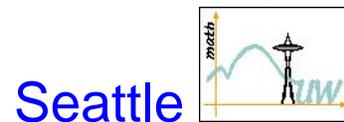


Parametrized Variational Inequality Approaches to the Generalized Nash Equilibrium Problem

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Talk Outline

- Generalized Nash Equilibrium with Shared Constraints
- VI Approach to Finding Some GNEs
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Generalized Nash Equilibrium with Shared Constraints

N players. Each player ν has a “cost” function $\theta_\nu : \mathbb{R}^n \rightarrow \mathbb{R}$ and a “feasible” set $X_\nu \in \mathbb{R}^{n_\nu}$, $\nu = 1, \dots, N$ ($n_1 + \dots + n_N = n$).

There is a shared constraint function $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

A Generalized Nash Equilibrium (GNE) is any $x^* = (x_1^*, \dots, x_N^*) \in \mathbb{R}^n$ satisfying

$$x_\nu^* \in \arg \min_{x_\nu \in X_\nu} \{ \theta_\nu(x_\nu, x_{-\nu}^*) \mid g(x_\nu, x_{-\nu}^*) \leq 0 \}, \quad \nu = 1, \dots, N$$

Assumption:

- Each X_ν is nonempty, closed, convex.
- $\theta_\nu(\cdot, x_{-\nu})$ is convex for each ν and $x_{-\nu} \in X_{-\nu}$.
- $g = (g_1, \dots, g_m)^T$, with each g_i differentiable, convex.

Under suitable CQ at x^* , there exist $\lambda_\nu^* \in \mathbb{R}^m$, $\nu = 1, \dots, N$, satisfying the **GNE-KKT condition**:

$$\begin{aligned} 0 &\in \nabla_{x_\nu} \theta_\nu(x^*) + \nabla_{x_\nu} g(x^*) \lambda_\nu^* + N_{X_\nu}(x_\nu^*), & \nu = 1, \dots, N \\ 0 &\leq \lambda_\nu^* \perp g(x^*) \leq 0, & x_\nu^* \in X_\nu, \end{aligned}$$

GNE has many interesting applications. [Facchinei, Fischer, Fukushima, Kanzow, Krawczyk, Pang, Robinson, Rosen, Smeers, Uryasev, Wei, ...](#)

Existing approaches, based on penalty method [Fukushima, Pang](#) or VI formulation [Facchinei, Fischer, Piccialli, Smeers, Wei](#) or Nikaido-Isoda function [von Heusinger, Kanzow, Krawczyk, Uryasev](#), find only one or some GNEs, but not all GNEs.

Like to find all GNEs or, at least, a “sufficiently rich” subset of GNEs.

VI Approach to Finding Some GNEs

Define

$$\begin{aligned} F(x) &:= (\nabla_{x_\nu} \theta_\nu(x))_{\nu=1}^N \\ X &:= \{x \in X_1 \times \cdots \times X_N \mid g(x) \leq 0\} \end{aligned}$$

$$x^* \text{ is a soln of VI}(F, X) \iff x^* \in \arg \min_{x \in X} \langle F(x^*), x \rangle$$

Theorem 0: Wei & Smeers, Facchinei et al.

If x^* and $\lambda_0^* \in \mathfrak{R}^m$ satisfy KKT condition for VI (F, X) , then x^* and $\lambda_\nu^* = \lambda_0^*$, $\nu = 1, \dots, N$, satisfy **GNE-KKT condition**.

Parameterized VI Approach to Finding “All” GNEs

1. Price-Directed Parametrization:

For any $\pi_\nu \in \mathfrak{R}_+^m$, $\nu = 1, \dots, N$, let $\pi = (\pi_\nu)_{\nu=1}^N$ and define

$$F^\pi(x) := F(x) + (\nabla_{x_\nu} g(x) \pi_\nu)_{\nu=1}^N$$

Theorem 1: Fix any $\pi = (\pi_\nu)_{\nu=1}^N \in \mathfrak{R}_+^{mN}$. If x^* and $\lambda_0^* \in \mathfrak{R}^m$ satisfy KKT condition for VI (F^π, X) , then a sufficient condition for x^* and $\lambda_\nu^* = \lambda_0^* + \pi_\nu$, $\nu = 1, \dots, N$, to satisfy **GNE-KKT condition** is

$$\langle g(x^*), \pi_\nu \rangle = 0, \quad \nu = 1, \dots, N$$

If x^* satisfies **GNE-LICQ**, this condition is also necessary.

Converse Fact: If x^* and $\lambda^* = (\lambda_\nu^*)_{\nu=1}^N$ satisfy the **GNE-KKT condition**, then x^* is a soln of VI (F^{λ^*}, X) .

GNE-LICQ:

$$\left\{ \begin{array}{l} 0 \in \nabla_{x_\nu} g(x^*) \lambda_\nu + N_{X_\nu}(x_\nu^*) + (-N_{X_\nu}(x_\nu^*)) \\ \lambda_\nu \perp g(x^*) \leq 0 \end{array} \right\} \implies \lambda_\nu = 0, \quad \nu = 1, \dots, N.$$

Fact: Assume $g(x) = \sum_{\nu=1}^N g_\nu(x_\nu)$.

If F is (strongly) monotone on X , then F^π is (strongly) monotone on X for any $\pi \in \mathfrak{R}_+^{mN}$.

2. Resource-Directed Parametrization:

Assume $g(x) = \sum_{\nu=1}^N g_{\nu}(x_{\nu})$.

For any $\beta_{\nu} \in \mathfrak{R}^m$, $\nu = 1, \dots, N$, satisfying $\sum_{\nu=1}^N \beta_{\nu} = 0$, let $\beta := (\beta_{\nu})_{\nu=1}^N$,

$$X^{\beta} := X_1^{\beta_1} \times \dots \times X_N^{\beta_N} \quad \text{with} \quad X_{\nu}^{\beta_{\nu}} := \{x_{\nu} \in X_{\nu} \mid g_{\nu}(x_{\nu}) \leq \beta_{\nu}\}$$

Theorem 2: Fix any $\beta = (\beta_{\nu})_{\nu=1}^N$ satisfying $\sum_{\nu=1}^N \beta_{\nu} = 0$. If x^* is a soln of VI(F, X^{β}), then a sufficient condition for x^* to be a GNE is that

$$\text{for each } i = 1, \dots, m, \quad \left\{ \begin{array}{l} \text{either } g_{\nu,i}(x_{\nu}^*) = \beta_{\nu,i} \quad \nu = 1, \dots, N \\ \text{or } g_{\nu,i}(x_{\nu}^*) < \beta_{\nu,i} \quad \nu = 1, \dots, N \end{array} \right\}$$

Converse Fact: If x^* is a GNE, then x^* is a soln of VI(F, X^{β}), where $\beta = (\beta_{\nu})_{\nu=1}^N$, $\beta_{\nu} = g_{\nu}(x_{\nu}^*) - \alpha_{\nu}g(x^*)$, with $\alpha_{\nu} > 0$ satisfying $\sum_{\nu=1}^N \alpha_{\nu} = 1$.

Some Numerical Results

1. Harker's example: $N = 2, n = 2, m = 1$.

$$x_1^* = \arg \min_{x_1 \in [0,10]} \left\{ x_1^2 + \frac{8}{3}x_1x_2^* - 34x_1 \mid x_1 + x_2^* \leq 15 \right\}$$

$$x_2^* = \arg \min_{x_2 \in [0,10]} \left\{ x_2^2 + \frac{5}{4}x_1^*x_2 - 24.25x_2 \mid x_1^* + x_2 \leq 15 \right\}$$

$$F(x) = \begin{bmatrix} 2x_1 + \frac{8}{3}x_2 - 34 \\ \frac{5}{4}x_1 + 2x_2 - 24.25 \end{bmatrix}$$

$$X = \{(x_1, x_2) \mid 0 \leq x_1, x_2 \leq 10, x_1 + x_2 \leq 15\}$$

VI(F, X) is strongly monotone, affine. Soln (5, 9).

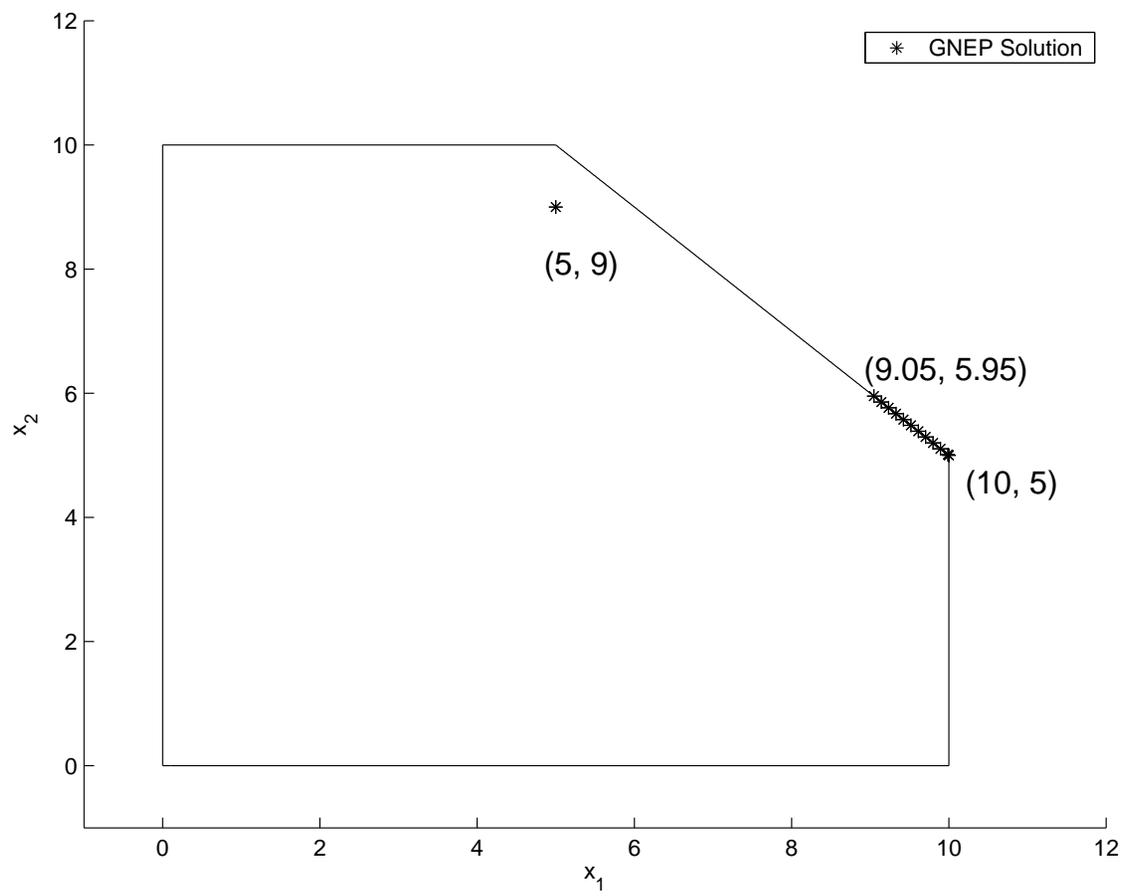
$g(x) = x_1 + x_2 - 15$ is separable.

Price-directed decomp:

Can restrict to $\pi_1 \in [0, 2], \pi_2 = 0$ or $\pi_1 = 0, \pi_2 \in [0, 2]$. Use 256 grid pts for each.

For each grid pt $\pi = (\pi_1, \pi_2)$, VI (F^π, X) is strongly monotone, affine.
Using Thm 1, soln x^* (found by PATHLCP.M [Ferris, Munson](#)) is declared GNE if

$$|\pi_\nu g(x^*)| < 10^{-6}, \quad \nu = 1, 2.$$



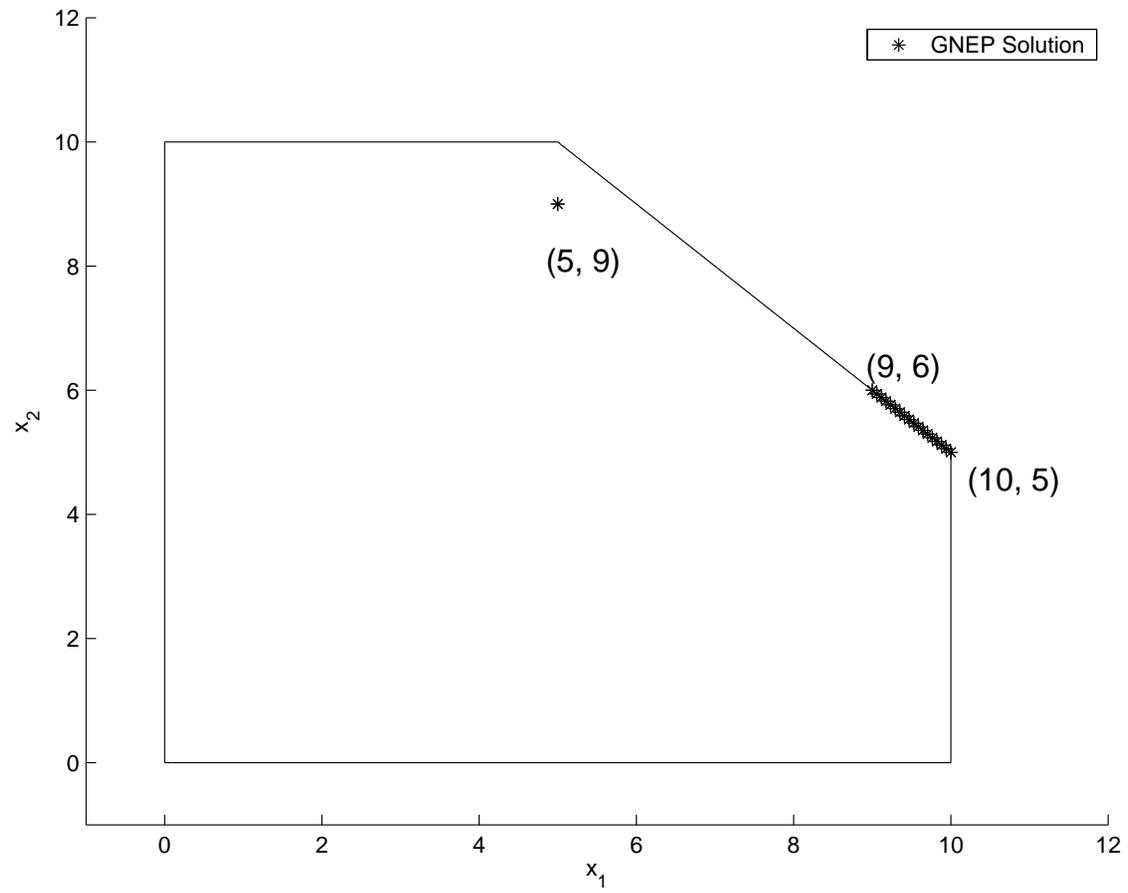
Resource-directed decomp:

Choose $g_1(x_1) = x_1 - \frac{15}{2}$, $g_2(x_2) = x_2 - \frac{15}{2}$.

Can restrict to $\beta_1 + \beta_2 = 0$, $|\beta_1| \leq \frac{15}{2}$. Use 256 grid pts.

For each grid pt $\beta = (\beta_1, \beta_2)$, VI (F, X^β) is strongly monotone, affine.
Using Thm 2, soln x^* is declared GNE if

$$\begin{aligned} &\text{either } |g_\nu(x_\nu^*) - \beta_\nu| < 10^{-6}, \quad \nu = 1, 2 \\ &\text{or } g_\nu(x_\nu^*) - \beta_\nu < -10^{-6}, \quad \nu = 1, 2. \end{aligned}$$



2. River basin pollution Krawczyk, Uryasev: $N = 3, n = 3, m = 2$.

$$x_\nu^* = \arg \min_{x_\nu \geq 0} \{(\alpha_\nu x_\nu + 0.01(x_\nu + x_{-\nu}^*) - \chi_\nu)x_\nu \mid g(x_\nu, x_{-\nu}^*) \leq 0\}, \quad \nu = 1, 2, 3$$

with $\alpha_1 = \alpha_3 = 0.01, \alpha_2 = 0.05, \chi_1 = 2.9, \chi_2 = 2.88, \chi_3 = 2.85$, and

$$g(x) = \begin{bmatrix} 3.25x_1 + 1.25x_2 + 4.125x_3 - 100 \\ 2.2915x_1 + 1.5625x_2 + 2.8125x_3 - 100 \end{bmatrix}$$

$$F(x) = \begin{bmatrix} 0.04 & 0.01 & 0.01 \\ 0.01 & 0.12 & 0.01 \\ 0.01 & 0.01 & 0.04 \end{bmatrix} x - \begin{bmatrix} 2.9 \\ 2.88 \\ 2.85 \end{bmatrix}$$

$$X = \{x \in \mathbb{R}_+^3 \mid g(x) \leq 0\}$$

VI(F, X) is strongly monotone, affine. Soln = (21.14..., 16.03..., 2.73..)

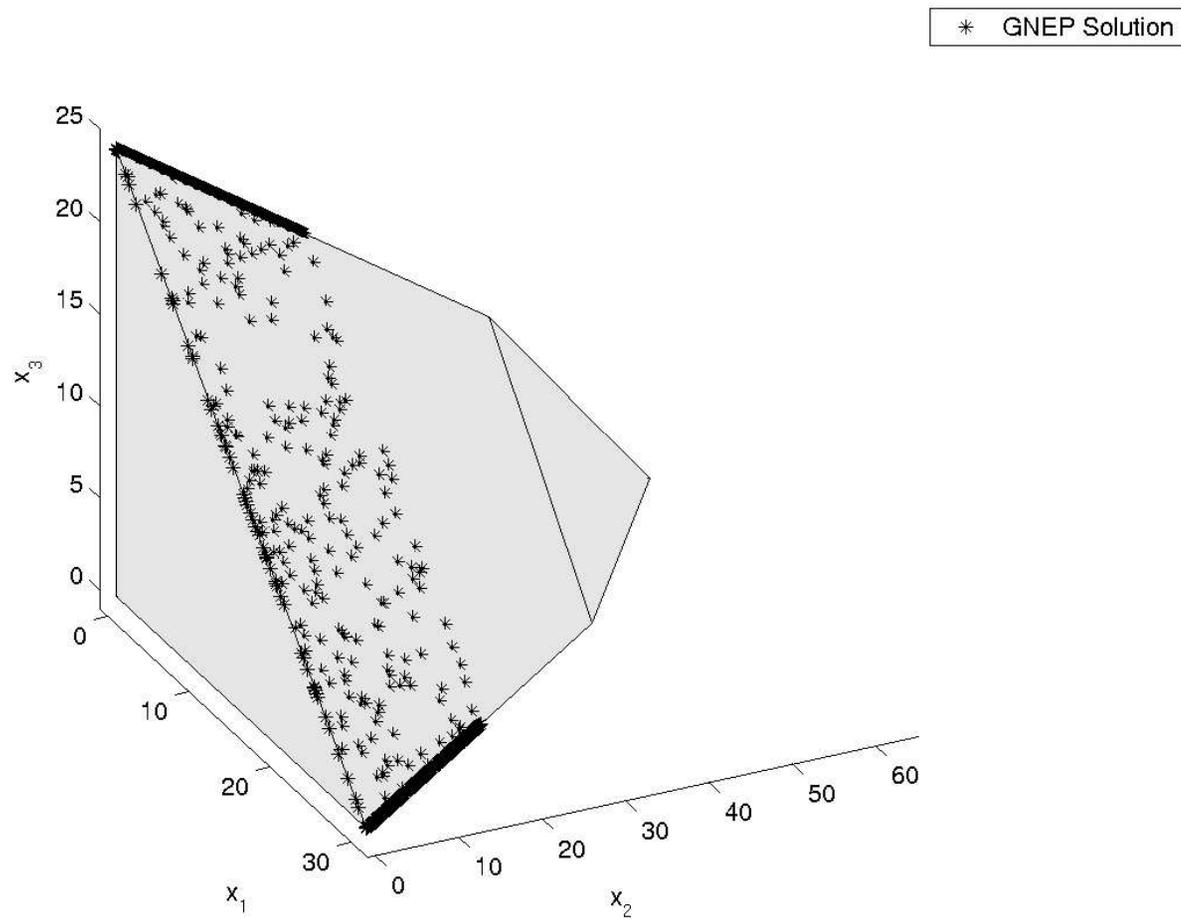
$g(x)$ is separable.

Price-directed decomp:

Restrict to $\pi_1, \pi_2, \pi_3 \in [0, 2]^2$ such that the i th component is zero in one or three of them, $i = 1, 2$. Randomly generate 1000 pts for each of 16 cases except the all-zero case. Total of 15,001 pts.

For each pt $\pi = (\pi_1, \pi_2, \pi_2)$, VI (F^π, X) is strongly monotone, affine. Using Thm 1, soln x^* (found by PATHLCP.M) is declared GNE if

$$|\langle \pi_\nu, g(x^*) \rangle| < 10^{-6}, \quad \nu = 1, 2, 3.$$



Resource-directed decomp:

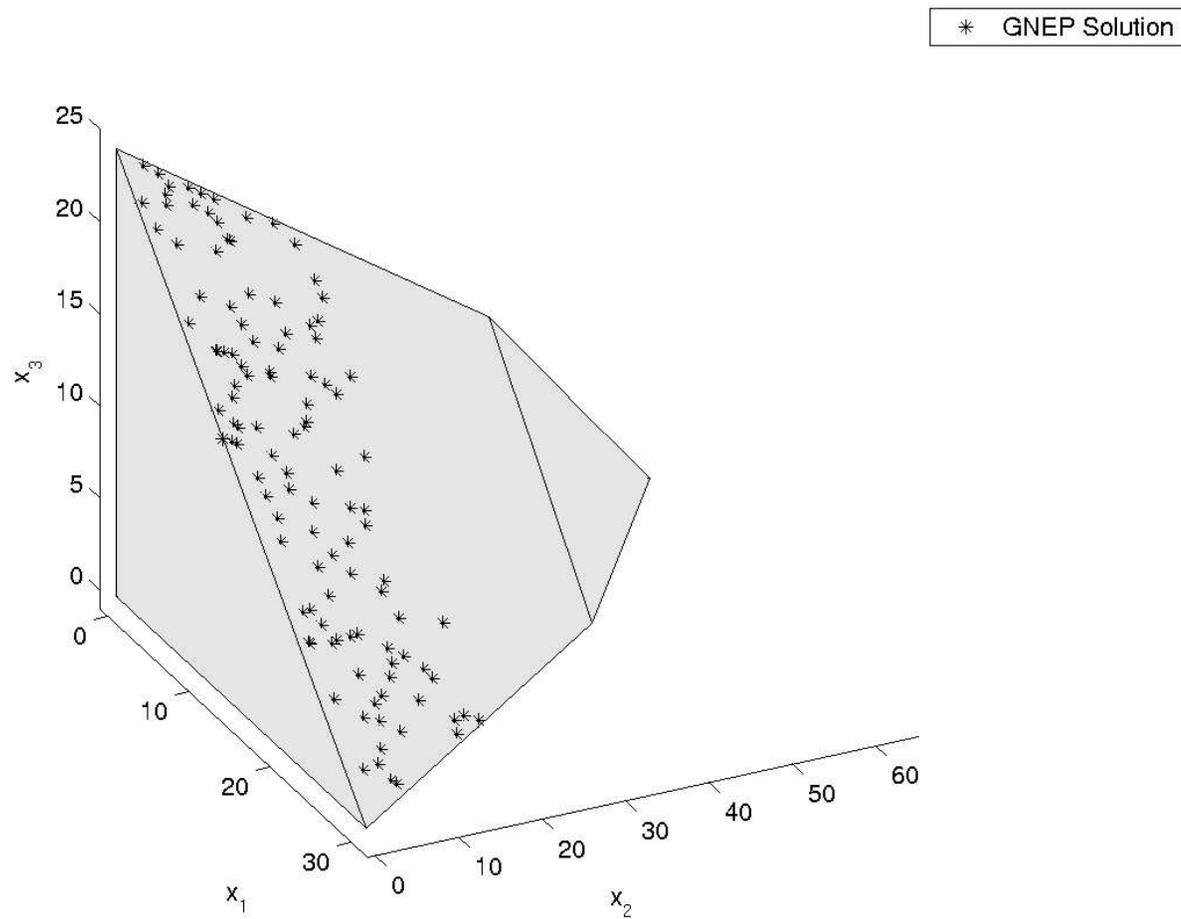
Choose

$$g_1(x_1) = \begin{bmatrix} 3.25x_1 - \frac{100}{3} \\ 2.2915x_1 - \frac{100}{3} \end{bmatrix}, g_2(x_2) = \begin{bmatrix} 1.25x_2 - \frac{100}{3} \\ 1.5625x_2 - \frac{100}{3} \end{bmatrix}, g_3(x_3) = \begin{bmatrix} 4.125x_3 - \frac{100}{3} \\ 2.8125x_3 - \frac{100}{3} \end{bmatrix}$$

Can restrict to $\beta_1 + \beta_2 + \beta_3 = 0$, $\beta_1, \beta_2 \geq -\left[\frac{100}{3}\right]$, $\beta_1 + \beta_2 \leq \left[\frac{100}{3}\right]$. Use 3700 randomly generated pts.

For each pt $\beta = (\beta_1, \beta_2, \beta_3)$, VI (F, X^β) is strongly monotone, affine.
Using Thm 2, soln x^* is declared GNE if

$$\text{for each } i = 1, 2, \left\{ \begin{array}{l} \text{either } |g_{\nu,i}(x_\nu^*) - \beta_{\nu,i}| < 10^{-6}, \quad \nu = 1, 2, 3 \\ \text{or } g_{\nu,i}(x_\nu^*) - \beta_{\nu,i} < -10^{-6}, \quad \nu = 1, 2, 3 \end{array} \right\}$$



Fact: If each θ_ν is quadratic, then $\{\text{GNEs}\} \cap \text{ri}Y$ is convex (possibly \emptyset) for each face Y of X . (So suffices to find extreme pts.)

Conclusions & Future Directions

1. More diverse GNEs can give more insight.
2. Price-directed decomposition does not require shared constraint function g be separable, but requires existence of multipliers. It samples in the space of prices. Sampling may not be “uniform” in the space of strategies.
3. Resource-directed decomposition does not require existence of multipliers but requires g be separable. Sampling appears more “uniform” in the space of strategies. Fewer samples are used.
4. More efficient ways to search the price/strategy space (beyond grid sampling or random sampling)? Restricting the search space?