max_b \sup_{x \in S_s} \|F(A_b)x\|_2 \leq \max_b \sup_{y \in T_s} \|F(A_b)f(y)\|_2 = \max_b \sup_{y \in T_s} \|A_b y\|_2 \leq l(s)
$$

Similarly, item 2 follows because for any $x, y \in T_k$,

$$
\begin{aligned}
\|x - y\|_X &= \max_{b \in [m]} \|A_b(x - y)\|_2 \\
&= \max_{b \in [m]} \|F(A_b)f(x - y)\|_2 \\
&= \max_{b \in [m]} \|F(A_b)(f(x) - f(y))\|_2 \\
&= \|f(x) - f(y)\|_{\tilde{X}}.
\end{aligned}
$$

Hence

$$
N(T_k, \|\cdot\|_X, u) = N(f(T_k), \|\cdot\|_{\tilde{X}}, u) \leq N(S_{2k}, \|\cdot\|_{\tilde{X}}, u).
$$

∎

Lemma 17. *Let $\mathcal{F}$ denote the $d \times d$ Fourier matrix. Let Ω with $|\Omega| = B$ be a random multiset with elements in $[d]$, and for $S \subseteq [d]$ let $\mathcal{F}_{\Omega \times S}$ denote the $|\Omega| \times |S|$ matrix whose rows are the rows of $\mathcal{F}$ in Ω, restricted to the columns in S. Then for any $t > 1$,*

$$
\max_{|S|=k} \|\mathcal{F}_{\Omega \times S}\| \lesssim \sqrt{t(B + k\beta)}
$$

with probability at least

$$
1 - O\left(\exp\left(-\min\left\{t^2, t\beta\right\}\right)\right),
$$

where

$$
\beta = \log^2 k \log d \log B.
$$

Proof. (Implicit in [RV08]). Let $X = \sup_{|S|=k} \left\| I_k - \frac{1}{B} \mathcal{F}^*_{\Omega \times S} \mathcal{F}_{\Omega \times S} \right\|$, where I_k is the $k \times k$ identity matrix. It is shown in [RV08] that

$$\mathbb{E}_{\Omega} X \lesssim \sqrt{\frac{k \log^2 k \log d \log B}{B}} (\mathbb{E}\, X + 1) =: \sqrt{\frac{k\beta}{B}} (\mathbb{E}\, X + 1).$$

This implies that

$$\mathbb{E}\, X \leq 1 + \frac{O(k\beta)}{B} =: \alpha. \tag{17}$$

Indeed, whenever $x^2 \leq A(x+1)$, we have $x < A + 1$ or else we conclude $(A+1)^2 \leq A^2 + 2A$. Let α denote the right hand side of (17). We may plug this expectation into the proof of Theorem 3.9 in [RV08], and we obtain

$$\mathbb{P}\left[X > Ct\alpha\right] \leq 3\exp(-C't\alpha B/k) + 2\exp(-t^2)$$

for constants C and C'. In the case $X \leq Ct\alpha$, we have

$$\max_{|S|=k} \|\mathcal{F}_{\Omega \times S}\| \leq \sqrt{B(1 + Ct\alpha)} \leq \sqrt{B} + \sqrt{BCt\alpha},$$

and so we conclude that

$$\max_{|S|=k} \|\mathcal{F}_{\Omega \times S}\| \leq \sqrt{B} + O\left(\sqrt{t(B + k\beta)}\right)$$

with probability at least

$$1 - 3\exp(-C't(\beta + B/k)) - 2\exp(-t^2).$$

∎