RESTAURANT REVENUE MANAGEMENT

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We develop two classes of optimization models to maximize revenue in a restaurant (while controlling average waiting time as well as perceived fairness) that may violate the first-come-first-serve (FCFS) rule. In the first class of models, we use integer programming, stochastic programming, and approximate dynamic programming methods to decide dynamically when, if at all, to seat an incoming party during the day of operation of a restaurant that does not accept reservations. In a computational study with simulated data, we show that optimization-based methods enhance revenue relative to the industry practice of FCFS by 0.11% to 2.22% for low-load factors, by 0.16% to 2.96% for medium-load factors, and by 7.65% to 13.13% for high-load factors, without increasing, and occasionally decreasing, waiting times compared to FCFS. The second class of models addresses reservations. We propose a two-step procedure: Use a stochastic gradient algorithm to decide a priori how many reservations to accept for a future time and then use approximate dynamic programming methods to decide dynamically when, if at all, to seat an incoming party during the day of operation. In a computational study involving real data from an Atlanta restaurant, the reservation model improves revenue relative to FCFS by 3.5% for low-load factors and 7.3% for high-load factors.

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1. INTRODUCTION

Maximizing efficiency is of utmost importance in order for large and popular restaurants to increase their profits and to remain competitive. This can explain the surge in the usage of point of sales (POS) softwares that track the arrival time, size, and order of each customer. Although floor managers can utilize these tools as an aid to better estimate the remaining service time of the customers and to see which tables need to speed up their service, their seating policy is mainly based on intuition brought on by experience. In most cases, they follow a simple first-come-first-serve (FCFS) policy.

The challenge of a floor manager is to decide when and where to seat each arriving customer. If there are only tables of four available and a party of two enters, does he seat the party at the larger table or reserve it for a larger, more revenue-producing party? In addition, if the restaurant takes reservations, he needs to further decide how to seat walk-in customers so that they would not take tables away from the reservation customers while considering the possibility of no-shows. These are important practical issues for restaurant managers, where in some cases a good floor manager can make the difference of couple of hundred dollars per night (Kosugi 1999). Thus, a tool that can help floor managers better make these decisions would be of significant value to a restaurant.

With all the data that are collected by the POS software, a revenue-maximizing seating policy can be utilized. We believe the key lies in nesting—where parties are seated at tables that can seat larger parties. The present paper stems from the belief that restaurants can increase their revenue by optimizing their nesting decisions, i.e., when to save tables in anticipation for larger parties, even when there are smaller parties currently in queue. We develop two classes of optimization models to maximize revenue in a restaurant, while controlling average waiting time as well as perceived fairness, that may violate the FCFS rule. In the first class of models, we use integer programming, stochastic programming, and approximate dynamic programming methods to decide dynamically when, if at all, to seat an incoming party *during the day of operation* of a restaurant that does not accept reservations. In the second class of models, we use a stochastic gradient algorithm to decide when, if at all, to accept a reservation for *a future time* and also incorporate reservations in a dynamic model. We illustrate, using both simulated and real data, that our models lead to significant revenue enhancements relative to FCFS.

Literature

Revenue management in general is the practice of maximizing a company's revenue by optimally choosing which customers to serve. It has been used extensively in the airline, hotel, and car rental industries. McGill and van Ryzin (1999) give a comprehensive overview of the history of revenue management in transportation, where it has had the greatest impact.

In the case of restaurants, restaurant managers want to allocate their tables by seating the largest possible party at each table—assuming the total bill increases with party size. However, they need to also consider seating small parties at large tables when the larger parties are not expected

to arrive in the near future, because they would rather seat them than have an empty table. Thus, the challenge is to understand the demand flow throughout the day of each type of customer and optimize the allocation of the tables among them.

Unlike the widespread application of revenue management methods in airlines, hotels, and rental cars, the number and depth of studies on revenue management in restaurants have been comparatively slim. Kimes (1998, 1999) and Kimes et al. (1999) have been among the first to directly address the issue of restaurant revenue management. They built a strategic framework for applying revenue management for restaurants to increase demand, and thus revenue, by effective duration management and demand-based pricing. They proposed using the revenue per available seat hour (RevPASH := revenue accrued in a given time interval divided by the number of seats available during that time) as the restaurant's performance metric. This value is calculated for each time period of each day, to identify times that the RevPASH is low. Similarly, Sill et al. (1999, 2000) propose the use of Capacity-Management Science (CMS)® as a systematic method of assessing the restaurant's capacity potential and process efficiency. CMS® involves monitoring every component of the service and production delivery process with quantifiable measurements to improve customer satisfaction, enhance employee work life, and increase profit.

Although not specified under the name of revenue management, many other approaches have been proposed to increase the revenue of restaurants. Vakharia et al. (1992) developed models and heuristics to find the best trade-off between wages and hour preferences to minimize the cost of employees while maintaining employee satisfaction. Quain et al. (1998) and Muller (1999) addressed managerial factors that may improve the efficiency of restaurants, such as realizing profit centers, dispersing demand, decreasing operating hours, and decreasing service time by making the restaurant operational procedures as efficient as possible.

Most of the studies in this area address issues concerning the overall management of the restaurant. However, to the best of our knowledge there are no studies on a mathematically rigorous dynamic seating model.

Our objective in the present paper is to develop and test, using both simulated and real data, several increasingly sophisticated optimization-based approaches to restaurant revenue management (RRM) that address trade-offs between expected revenue, average waiting time, and perceived fairness, that may violate the FCFS rule.

Contributions

Our contributions are:

(1) Because an exact dynamic programming approach to RRM is infeasible due to "the curse of dimensionality," we develop mathematical-programming-based approaches of increasing sophistication to maximize expected revenue, taking into account expected waiting time and associated fairness issues. We develop integer programming, stochastic programming, and approximate dynamic programming models to provide efficiently implementable policies for RRM. These approaches are interesting in their own right and may find application in revenue management in other contexts. A particularly promising method is the approach of approximate dynamic programming based on an integer programming model.

(2) We propose a stochastic gradient algorithm motivated by the work of Karaesmen and van Ryzin (1998) to address RRM with reservations. We also apply approximate dynamic programming to make optimal seating decisions for both reservation and walk-in customers online.

(3) In computational studies involving both simulated and real data, we show that our models improve revenue, often substantially, relative to the industry standard of seating parties in a FCFS manner, without increasing the average waiting time.

Structure

The structure of this paper is as follows: §2 describes the structure and components of the basic model. Section 2.1 describes the integer programming approach, while §2.2 outlines the simulation model. Section 3 elaborates on extensions to the basic model. Two variations of the model are introduced in this section: §3.1 describes the stochastic programming version of the basic model; §3.2 introduces an approximate dynamic programming approach for the basic integer programming model; §3.3 describes FCFS models and the bid-pricing model used as a performance baseline for the previous models. Section 4 introduces reservations to our previous models. Section 4.1 describes the reservation-booking model that determines the optimal booking level using a stochastic gradient algorithm, while §4.2 describes a modified version of the approximate dynamic programming model introduced earlier. In §§5 and 6 we report computational results for models without and with reservations, respectively. Section 7 summarizes our findings and contains some concluding remarks.

2. THE BASIC MODEL

2.1. An Integer Programming Approach

In this section, we develop an integer programming (IP) model that aims to maximize the expected future revenue, while controlling for expected waiting time by deciding when and where to seat each incoming party. We use a discrete time horizon of N equal-length periods so that the number of decision variables and constraints remain tractable. We first introduce the data on which the model is based.

Data. We consider a restaurant that can seat parties of size $k = 2, 4, \ldots, K$, with K even. For simplicity, parties of sizes $1, 3, \ldots, K-1$ can be considered to be one person larger. There are $k' = 2, 4, \ldots, K$ different table sizes such that a party of size k can sit at a table of size k',

for $k' \geqslant k$. We assume that the total revenue generated by a party increases with the party size. Note that we do not necessarily assume that the revenue per person is affected by party size. We model the service time as a collection of SP service phases (for example: first course, second course, dessert). By breaking up the service time and keeping track of how many parties are in each phase, we can make a better estimate of the remaining service time. Our model only uses information about expected values. In this respect, our model is similar to network airline revenue management systems that use a linear programming model (for example, the widely used bid-price control approach) to decide seat allocation. We assume the following information is known:

$c_k :=$ the number of tables of size k available,

$D_{t,k} :=$ the expected number of size k parties arriving at time, t,

$S_{k,s} :=$ the expected duration of phase s for a size k party,

$S_{k.} := \sum_{s=1}^{SP} S_{k,s}$, the expected total service duration of a size k party,

$S'_{k,s} := \sum_{n=s}^{SP} S_{k,n}$, the expected remaining service duration for a size k party entering phase s,

$R_k :=$ the revenue expected from a party of size k,

$CostQ_{t,k} :=$ the cost of postponing service to a party of size k that arrived at time t and is currently in queue, and

$CostX_{t,k} :=$ the cost of postponing service to a party of size k that is expected to arrive at time t.

The above data can be collected by many POS softwares. For example, $D_{t,k}$ and R_k can be estimated using historical data on customer arrivals and bills, which is often kept track of by POS softwares. We have found there are several POS products that have the ability to track service phases of customers with an electronic ordering pad used by waiters when taking orders. Currently, these pads are used to send orders to the kitchen, but we believe they can also be used to notify the floor manager of the progress of the customers in their meals. With this added feature, it would be easy for the POS software to estimate average service-phase durations. Floor managers would need to record arrival and departure times of parties, but that can be readily linked to seating the parties and processing their bills, respectively. Finally, we set the values for $CostQ_{t,k}$ and $CostX_{t,k}$ in our computational experiments (see §5) to capture the trade-off between quality of service (excessive waiting times and denied service) and revenue.

In addition to revenue, important considerations in managing restaurants are the control of waiting time and associated fairness issues. Thus, in the IP model we explicitly address these issues. For this purpose, we introduce the following parameters that we adjust to achieve the "right" trade-off between revenue, waiting time, and fairness.

$Max :=$ the maximum number of periods that a party will wait,

$M :=$ a user-defined parameter that controls the trade-off between revenue and waiting time (the higher M, the higher the importance of the waiting time; see Equation (1)), and

$\eta :=$ a user-defined parameter that controls the trade-off between revenue and allowing flexibility in allocating a size k party to a table of size $k' \geqslant k$; see Equation (1).

In practice, the waiting time behavior of customers is complex. The amount of time a party may wait in queue may follow a probabilistic distribution and may be dependent on the size of the party and time of arrival. However, to simplify the model, we assume that every party is willing to wait up to Max periods. If they are not seated within Max periods, the model assumes that they automatically renege from the queue.[1] It further assumes that parties cannot renege earlier or later than Max periods. Appropriate values for Max, M, and η are discussed in §§5 and 6.

State. The state of the system is described as follows.

$now :=$ the current time (in periods),

$Q_{t,k} :=$ the number of size k parties that arrived at time t currently waiting in queue, and

$N^s_{k,k'} :=$ the number of size k parties in service phase s seated at a size k' table.

To better utilize capacity, the IP model allows parties of size k to be seated at a table of size $k' \geqslant k$. The service state parameters $N^s_{k,k'}$ keep track of these parties.

Decision Variables. We introduce the following decision variables:

$q_{t,t',k,k'} :=$ the number of parties of size k, who arrived at time t and are currently in the queue, that should be seated at a size k' table at time t',

$qdeny_{t,k} :=$ the number of parties of size k, who arrived at time t and are currently in the queue, that are not currently allocated a seat (i.e., not seated within Max periods),

$x_{t,t',k,k'} :=$ the number of parties of size k, out of $D_{t,k}$, that should be seated at a size k' table at time t',

$xdeny_{t,k} :=$ the number of parties of size k, out of $D_{t,k}$, that are not currently allocated a seat (i.e., not seated within Max periods),

$z^q_{t,k} :=$ the auxiliary variables that allow us to model fairness in the seating decisions, captured in Equations (5) and (6) below, and

$z^x_k :=$ the auxiliary variables that allow fairness in the seating decisions, captured in Equations (7) and (8) below.

Each time the IP model is formulated, there are two disjoint sets of customers that it must consider, those that have already arrived and those that are expected to arrive. $q_{t,t',k,k'}$ and $qdeny_{t,k}$ are seating-decision variables corresponding to the former type of customers, and $x_{t,t',k,k'}$ and $xdeny_{t,k}$ are the seating-decision variables for the latter type. The parties represented by the $q_{t,t',k,k'}$s and $qdeny_{t,k}$s are parties that have already arrived and are thus known. However, the parties represented by $x_{t,t',k,k'}$s and $xdeny_{t,k}$s have not yet arrived and are thus uncertain. Partitioning the decision variables in such a way allows for more dynamic and flexible modeling.

The model does not explicitly *deny* service to the customers, but it may not be able to seat some parties within Max periods—the maximum number of periods that a party would be willing to wait in queue. These parties that are not currently allocated a table are captured by the decision

variables $qdeny_{t,k}$ and $xdeny_{t,k}$. The use of the auxiliary variables $z^q_{t,k}$ and z^x_k will be described in more detail in the IP formulation.

The Integer Program Formulation. We formulate and solve an integer program at each customer arrival and departure, and determine from the optimal solution whether a party should be seated. Our objective is to maximize expected revenue, while maintaining reasonable waiting times and fairness in our seating decisions, by considering the state of the restaurant. We can also maximize occupancy by assuming that the revenue per person is independent of the number in the party. Although we solve the IP to optimality, the data we use, such as expected demand, expected service time, and the simplified waiting-time behavior, are only estimations. Thus, the expected future state of the restaurant modeled by the IP are also estimations. However, capturing the states of the system exactly in a stochastic dynamic programming sense would be computationally intractable, thus making our IP model a viable heuristic. The proposed model is as follows.

Objective Function. The objective is the maximization of expected future revenue while controlling waiting time:

$$\max \sum_{\substack{t=1,\dots,\lfloor now\rfloor \\ k=2,\dots,K}} \sum_{\substack{k'=k,\dots,K \\ t'=\lfloor now\rfloor,\dots,\min(N,t+Max-1)}} (R_k - M(t'-t) - \eta(k'-k)) q_{t,t',k,k'} - \sum_{\substack{t=1,\dots,\lfloor now\rfloor \\ k=2,\dots,K}} CostQ_{t,k}\, qdeny_{t,k},$$

$$\sum_{\substack{t=\lfloor now\rfloor,\dots,N \\ k=2,\dots,K}} \sum_{\substack{k'=k,\dots,K \\ t'=t,\dots,\min(N,t+Max-1)}} (R_k - M(t'-t) - \eta(k'-k)) x_{t,t',k,k'} - \sum_{\substack{t=\lfloor now\rfloor,\dots,N \\ k=2,\dots,K}} CostX_{t,k}\, xdeny_{t,k}. \quad (1)$$

The first set of summations corresponds to the expected revenue that can be attained from parties *currently* in the queue. The second set corresponds to the cost of not allocating a table to parties currently in the queue. The third set corresponds to the revenue from parties *expected* to arrive in the future, and the last is the cost of not allocating a table to those customers.

The term $-M(t'-t)$ in the first and third coefficients is a cost against excessive waiting time. The cost $-\eta(k'-k)$ encourages seating from the smallest available table first. Without this term, the model may, for example, seat a party of size two at a table of size eight if it does not expect larger-sized parties in the near future. However, because our expected demand data are only estimations and the actual demand is uncertain, we want to be on the safe side and seat from the smallest available table first.

The costs $CostQ_{t,k}$ and $CostX_{t,k}$ are necessary for the model to give preference to customers in the queue, as well as those expected to arrive in the current period, over those expected to arrive in the future. Thus, the value of $CostQ_{t,k}$ is higher than $CostX_{t,k}$ for all t for each k, because postponing service to a customer already in queue should be higher than postponing service to a customer expected to arrive in the future. Also, $CostX_{t,k}$ for $t = \lfloor now\rfloor$ is higher than that for $t > \lfloor now\rfloor$. If it were the same, the model would consider postponing service to a party that arrives in the current period versus seating that party and postponing service to an equal-sized future party as the same. We prefer the former solution, since there is a possibility that a party will arrive in the current period, and thus we want the model to give us the ability to seat them. The exact numerical value of these weights are determined by computational experimentation.

Constraints.

(1) *Demand Constraints.*

$$\sum_{\substack{t'=\lfloor now\rfloor,\dots,\min(N,t+Max-1) \\ k'=k,\dots,K}} q_{t,t',k,k'} + qdeny_{t,k} = Q_{t,k} \quad \forall\ t=1,\dots,\lfloor now\rfloor; k=2,\dots,K, \quad (2)$$

$$\sum_{\substack{t'=t,\dots,\min(N,t+Max-1) \\ k'=k,\dots,K}} x_{t,t',k,k'} + xdeny_{t,k} = D_{t,k} \quad \forall\ t=\lfloor now\rfloor,\dots,N; k=2,\dots,K. \quad (3)$$

Constraints (2) insure that the model does not seat more parties than those currently in the queue. Constraints (3) insure that the model does not seat more parties than currently expected.

(2) *Seating-Capacity Constraints.* This constraint characterizes the capacity constraint at each time τ for each table size k'. It also incorporates a nesting concept that allows parties of size k to sit at a size k' table, where $k \leqslant k'$:

$$\sum_{\substack{k=2,\dots,k' \\ t'\in T(t,k)}} \left(\sum_{t=\max(1,\,t'-Max+1),\dots,\lfloor now\rfloor} q_{t,t',k,k'} + \sum_{t=\max(\lfloor now\rfloor,\,t'-Max+1),\dots,t'} x_{t,t',k,k'} \right) + \sum_{\substack{k=2,\dots,k' \\ s=1,\dots,SP}} I_N(\tau) \leqslant c_{k'} \quad \forall\ \tau=\lfloor now\rfloor,\dots,N; k'=2,\dots,K, \quad (4)$$

where

$$T(t,k) = \{t' : t \leqslant t' \leqslant \tau \leqslant t' + S_k, t' \in \mathcal{T}\},$$

$$I_N(\tau) = \begin{cases} N^s_{k,k'}, & \text{if } \tau \leqslant now + S'_{k,s}, \\ 0, & \text{otherwise.} \end{cases}$$

Note that the parameters $N^s_{k,k'}$ allow for a more accurate estimation of the remaining service time of the parties currently being served. The last summation term in Equation (4) corresponds to the expected number of parties currently seated at table k' who are still being served at time τ.

(3) *Fairness Constraints.* The model uses parameter M to control waiting time in the objective function. However, when this cost is added, the model would rather seat last-come-first-serve within the same party size because the last customer to arrive would have less waiting time, and thus a higher objective value. To avoid this problem, we add constraints in the model that would seat the customers *within* the same party size in the order that they arrived. By seat-

ing parties in queue by FCFS within the same party size, the waiting time of the parties decreases and fewer parties will leave from the queue. In particular, because of perceived unfairness, customers in a restaurant would strongly complain if a same-sized party that arrived after them were seated before them.

The following constraint insures a FCFS seating policy within the same party size for those in the queue that are able to be seated at the current time. It is not extended to future periods due to the uncertainty of the future state of the queue.

$$\sum_{\substack{\tilde{t}=\max(1,\lfloor now\rfloor-Max+1),\ldots,t-1\\ \tilde{k}=k,\ldots,K}} \left(Q_{\tilde{t},k}-q_{\tilde{t},\lfloor now\rfloor,k,\tilde{k}}\right) \leqslant \left(\sum_{\tilde{t}=\max(1,\lfloor now\rfloor-Max+1),\ldots,t-1} Q_{\tilde{t},k}\right) z^q_{t,k}, \tag{5}$$

$$\sum_{\tilde{k}=k,\ldots,K} q_{t,\lfloor now\rfloor,k,\tilde{k}} \leqslant L(1-z^q_{t,k})$$

$$\text{for } t=\max(2,\lfloor now\rfloor-Max+2),\ldots,\lfloor now\rfloor; \quad k=2,\ldots,K, \tag{6}$$

$$\sum_{\substack{\tilde{t}=\max(1,\lfloor now\rfloor-Max+1),\ldots,\lfloor now\rfloor\\ \tilde{k}=k,\ldots,K}} \left(Q_{\tilde{t},k}-q_{\tilde{t},\lfloor now\rfloor,k,\tilde{k}}\right) \leqslant \left(\sum_{\tilde{t}=\max(1,\lfloor now\rfloor-Max+1),\ldots,t-1} Q_{\tilde{t},k}\right) z^x_k, \tag{7}$$

$$\sum_{\tilde{k}=k,\ldots,K} x_{\lfloor now\rfloor,\lfloor now\rfloor,k,\tilde{k}} \leqslant L(1-z^x_k), \quad \text{for } k=2,\ldots,K. \tag{8}$$

Here $z^q_{t,k}$, z^x_k are auxiliary binary decision variables associated with each set of constraints. L is some large positive constant. Equations (5) and (6) state that if there are parties of size k that arrived before time t still in queue (i.e., the LHS of (5) is positive), then $z^q_{t,k}$ has to be equal to 1. This implies that the LHS of (6) must be zero. In other words, Equations (5) and (6) insure that a party of size k that arrived at time t can be seated only when there are no parties of k that arrived before them still in queue. Constraints (7) and (8) are analogous to parties of size k expected to arrive at the current period.

(4) *Integrality Constraints.* For $t = 1,\ldots,N; t' = t, \ldots, N; k = 2,\ldots,K; k' = k,\ldots,K;$

$$q_{t,t',k,k'} \in \mathbb{Z}^+, \quad x_{t,t',k,k'} \in \mathbb{Z}^+,$$
$$z^q_{t,k} \in \{0,1\}, \quad z^x_k \in \{0,1\}. \tag{9}$$

2.2. The Simulation

The IP described in Equations (1)–(9) will be formulated and solved whenever the floor manager needs to make a seating decision. When incorporated into a POS product, the system would optimize the IP model with the current system data each time a new customer arrives or when a customer exits. If the optimal solution of the model indicates that a party should be seated or not seated at that moment, the result is conveyed to the floor manager, who can act accordingly.

The implementation of the model is simple. There is little or no added work for the floor manager who uses most POS products. He or she needs only to input the size of a newly arrived party and take note when a party exits. All the information needed to run the model is already being collected in many large restaurants.

To summarize, there are three events that drive the model: (1) customer arrivals, (2) service completion, and (3) customer attrition from the queue. The model works in the following way after each of these events:

(1) Customer Arrives:
- Input the party size and time of arrival.
- Update appropriate $D_{t,k}$.
- Formulate and solve the IP model using current system data.
- Act according to the IP solution and update system data, i.e.,
  - — If the party is to be seated, seat them at the specified table. Update $N^s_{k,k'}$ accordingly.
  - — If the party is not to be seated, put them at the end of the line. Update $Q_{t,k}$ accordingly.

(2) Customer Exits After Service Completion:
- Exit the party from the table.
- Update appropriate $N^s_{k,k'}$.
- Formulate and solve the IP model using current system data.
- Act according to the IP output and update system data, i.e.,
  - — If a party currently in the queue is to be seated, take them off the queue and seat them at the specified table. Update $N^s_{k,k'}$ and $Q_{t,k}$ accordingly.

(3) Customer Attrition from the Queue
- Update appropriate $Q_{t,k}$.

We update $N^s_{k,k'}$ and $Q_{t,k}$ by incrementing or decrementing the appropriate term. We do the same for $D_{t,k}$, the expected future demand, instead of using any probabilistic approach to forecasting demand. The initial value of $D_{t,k}$ is set to the expected demand for each time period t and party size k calculated by a simple average of the historical data. As arrivals are seen for a given t and k, $D_{t,k}$ is decremented. If $D_{t,k}$ is 0 when an unexpected customer arrives, the simulation model automatically puts them in the queue, the queue state is updated, and the IP is optimized. Although the party is theoretically put in the queue from the model's perspective, they often do not have to wait to be seated. Though this is a simplified estimate of future demand levels, it seems sufficient from our computational experimentations.

3. EXTENSIONS OF THE BASIC MODEL

In this section, we present several increasingly more sophisticated extensions of the basic model.

3.1. A Stochastic Integer Programming Model

One of the shortcomings of the basic model is its sole use of the expected demand values as an indication of future customer arrivals. The stochastic version of the IP introduces various demand scenarios that the IP model can work with. Several demand scenarios are generated similarly to the process of generating arrivals in simulations. By using the generated scenarios with the expected demand values, the IP attempts to more accurately capture the future demand characteristics.

The stochastic IP model works with Ω demand scenarios (one of them being the expected case), each with probability α_ω, where $\omega = 1, 2, \ldots, \Omega$. The objective function is modified to maximize the expected revenue over the possible scenarios.

Additional and Modified Data and Parameters. To summarize the new parameters and data required:

$\Omega :=$ the total number of scenarios,

$\alpha_\omega :=$ the probability of scenario ω, and

$D^\omega_{t,k} :=$ the number of currently expected size k parties arriving at time t in scenario ω.

Modified Decision Variables. To summarize the modified decision variables:

$x_{t,t',k,k',\omega} :=$ the number of size k parties, out of $D^\omega_{t,k}$, that should be seated at a table of size k' at time t' in scenario ω,

$xdeny_{t,k,\omega} :=$ the number of size k parties, out of $D^\omega_{t,k}$, that are not allocated a table in scenario ω, and

$z^x_{k,\omega} :=$ the auxiliary variables that allow fairness in the seating decision, captured in Equations (14) and (15).

Stochastic Integer Programming Formulation.

Objective Function.

$$\max \sum_{\substack{t=1,\ldots,\lfloor now\rfloor \\ k=2,\ldots,K}} \sum_{\substack{k'=k,\ldots,K \\ t'=\lfloor now\rfloor,\ldots,\min(N,t+Max-1)}} (R_k - M(t'-t) - \eta(k'-k)) q_{t,t',k,k'}$$
$$- \sum_{\substack{t=1,\ldots,\lfloor now\rfloor \\ k=2,\ldots,K}} CostQ_{t,k}\, qdeny_{t,k},$$
$$\sum_{\substack{t=\lfloor now\rfloor,\ldots,N \\ k=2,\ldots,K}} \sum_{\substack{k'=k,\ldots,K \\ t'=t,\ldots,\min(N,t+Max-1) \\ \omega=1,\ldots,\Omega}} \alpha_\omega (R_k - M(t'-t) - \eta(k'-k)) x_{t,t',k,k',\omega}$$
$$- \sum_{\substack{t=\lfloor now\rfloor,\ldots,N \\ k=2,\ldots,K \\ \omega=1,\ldots,\Omega}} \alpha_\omega CostX_{t,k}\, xdeny_{t,k,\omega}. \quad (10)$$

Constraints.

(1) *Demand Constraints.* The first set of constraints insures that the IP model does not seat more customers than those in the queue. The second set insures that the IP model does not seat more parties than the demand for each scenario:

$$\sum_{\substack{t'=\lfloor now\rfloor,\ldots,\min(N,t+Max-1) \\ k'=k,\ldots,K}} q_{t,t',k,k'} + qdeny_{t,k} = Q_{t,k}$$
$$\forall \quad t = 1, \ldots, \lfloor now\rfloor;\ k = 2, \ldots, K, \quad (11)$$

$$\sum_{\substack{t'=t,\ldots,\min(N,t+Max-1) \\ k'=k,\ldots,K}} x_{t,t',k,k',\omega} + xdeny_{t,k,\omega} = D^\omega_{t,k}$$
$$\forall\ t = \lfloor now\rfloor, \ldots, N;\ k = 2, \ldots, K;\ \omega = 1, \ldots, \Omega. \quad (12)$$

(2) *Seating-Capacity Constraint.*

$$\sum_{\substack{k=2,\ldots,k' \\ t'\in T(t,k)}} \Bigg(\sum_{t=\max(1,\, t'-Max+1),\ldots,\lfloor now\rfloor} q_{t,t',k,k'} + \sum_{t=\max(\lfloor now\rfloor,\, t'-Max+1),\ldots,t'} x_{t,t',k,k',\omega} \Bigg)$$
$$+ \sum_{\substack{k=2,\ldots,k' \\ s=1,\ldots,SP}} I_N(\tau) \leqslant c_{k'} \quad \forall\ \tau = \lfloor now\rfloor, \ldots, N;$$
$$k' = 2, \ldots, K;\ \omega = 1, \ldots, \Omega, \quad (13)$$

where $T(t,k')$ and $I_N(\tau)$ are as in (4).

(3) *Fairness Constraint.* Same as (5) and (6). In addition,

$$\sum_{\substack{\tilde{t}=\max(1,\,\lfloor now\rfloor-Max+1),\ldots,\lfloor now\rfloor \\ \tilde{k}=l,\ldots,K}} \left(Q_{\tilde{t},k} - q_{\tilde{t},\lfloor now\rfloor,k,\tilde{k}}\right)$$
$$\leqslant \left(\sum_{\tilde{t}=\max(1,\,\lfloor now\rfloor-Max+1),\ldots,t-1} Q_{\tilde{t},k} \right) z^x_{k,\omega}, \quad (14)$$

$$\sum_{\tilde{k}=k,\ldots,K} x_{\lfloor now\rfloor,\lfloor now\rfloor,k,\tilde{k}} \leqslant L(1 - z^x_{k,\omega})$$
$$\text{for } k = 2, \ldots, K,\ \omega = 1, \ldots, \Omega. \quad (15)$$

(4) *Integrality Constraints.* For $t = 1, \ldots, N; t' = t, \ldots, N; k = 2, \ldots, K; k' = k, \ldots, K; \omega = 1, \ldots \Omega,$

$$q_{t,t',k,k'} \in \mathcal{Z}^+, \quad x_{t,t',k,k',\omega} \in \mathcal{Z}^+,$$
$$z^q_{t,k} \in \{0,1\}, \quad z^x_{k,\omega} \in \{0,1\}. \quad (16)$$

The Simulation for the Stochastic Model. The simulation using the stochastic IP model is similar to that of the basic model. The model follows the procedure described in §2.2 using the stochastic programming model instead of the deterministic IP model.

3.2. An Approximate Dynamic Programming Model

The approximate dynamic programming model solves for the maximum revenue-producing seating policy for each customer. We formulate and solve the IP under each possible seating decision for a particular customer, and the decision that results in the maximum revenue value is chosen.

Let S be a vector describing the current states of the system that can be affected by a seating decision. In particular,

$$S = (Q_{t,k}, N^s_{k,k'}) \quad \text{for}$$
$$t = \max\{1, \lfloor now\rfloor - Max + 1\}, \ldots, \lfloor now\rfloor;$$
$$k = 2, \ldots, K; k' = k, \ldots, K; s = 1, \ldots, SP. \quad (17)$$

A decision time is when a party arrives or a party exits after service completion. If an arrival of size k occurs, the following decisions are available:

(1) Do not seat the incoming party. The new state is such that: $Q_{t,k} \leftarrow Q_{t,k} + 1$.

(2) For $k' = k, \ldots, K$, seat the incoming party at a table of size k'. The new state is such that: $N^1_{k,k'} \leftarrow N^1_{k,k'} + 1$.

If a party of size k occupying a table of size k' exits from the restaurant, the following decisions are available:

(1) Do not assign the table to a party from the queue. The new state is such that: $N^{SP}_{k,k'} \leftarrow N^{SP}_{k,k'} - 1$.

(2) Assign the table to a party of size $k'' \leqslant k'$, who has been in the queue since time t''. The new state is such that: $Q_{t'',k''} \leftarrow Q_{t'',k''} - 1$, $N^1_{k'',k'} \leftarrow N^1_{k'',k'} + 1$, $N^{SP}_{k,k'} \leftarrow N^{SP}_{k,k'} - 1$.

Let u be the decision taken, so that

$$u = \begin{cases} 0, & \text{don't seat now,} \\ k', & \text{seat at a table of size } k', \end{cases} \tag{18}$$

for each of the events. Let S_u be the updated state after a decision u is taken. Let $IP(S)$ be the expected future revenue resulting from the IP model (Equations (1)–(9)) as a function of the state S.

Under an approximate dynamic programming (ADP) framework, we choose the decision u, corresponding to seating a size k party that arrived at time t, by solving

$$\max\left\{ \max_{\substack{u=k,\ldots,K \\ \text{table of size } u \text{ available}}} [R_k - \eta(u-k) + IP(S_u)], IP(S_0) \right\}. \tag{19}$$

The first term in the maximization corresponds to the expected revenue of seating the party minus a nesting cost, and the second term corresponds to the expected revenue of not seating the party. This method uses the ADP methodology by approximating the true value function (in a dynamic programming sense) by the value of the IP model.

We note that the IP in (19) need not include the fairness constraints (5)–(8) required in the previous models because ADP evaluates the value function of each party in the order of their arrival and thus ensures FCFS seating within the same party size.

3.3. Comparison Models

First-Come-First-Serve. We develop three FCFS models to compare their revenue with the revenue generated by using the above models. The FCFS model seats the customers in the order of arrival if there are tables available for them. The "Full Nesting" FCFS model incorporates full nesting of capacity, where a party of size k is allowed to sit at a size k' table for $k' \geqslant k$. If there are several possible table sizes, the model would seat them at the smallest of those tables. The "1 Up Nesting" FCFS model allows a party of size k to sit at either a table of size k or at the next largest table if size k tables are saturated. The "No Nesting" FCFS model allows no nesting. If there are no tables for a particular customer of size k, but there are tables for smaller customers that arrived after them, the model will seat those customers in order of arrival. Customers who have waited longer than *Max* will automatically leave the queue. The average of the simulated revenues over several iterations are compared to the revenue of the IPs.

Bid-Pricing Model. The bid-pricing heuristic commonly applied in airline revenue management is run as a performance benchmark. The linear programming relaxation of the basic IP model is solved and the seating decisions are made based on the difference between the immediate revenue and the sum of the dual prices corresponding to the utilized capacity corresponding to the party's stay. Suppose $p_{t,k'}$ is the dual value of the seating-capacity constraint corresponding to a table of size k' at time t. The bid price for seating a party of size k to a table of size $k' \geqslant k$ is as follows:

$$R_k - \sum_{t=\lceil now \rceil}^{\lfloor exit \rfloor - 1} p_{t,k'} - (\lceil now \rceil - now) p_{\lfloor now \rfloor, k'} - (exit - \lfloor exit \rfloor) p_{\lfloor exit \rfloor, k'}, \tag{20}$$

where $exit = now + S_k$. The term $(\lceil now \rceil - now) p_{\lfloor now \rfloor, k'}$ and $(exit - \lfloor exit \rfloor) p_{\lfloor exit \rfloor, k'}$ are to prevent overestimation of the expected stay of the customer due to the discreteness of time. $(\lceil now \rceil - now)$ is the fraction of period $\lfloor now \rfloor$ and$(exit - \lfloor exit \rfloor)$ is the fraction of period $\lfloor exit \rfloor$ that the party is expected to be in service. If there are positive bid prices, the party is seated at the table corresponding to the maximum price. Otherwise, the party is not seated.

4. MODELS WITH RESERVATIONS

The models in the previous two sections assume that the restaurant does not accept any reservations. Many high-end restaurants, however, do indeed accept reservations for their customers' convenience. Such a policy introduces several decisions which need to be addressed. For example, how much should they overbook and how should they service walk-in customers? We will incorporate reservations into our previous models by using two models: (1) a static reservation-booking (RB) model, and (2) a dynamic seat allocation model with reservations (DSAR). The static reservation-booking model is an offline model that is optimized using a stochastic gradient approach as in Karaesmen and van Ryzin (1998). The dynamic seat allocation with the reservation model is an online model solved using an ADP approach as in §3.2.

4.1. A Reservation-Booking Model

In this section, we develop a model that determines how many reservations to accept in prior days for a particular day in the future, given data regarding the expected number of reservation requests, the expected number of walk-ins, and the rates for no-shows.

As before, we assume that there are N time periods in which reservations can be accepted. We do not, however,

consider nesting of table sizes; i.e., a party of size k can only be assigned to a table of size k. Thus, the seating decisions are independent across the party sizes so that the problem can be broken down into smaller subproblems for each party size. Because we are building a planning, as opposed to operational, model in this section, we feel that this is justified. Methodologically, motivated by the work of Karaesmen and van Ryzin (1998) in a very different context, we solve the optimization problem using a steepest-descent algorithm with stochastic gradient estimation.

Data. The following are the data that we expect the restaurant to have for each party size,

$R :=$ the expected revenue of the given party size,

$p :=$ the probability that a reservation party will show up,

$ER_t :=$ the expected number of reservation requests for time t, and

$EW_t :=$ the expected number of walk-in parties that arrive at time t.

Decision Variables. The key decision is the number of reservations u_t to accept for time period t; $t = 1, \ldots, N$.

Random Variables. We define

$z_t :=$ the number of reservation parties booked for time t that show up, and

$w_t :=$ the number of walk-ins that show up at time t.

We assume that the probability of no-shows is independent and identically distributed across parties of the same size, as shown empirically by Martinez and Sanchez (1970). We further assume that z_t obeys a binomial distribution with parameters (u_t, p). We approximate this distribution for time t as a nonhomogeneous Poisson distribution of rate pu_t for ease in numerical computation. We also model w_t as a nonhomogeneous Poisson with rate EW_t for time t.

Objective Function. We maximize the following objective function $RB(\mathbf{u})$, where $\mathbf{u}$, $\mathbf{ER}$, $\mathbf{z}$, and $\mathbf{w}$ are N-dimensional vectors of elements u_t, ER_t, z_t, and w_t, respectively, $t = 1, \ldots, N$:

$$\max_{\mathbf{u} \geq \mathbf{0}} RB(\mathbf{u}) \tag{21}$$

such that

$$RB(\mathbf{u}) = E\left[V(\mathbf{z}, \mathbf{w})\right] - \theta \frac{1}{2} E\left[||\mathbf{u} - \mathbf{ER}||^2\right]. \tag{22}$$

The first term in Equation (22) corresponds to the expected maximum revenue resulting from having $\mathbf{z}$ reservation customers and $\mathbf{w}$ walk-in customers arrive on the requested date. We will refer to the term $V(\mathbf{z}, \mathbf{w})$ as the the optimal OTD (on-the-day) revenue. This value is calculated by solving a simplified version of the previously discussed seating models of §§2.1–3.2 generalized for reservations. We describe this term in further detail in the following section.

The second term is a regularizing term that discourages the decision variables from straying too far from the expected reservation requests. Without this term, the model may allocate no seats for the 6 o'clock time period and many for the 10 o'clock period, though the expected requests are mostly for 6 o'clock and hardly any are for 10 o'clock. Thus, a policy that allocates significantly more (less) seats for a particular period with few (many) reservation requests overestimates (underestimates) the possible expected revenue. The parameter $\theta > 0$ represents the trade-off between the two terms.

Static On-the-Day Model. We calculate the value of $V(\mathbf{z}, \mathbf{w})$ for a given vector $\mathbf{z}$ and $\mathbf{w}$ by solving an integer program that optimally allocates the tables to reservation and walk-in customers. The OTD model is similar to the previous models with an additional class of reservation parties. However, it does not consider nesting of party sizes and assumes that there are no queues. By making each period large enough (e.g., half an hour), it is reasonable to assume that after one period, both walk-in and reservation parties will renege. Also, most reservation requests are on the half-hour. Thus, this simplification will not significantly jeopardize the accuracy of the model. We will see that these assumptions make the problem a single-commodity maximum flow problem which aids us in the convergence analysis of the stochastic gradient algorithm.

The OTD model is also a static model that is not updated dynamically because it is solved before the day in question. It decides offline how many of the reservation and walk-in parties to seat and how many to deny service for each time period, $t = 1, \ldots, N$. We need to introduce some additional and modified notation.

Data.

$S :=$ the expected service time for the given party size,

$CostW :=$ the cost of denying service to a walk-in party,

$CostR :=$ the cost of denying service to a party with a reservation, and

$C :=$ the total capacity (number of tables) for the given party size.

We assume that the expected revenue and service-time distributions are the same for walk-in and reservation customers of the same party size. $CostW$ and $CostR$ are qualitative values of the loss of goodwill and customer dissatisfaction. $CostR$ should be large relative to R, because not being able to serve a customer with a reservation would most likely entail losing that customer and garnering a negative reputation. However, $CostW$ can be negligible because walk-in customers' expectation of being served is significantly less.

Decision Variables.

$xw_t :=$ the number of walk-in parties that are seated at time t,

$xr_t :=$ the number of reservation parties booked for time t that are seated,

$xwdeny_t :=$ the number of walk-in parties that arrive at time t that are denied service, and

$xrdeny_t :=$ the number of reservation parties booked for time t that are denied service.

Problem Formulation. Given a particular vector $\mathbf{z}$ and $\mathbf{w}$, the OTD problem is as follows:

(OTD)

$$V(\mathbf{z},\mathbf{w}) = \max \sum_{t=1,\dots,N} \big[R\cdot(xw_t + xr_t) - (CostW)\cdot xwdeny_t - (CostR)\cdot xrdeny_t\big] \quad (23)$$

subject to

$$xw_t + xwdeny_t = w_t, \quad t = 1,\dots,N, \quad (24)$$

$$xr_t + xrdeny_t = z_t, \quad t = 1,\dots,N, \quad (25)$$

$$\sum_{\tau=\max\{1,t-S+1\},\dots,t} (xw_\tau + xr_\tau) \leqslant C, \quad t = 1,\dots,N, \quad (26)$$

$$xw_t \geqslant 0, \quad t = 1,\dots,N, \quad (27)$$

$$xr_t \geqslant 0, \quad t = 1,\dots,N. \quad (28)$$

The objective value is the net revenue of seating xw_t walk-ins and xr_t reservation parties and denying service to $xwdeny_t$ walk-ins, and $xrdeny_t$ reservation parties for $t = 1,\dots,N$. Equations (24) and (25) are the demand constraints for walk-ins and reservations, respectively, for the particular realizations of demand z_t and w_t for $t = 1,\dots,N$. Equation (26) represents the capacity constraint for each time period, $t = 1,\dots,N$.

Equations (23)–(28) can be characterized as a single-commodity minimum cost flow problem; thus, the value of $V(\mathbf{z},\mathbf{w})$ can be calculated by solving the OTD problem as a linear program. It follows by the network structure of OTD and Karaesmen and van Ryzin (1998) that the function $V(\mathbf{z},\mathbf{w})$ is submodular and jointly concave with respect to z_t and w_t, $t = 1,\dots,N$, and $RB(\mathbf{u})$ is componentwise concave, continuous, and differentiable with respect to u_t, $t = 1,\dots,N$. As shown in Karaesmen and van Ryzin (1998), these properties allow convergence of the stochastic gradient algorithm described in the next section.

Stochastic Gradient Algorithm. We solve the stochastic optimization problem (21) by estimating the stochastic gradient of $RB(\mathbf{u})$ as done in Karaesmen and van Ryzin (1998). We apply this gradient to maximize $RB(\mathbf{u})$ using a method similar to the steepest descent algorithm. We first calculate

$$\frac{\partial}{\partial u_t} RB(\mathbf{u}) = \frac{\partial}{\partial u_t} E[V(\mathbf{z},\mathbf{w})] - \theta(u_t - ER_t), \quad t = 1,\dots,N. \quad (29)$$

When $z_t \sim Poisson(pu_t)$ and $w_t \sim Poisson(EW_t)$, $t = 1,\dots,N$, Karaesmen and van Ryzin (1998) show that an unbiased estimate of $\partial/\partial u_t E[V(\mathbf{z},\mathbf{w})]$ is given by

$$\frac{\partial}{\partial u_t} E[V(\mathbf{z},\mathbf{w})] = p(V(\mathbf{z}+\mathbf{e_t},\mathbf{w}) - V(\mathbf{z},\mathbf{w})), \quad t = 1,\dots,N. \quad (30)$$

The step sizes $\{b_k\}$ satisfy

$$\sum_{k=1}^{\infty} b_k = +\infty, \qquad \sum_{k=1}^{\infty} b_k^2 < \infty. \quad (31)$$

Let *MaxIt* be the maximum number of iterations we allow. The following is the stochastic gradient algorithm.

Step 0. Initialization. $k = 1$, $u_t^k = ER_t$ for $t = 1,\dots,N$.

Step 1. Generate $\nabla RB(\mathbf{u^k})$:

- Generate new vectors $z_t^k \sim Poisson(pu_t^k)$ and $w_t \sim Poisson(EW_t)$ for $t = 1,\dots,N$.
- Evaluate $V(\mathbf{z^k},\mathbf{w})$ using a network flow algorithm (for example, the network simplex algorithm).
- Evaluate $V(\mathbf{z^k}+\mathbf{e_t},\mathbf{w})$ for $t = 1,\dots,N$.
- Derive $\nabla RB(\mathbf{u^k})$ such that, for $t = 1,\dots,N$:

$$\frac{\partial}{\partial u_t} RB(\mathbf{u^k}) = p(V(\mathbf{z}+\mathbf{e_t},\mathbf{w}) - V(\mathbf{z},\mathbf{w})) - \theta(u_t - ER_t).$$

Step 2. Compute

$$u^{k+1} = Project(u^k + b_k \nabla RB(\mathbf{u^k})).$$

where $Project(\cdot)$ is the projection function to the feasible space $\mathbf{u^k} \geqslant 0$.

Step 3. If $k > MaxIt$, Exit. Else, set $k := k+1$ and return to Step 1.

THEOREM 1 (KUSHNER, CLARK, KARAESMEN, AND VAN RYZIN). *Let KT be the set of Kuhn-Tucker points of* (21). *If KT is a connected set and* $\{u^k\}$ *is the sequence determined by the previous algorithm with step sizes satisfying* (31), *then* $\{u^k\} \to KT$ *in probability as* $k \to \infty$.

The proof is given in Kushner and Clark (1978) and Karaesmen and van Ryzin (1998), Theorem 3 and Theorem 6.3.1, respectively. Kusher and Clark also show that a weaker convergence follows when KT is not a connected set.

4.2. Dynamic Seat Allocation with Reservations

The DSAR model is the same as the previous dynamic seating models of §§2.1–3.2, but with reservation customers taken into account. It takes the reservations accepted as input and determines the optimal seating policy for each arriving party given the current state of service and queue. It does not, however, update the maximum reservation-booking number produced by the RB model. As before, each time the state changes (i.e., due to a customer arrival or customer exit), the state parameters are updated and the model is continually reoptimized online. We apply the the ADP approach as in §3.2, with a slight modification in the IP formulation.

The following are additional and modified notations for the DSAR model:

Input.

$v_{t,k}$:= the number of reservations booked of size k for time t. $v_{t,k}$ is such that $v_{t,k} \leqslant u^*_{t,k}$, where $u^*_{t,k}$ is the optimal reservation booking value outputted from the RB model.

Data.

$CostQW_{t,k}$:= the cost of postponing service to a walk-in party of size k that arrived at time t and currently waiting in queue,

$CostQR_{t,k}$:= the cost of postponing service to a party of size k with reservations that arrived at time t and is currently waiting in queue,

$CostXW_{t,k}$:= the cost of postponing service to a walk-in party of size k that is expected to arrive at time t,

$CostXR_{t,k}$:= the cost of postponing service to a party of size k with reservations that is booked for time t,

p_k := the probability that a party of size k with reservations will show up,

$MaxW$:= the maximum number of periods that a walk-in party will wait,

$MaxR$:= the maximum number of periods that a reservation party will wait,

M_w := a user-defined parameter that controls the trade-off between revenue and waiting time for walk-in customers, and

M_r := a user-defined parameter that controls the trade-off between revenue and waiting time for reservation customers.

The quantities $CostQW_{t,k}$, $CostQR_{t,k}$, $CostXW_{t,k}$, and $CostXR_{t,k}$ are analogous to $CostQ_{t,k}$ and $CostX_{t,k}$ in §2.1 which are split into walk-ins and reservation customers (denoted by W and R, respectively). Similarly, $MaxW$ and $MaxR$ are analogous to Max, and M_w and M_r are analogous to M in §2.1.

State. The following are modified state parameters in addition to those described in §2.1.

$Qw_{t,k}$:= the number of size k walk-in parties currently in queue that arrived at time t,

$Qr_{t,k}$:= the number of size k reservation parties currently in queue that arrived at time t,

$Dw_{t,k}$:= the expected number of walk-in parties of size k that are going to arrive in time t who have not already arrived, and

$Dr_{t,k}$:= the expected number of reservation parties of size k that are going to arrive in time t who have not already arrived.

When $now < t$, $Dw_{t,k} = EW_{t,k}$ and $Dr_{t,k} = p_k v_{t,k}$. Each time a walk-in or reservation party of size k arrives at time t, $Dw_{t,k}$ or $Dr_{t,k}$ is decremented, respectively.

Decision Variables.

$qw_{t,t',k,k'}$:= the number of walk-in parties of size k that arrived at time t and are currently in queue, that should be seated at a size k' table at time t,

$qr_{t,t',k,k'}$:= the number of reservation parties of size k that arrived at time t and are currently in queue, that should be seated at a size k' table at time t,

$qwdeny_{t,k}$:= the number of walk-in parties of size k that arrived at time t and are currently in queue, that are not allocated a table (i.e., are not seated within $MaxW$ periods),

$qrdeny_{t,k}$:= the number of reservation parties of size k that arrived at time t and are currently in queue, that are not allocated a table (i.e., are not seated within $MaxR$ periods),

$xw_{t,t',k,k'}$:= the number of walk-in parties of size k out of $Dw_{t,k}$, that should be seated at a size k' table at time t',

$xr_{t,t',k,k'}$:= the number of reservation parties of size k out of $Dr_{t,k}$, that should be seated at a size k' table at time t',

$xwdeny_{t,k}$:= the number of walk-in parties of size k out of $Dw_{t,k}$, that are not allocated a table (i.e., are not seated within $MaxW$ periods), and

$xrdeny_{t,k}$:= the number of reservation parties of size k out of $Dr_{t,k}$, that are not allocated a table (i.e., are not seated within $MaxR$ periods).

IP Formulation. The DSAR uses a slightly modified version of the ADP model described in §3.2 due to its superior performance compared to the other models. The following describes these modifications:

Objective.

$$\begin{aligned}
\max \quad & \sum_{\substack{t=1,\ldots,\lfloor now\rfloor \\ k=2,\ldots,K \\ t'=\lfloor now\rfloor,\ldots,\min(N,t+MaxW-1) \\ k'=k,\ldots,K}} (R_k - M_w(t'-t) - \eta(k'-k))\, qw_{t,t',k,k'} \\
& + \sum_{\substack{t=1,\ldots,\lfloor now\rfloor \\ k=2,\ldots,K \\ t'=\lfloor now\rfloor,\ldots,\min(N,t+MaxR-1) \\ k'=k,\ldots,K}} (R_k - M_r(t'-t) - \eta(k'-k))\, qr_{t,t',k,k'} \\
& + \sum_{\substack{t=\lfloor now\rfloor,\ldots,N \\ k=2,\ldots,K \\ t'=t,\ldots,\min(N,t+MaxW-1) \\ k'=k,\ldots,K}} (R_k - M_w(t'-t) - \eta(k'-k))\, xw_{t,t',k,k'} \\
& + \sum_{\substack{t=\lfloor now\rfloor,\ldots,N \\ k=2,\ldots,K \\ t'=t,\ldots,\min(N,t+MaxR-1) \\ k'=k,\ldots,K}} (R_k - M_r(t'-t) - \eta(k'-k))\, xr_{t,t',k,k'} \\
& - \sum_{\substack{t=1,\ldots,\lfloor now\rfloor \\ k=2,\ldots,K}} \left(CostQW_{t,k}\ qwdeny_{t,k} + CostQR_{t,k}\ qrdeny_{t,k}\right) \\
& - \sum_{\substack{t=\lfloor now\rfloor,\ldots,N \\ k=2,\ldots,K}} \left(CostXW_{t,k}\ xwdeny_{t,k} + CostXR_{t,k}\ xrdeny_{t,k}\right).
\end{aligned} \tag{32}$$

The first four sets of summations correspond to the expected revenue, waiting-time cost, and nesting costs of seating (1) the walk-in parties currently in queue, (2) the reservation parties currently in queue, (3) the walk-in parties expected to arrive in the future, and (4) the reservation parties expected to arrive in the future, respectively. The last two sets of summations correspond to the cost of postponing service to (1) walk-in parties and reservation parties currently in queue, and (2) walk-in parties and reservation parties expected to arrive in the future, respectively.

Constraints. (1) *Demand Constraints.* The following constraints are analogous to Constraints (2) and (3) in §2.1:

$$\sum_{\substack{t'=t,\dots,\min(N,\,t+MaxW-1)\\ k'=k,\dots,K}} qw_{t,t',k,k'} + qwdeny_{t,k} = Qw_{t,k} \quad \forall\ t=1,\dots,\lfloor now\rfloor;\ k=2,\dots,K, \tag{33}$$

$$\sum_{\substack{t'=t,\dots,\min(N,\,t+MaxR-1)\\ k'=k,\dots,K}} qr_{t,t',k,k'} + qrdeny_{t,k} = Qr_{t,k} \quad \forall\ t=1,\dots,\lfloor now\rfloor;\ k=2,\dots,K, \tag{34}$$

$$\sum_{\substack{t'=t,\dots,\min(N,\,t+MaxW-1)\\ k'=k,\dots,K}} xw_{t,t',k,k'} + xwdeny_{t,k} = Dw_{t,k} \quad \forall\ t=\lfloor now\rfloor,\dots,N;\ k=2,\dots,K, \tag{35}$$

$$\sum_{\substack{t'=t,\dots,\min(N,\,t+MaxR-1)\\ k'=k,\dots,K}} xr_{t,t',k,k'} + xrdeny_{t,k} = Dr_{t,k} \quad \forall\ t=\lfloor now\rfloor,\dots,N;\ k=2,\dots,K, \tag{36}$$

(2) *Seating-Capacity Constraints.* The following constraint is analogous to the (4) in §2.1 with reservation parties:

$$\sum_{\substack{k=2,\dots,k'\\ t'\in T(t,k)}} \Bigg(\sum_{t=\max(1,\,t'-MaxW+1),\dots,\lfloor now\rfloor} qw_{t,t',k,k'} + \sum_{t=\max(1,\,t'-MaxR+1),\dots,\lfloor now\rfloor} qr_{t,t',k,k'} + \sum_{t=\max(\lfloor now\rfloor,\,t'-MaxW+1),v\dots,t'} xw_{t,t',k,k'} + \sum_{t=\max(\lfloor now\rfloor,\,t'-MaxR+1),\dots,t'} xr_{t,t',k,k'} \Bigg) + \sum_{\substack{k=2,\dots,k'\\ s=1,\dots,SP}} I_N(\tau) \leqslant c_{k'} \quad \forall\ \tau=\lfloor now\rfloor,\dots,N;k'=2,\dots,K \tag{37}$$

where $T(t,k')$ and $I_N(\tau)$ are as in (4).

(3) *Integrality Constraints.* For $t=1,\dots,N;\ t'=t,\dots,N;\ k=2,\dots,K;\ k'=k,\dots,K$,

$$qw_{t,t',k,k'},\quad qr_{t,t',k,k'},\quad xw_{t,t',k,k'},\quad xr_{t,t',k,k'},$$
$$qwdeny_{t,k},\quad qrdeny_{t,k},\quad xwdeny_{t,k},\quad xrdeny_{t,k} \in \mathcal{Z}^+.$$

Incorporating the ADP Model. In the DSAR model, the state vector S is characterized by

$$S=(Qw_{t_w,k}, Qr_{t_r,k}, N^s_{k,k'}) \quad \text{for} \tag{38}$$
$$t_w=\max(1,\lfloor now\rfloor-MaxW+1),\dots,\lfloor now\rfloor,$$
$$t_r=\max(1,\lfloor now\rfloor-MaxR+1),\dots,\lfloor now\rfloor,$$
$$k=2,\dots,K;\ k'=k,\dots,K;\ s=1,\dots,SP.$$

The service state parameter $N^s_{k,k'}$ remains the same as in §3.2.

There are two types of arrivals: reservation customer arrivals and walk-in arrivals. There is, however, no distinction between reservation and walk-in service completions. Thus, the decision times are when there is a reservation party arrival, walk-in arrival, and a customer service completion. The decisions available at each event are illustrated below:

- Reservation arrival at time t of size k:
  (1) Do not seat the incoming reservation party. The new state is such that: $Qr_{t,k} \leftarrow Qr_{t,k}+1$.
  (2) For $k'=k,\dots,K$, seat the incoming party at a table of size k'. The new state is such that: $N^1_{k,k'} \leftarrow N^1_{k,k'}+1$.
- Walk-in arrival at time t of size k:
  (1) Do not seat the incoming walk-in party. The new state is such that: $Qw_{t,k} \leftarrow Qw_{t,k}+1$.
  (2) For $k'=k,\dots,K$, seat the incoming party at a table of size k'. The new state is such that: $N^1_{k,k'} \leftarrow N^1_{k,k'}+1$.
- Party of size k exits table for k' at time t:
  (1) Do not assign the table to a party from the queue. The new state is such that: $N^{SP}_{k,k'} \leftarrow N^{SP}_{k,k'}-1$.
  (2) Assign the table to a reservation party of size $k'' \leqslant k'$, who has been in the queue since time t''. The new state is such that: $Qr_{t'',k''} \leftarrow Qr_{t'',k''}-1$, $N^1_{k'',k'} \leftarrow N^1_{k'',k'}+1$, $N^{SP}_{k,k'} \leftarrow N^{SP}_{k,k'}-1$.
  (3) Assign the table to a walk-in party of size $k'' \leqslant k'$, who has been in the queue since time t''. The new state is such that: $Qw_{t'',k''} \leftarrow Qw_{t'',k''}-1$, $N^1_{k'',k'} \leftarrow N^1_{k'',k'}+1$, $N^{SP}_{k,k'} \leftarrow N^{SP}_{k,k'}-1$.

Finally, the DSAR model uses the objective value of the *IP* described by Equations (32)–(38) for $IP(S)$ in (19).

Comparison Model

First-Come-First-Serve Model with Reservations. We incorporate reservation customers into the FCFS model in §3.3, which uses a heuristic to seat walk-in parties within reservations by taking the optimal reservation-booking data output from the RB model of §4.1. When a walk-in party arrives, the model will check whether seating them would take away a table from any outstanding reservations booked within a 15-minute (1 period) interval of the current time. The three different nesting models (Full Nesting, 1 UP Nesting, and No Nesting), as described in §3.3, are tested.

5. COMPUTATIONAL RESULTS FOR MODELS WITHOUT RESERVATIONS

In this section, we present the performance of the nonreservation models of §2 and 3 on simulated data.

5.1. Data

The test data for the capacity, service time, demand, and revenue are taken from a contrived restaurant. The data is constructed from its dinner-time operation, which runs from 6 pm to 10 pm. We divide this time into 16 equal periods of 15-minute durations.

Table 1. Expected duration (in minutes) of service phases.

	Party Size			
Phase	2	4	6	8
1	6	9	12	18
2	39	45	57	75
3	6	6	8	9
Total	51	60	77	102

Capacity Data. This is a small-scale restaurant with four tables for two, two tables for four, one table for six, and two tables for eight. The restaurant allows nesting of the capacity, i.e., a party of two can be seated at a table of two, four, six, or eight.

Service Time Data. The meal duration is split up into three phases: appetizer (phase 1), entrée (phase 2), and coffee and dessert (phase 3).[2] The expected service durations are illustrated in Table 1. For this example, we have in mind a restaurant with faster than usual turnover time.

Demand Data. The restaurant does not accept reservations. We have tested the various methods for three levels of demand; low, medium, and high with average load factors 0.68, 0.93, and 1.54.[3] Each demand level is split up into two demand distributions: constant, where all parties arrive uniformly throughout the day, and varied, where the larger parties arrive mainly in the later part of the evening.[4] We simplify the data so that there are only four possible types of customers: parties of sizes two, four, six, and eight. We simulate the customer arrivals as a nonhomogeneous Poisson process with rate $\lambda(t, k) :=$ expected demand of size k customers at time t.

Revenue Data. The expected revenue for parties of sizes two, four, six, and eight are \$50, \$120, \$210, and \$320, respectively. We simplify the revenue function so that it is time invariant.

5.2. Algorithms Tested and Parameter Settings

Using the above data, we tested the following algorithms: the FCFS models (FullNest, 1Up, and NoNest), the bid-pricing model (BidP), the basic integer programming model (IP), the stochastic programming model using three scenarios (STOCH), and the approximate dynamic programming model (ADP). We used CPLEX to solve the optimization models. The models were run on Dell Pentium II workstation operating under LINUX.

Parameter Settings. For the STOCH model, we used a three-scenario model (i.e., $\Omega = 3$) in which one of the scenarios is the expected demand and the other two are randomly generated. We assign the probability of 0.5 to the expected demand scenario and the probability of 0.25 to each of the generated scenarios. We tested models with larger Ω and with variations in the scenario probability, but the significant increase in the computation time was not worth the small increase in the average revenue.

The value of M is set to 5 for all of the models. After running the models for different values of M, $M = 5$ produced the highest revenue, on average, for most of the models. Setting this value too high makes the model averse to seating customers that have been waiting in the queue for a long time. When M is set to zero, the model would give no consideration to waiting time when solving for the optimal solution. For values of M between 0 and 5, the resulting average revenue actually increases because the model is forced to seat a customer at a table which it was reserving for a future customer. This may be beneficial because the model sometimes incorrectly forecasts future demand and keeps tables idle when they could have been used.

The appropriate values for η seem to vary according to the model and the demand level. For the IP and STOCH model we set $\eta = 4$, and for ADP we set $\eta = 0.25$. These values were chosen from empirical testing, thus they may not be the optimal. However, the differences in revenue and average waiting time were not significant for slight changes in η.

The value for Max is set to 3 for all models; thus we are assuming customers do not wait for more than 45 minutes. The models AUTOMATICALLY EXIT customers who have been waiting for more than three periods.

For the IP and STOCH model, the values of $CostQ_{t,k}$ are 2.5 for $k = 2$, 6.0 for $k = 4$, 10.5 for $k = 6$, and 16.0 for $k = 8$, $\forall t$. $CostX_{t,k}$ when $t = \lfloor now \rfloor$ are 0.5 for $k = 2$, 1.2 for $k = 4$, 2.1 for $k = 6$, and 3.2 for $k = 8$, and when $t > \lfloor now \rfloor$, $CostX_{t,k}$ is set to 0 for all k. The ADP model performed better with significantly higher values of $CostQ_{t,k}$ and $CostX_{t,k}$ than IP and STOCH. Thus, these costs for ADP were set to 10 times that of IP and STOCH.

Appropriate values for these parameters are clearly restaurant dependent. They would depend on the demand level and characteristics, expected revenue, expected service time, capacity, and waiting-time behavior of the customers of each restaurant. We suggest testing for the right values for these parameters by simulation, using the data and characteristics of each restaurant.

5.3. Results

Table 2 contains the average daily revenue, average waiting time per customer, and the percentage of customers served for all the algorithms we tested. Each subtable corresponds to a demand scenario, low and constant, low and varied, medium and constant, medium and varied, high and constant, and high and varied. Table 3 contains the average run times per party for each model.

For smaller load factors, Full Nesting is better than the other FCFS models and performs similarly to the IP, in general. This implies that the phenomenon that the IP captures to increase revenue for small load factors is nesting. The No Nesting model loses revenue by unnecessarily saving large tables for large parties. As demand level increases,

Table 2. Revenue, average wait, and percent served resulting from static capacity models.

	FullNest	1Up	NoNest	BidP	IP	STOCH	ADP
Load = 0.68 Constant							
Revenue ($)	2,351.94	2,390.32	2,125.46	2,328.10	2,354.46	2,375.92	2,401.56
% Difference	0.00%	1.63%	−9.63%	−1.01%	0.11%	0.98%	2.11%
Average Wait (min)	5.0	5.3	10.7	6.0	5.7	5.7	4.9
% Served	93.23%	93.08%	83.25%	90.89%	91.81%	91.94%	93.67%
Load = 0.68 Varied							
Revenue ($)	2,066.54	2,031.18	1,883.90	1,997.86	2,087.14	2,077.30	2,112.34
% Difference	0.00%	−1.71%	−8.84%	−3.32%	1.00%	0.52%	2.22%
Average Wait (min)	7.7	7.5	13.1	6.0	8.3	7.8	7.5
% Served	88.06%	88.11%	78.52%	90.89%	86.51%	87.35%	88.58%
Load = 0.93 Constant							
Revenue ($)	2,964.62	2,928.98	2,702.36	2,822.12	2,976.84	2,969.50	3,034.18
% Difference	0.00%	−1.20%	−8.85%	−4.81%	0.41%	0.16%	2.35%
Average Wait (min)	9.9	9.8	14.4	11.3	11.1	10.4	9.9
% Served	87.82%	87.69%	78.30%	83.35%	85.48%	86.26%	87.84%
Load = 0.93 Varied							
Revenue ($)	2,624.94	2,596.36	2,391.00	2,430.18	2,610.06	2,651.06	2,702.71
% Difference	0.00%	−1.09%	−8.91%	−7.42%	−0.57%	1.00%	2.96%
Average Wait (min)	10.8	10.4	15.9	12.6	10.8	11.3	10.5
% Served	83.16%	83.96%	75.35%	78.22%	82.71%	82.08%	83.31%
Load = 1.54 Constant							
Revenue ($)	3,409.82	3,467.66	3,498.8	3,203.10	3,676.74	3,708.76	3,857.36
% Difference	0.00%	1.70%	2.61%	−6.06%	7.83%	8.77%	13.13%
Average Wait (min)	12.3	24.2	25.9	23.7	23.7	24.0	22.9
% Served	68.84%	68.70%	60.36%	57.85%	65.65%	64.02%	68.96%
Load = 1.54							
Revenue ($)	3,146.76	3,154.98	3,051.06	2,902.52	3,393.36	3,387.42	3,545.40
% Difference	0.00%	0.26%	−3.04%	−7.76%	7.84%	7.65%	12.67%
Average Wait (min)	24.0	23.7	27.5	24.3	24.0	23.7	23.4
% Served	67.83%	68.50%	57.16%	56.77%	64.25%	64.33%	66.56%

the nesting decisions become more complex. This explains the decrease in the revenue gap across the FCFS models with higher demand.

We observe that increasing the sophistication of the models results in monotonically increasing revenue. There is a marginal revenue improvement of using stochastic programming versus the deterministic IP. The ADP model outperforms the deterministic and stochastic model in all demand scenarios, with about 2% improvement from FCFS in low and medium load factors and 12% improvement in high load factors in revenue.

We also observe that the models do not sacrifice waiting time for higher revenue. The optimization models had comparable waiting times to the FCFS models, and in most of the larger-load cases had lower waiting time than the FCFS. Thus, higher revenue was achieved without any sacrifices and some improvements in the average waiting time. When examining the waiting time for each party size separately, we see that the optimization models have significantly lower waiting times for parties of sizes six and eight, while slightly higher for parties of two compared to the FCFS models. Thus, our models have a smaller range of waiting times across party sizes.

Table 3. Run time per party in seconds for static capacity models.

	FCFS	BidP	IP	STOCH	ADP
Average Run Time (sec)	0.00	0.67	0.21	0.66	1.07

In addition, IP and STOCH have a lower percentage of parties served than the best performing FCFS models, while producing higher revenue. **Overall, the ADP model seems to be the best performing method: It serves about the same percentage of parties as the FCFS models, does not increase and occasionally decreases waiting time, and produces significantly higher revenue.** This implies that the optimization models are able to seat more of the "right" (higher-revenue-producing) customers. The run times are also in a practical range for all of the models. Thus, any of these models can be run online with a POS system.

6. COMPUTATIONAL RESULTS FOR RESERVATION MODELS

In this section, we report computational results for the models with reservations. We first run the static RB model to decide a priori how many reservations to accept, and we then run the DSAR model.

6.1. Data

The test data was taken from *Soto's*, a Japanese restaurant in Atlanta, Georgia (Kosugi 1999). Similar to the previous data set, the data are taken from its dinner-time operations

Table 4. Revenue, percent served, and average waiting time of reservation models for demand level 90.

Demand = 90	FullNest	1Up	NoNest	DSAR
Revenue ($)	6,944.68	6,917.18	6,777.02	7,182.20
% Difference	0.00%	−0.40%	−2.41%	3.42%
% Reservation Served	95.96%	95.95%	96.02%	97.97%
Average Wait Reservation (min)	3.0	3.2	3.3	4.0
% Walk-in Served	81.19%	80.90%	79.07%	85.02%
Average Wait Walk-in (min)	11.1	11.3	12.3	8.6

of 16 periods, from 6 pm to 10 pm. The service time and revenue data are also identical to that of §5.1.

Capacity. *Soto's* has many small tables that can be put together to accommodate large parties. For the purpose of our model, we assume that the restaurant takes only one table configuration. In this configuration, *Soto's* has 16 tables for two, 7 tables for four, 3 tables for six, and 1 table for eight. We allow nesting of capacity as before.

Demand Data. *Soto's* gets a total of around 90 customers on weekdays and 120 to 130 customers on weekends. We test the models on these two demand levels, with corresponding loads of 0.93 and 1.24, respectively. Around 30% of these customers are reservation customers with a no-show rate of 3% to 15%. We use a constant no-show rate of 10%. Out of the walk-in parties, 55% are of size two, 30% are of size, four and 15% are of size six. Out of the reservation parties, 40% are of size two, 43% are of size four, 10% are of size six and 7% are of size eight. The distribution of reservation customers throughout the day is as follows: 20% during 6 pm to 7 pm, 40% during 7 pm to 8 pm, 30% during 8 pm to 9 pm, and 10% during 9 pm to 10 pm. The distribution of walk-in customers is as follows: 30% during 6 pm to 7 pm, 35% during 7 pm to 8 pm, 25% during 8 pm to 9 pm, and 10% during 9 pm to 10 pm.

6.2. Parameter Settings

We use the following values for $CostQW_{t,k}$: 2.5 for $k = 2$, 6.0 for $k = 4$, 10.5 for $k = 6$, and 16.0 for $k = 8$, $\forall t$. The values for $CostQR_{t,k}$ are 150 for $k = 2$, 300 for $k = 4$, 500 for $k = 6$, and 700 for $k = 8$, $\forall t$. Distinction for the values for both $CostXW_{t,k}$ and $CostXR_{t,k}$ for $t = \lfloor now \rfloor$ are set higher than for $t > \lfloor now \rfloor$. This implies that parties expected to arrive in the current period are given more priority than those expected to arrive later because the state of the distant future is more uncertain than the near future. The values for $CostXW_{t,k}$ when $t = \lfloor now \rfloor$ are 0.05 for $k = 2$, 0.12 for $k = 4$, 0.21 for $k = 6$, and 0.32 for $k = 8$. When $t > \lfloor now \rfloor$, the values are set to 0 for all k. The values for $CostXR_{t,k}$ when $t = \lfloor now \rfloor$ are 101 for $k = 2$, 241 for $k = 4$, 421 for $k = 6$, and 641 for $k = 8$. When $t > \lfloor now \rfloor$, the values are 100 for $k = 2$, 240 for $k = 4$, 420 for $k = 6$, and 640 for $k = 8$.

The value of M_r was set to 8 and M_w was set to 3, reflecting higher cost for keeping reservation customers waiting η was set to 0.5. *MaxR* was set to 4 and *MaxW* was set to 2, which reflects the customer behavior at *Soto's*.

6.3. Computational Results

The average revenue, percentage of customers served, and average waiting time for reservation and walk-in customers are illustrated in Tables 4 and 5. Table 4 uses the demand data of 90 customers and Table 5 uses the demand data of 120 customers. In the low-demand scenario of 90 customers, the DSAR outperforms all of the FCFS models by 3.5% to 6.9%. The DSAR also serves a larger percentage of both reservation and walk-in customers than the FCFS models. The average wait for reservation parties is slightly higher for the DSAR, but 0.27 periods (4.05 minutes) is still a reasonable length of wait. The average wait for walk-in customers is lowest using the DSAR. The results for 120 customers are similar. The DSAR outperforms the FCFS model by 6.43% to 8.29%. It again has the best percentage seated for both the reservation and walk-in customers. It also has the highest average waiting time (0.40 periods, or 6 minutes) for reservation parties and the lowest average waiting time for walk-in parties. Thus, the DSAR produces more revenue and serves more customers than FCFS

Table 5. Revenue, percent served, and average waiting time of reservation models for demand level 120.

Demand = 120	FullNest	1Up	NoNest	DSAR
Revenue ($)	8,210.70	8,274.82	8,132.2	8,806.60
% Difference	0.00%	0.78%	-0.96%	7.26%
% Reservation Served	94.57%	94.42%	93.92%	97.39%
Average Wait Reservation (min)	3.6	3.75	4.2	6.0
% Walk-in Served	53.97%	53.75%	50.39%	65.83%
Average Wait Walk-in (min)	25.4	25.5	26.7	19.5

for both low and high demands. The results also imply that the DSAR has a higher revenue impact with higher demand.

7. SUMMARY AND CONCLUDING REMARKS

We feel we gained the following insights from the computational study:

(1) For models without reservations, optimization-based strategies outperform FCFS-based strategies for all low and medium load factors and significantly for high load factors. Somewhat surprisingly, optimization-based strategies do not adversely affect the service quality (waiting times either remain unchanged or decrease somewhat, while FCFS is maintained within parties of the same size).

(2) Increasing the sophistication in the models results in higher revenue without sacrificing waiting time. We believe that the performance of the ADP model represents the best trade-off between maximizing revenue and maintaining low average waiting time and run time.

(3) The reservation models we propose (using a stochastic gradient approach to decide the reservations a priori, and ADP to implement it online) result in a significant improvement relative to the FCFS models for both low and high demand levels. The RB and DSAR models result in both higher revenue and lower customer attrition.

(4) Overall, we feel that optimization-based models have a role to play in restaurant revenue management.

There are many areas for future research:

(1) Extending our model to support dynamic capacity—that is, allowing restaurants to move their tables around to better accommodate the demand at each time.

(2) Incorporating balking and reneging.

(3) Further empirical testing; this might be facilitated by combining algorithms from this paper with online restaurant reservation providers.

ENDNOTES

1. In the language of queueing theory, *reneging* is when a customer prematurely leaves the restaurant, after waiting in line, before receiving any service.

2. The probability distribution of the length of each phase for each party size is approximated by a discrete distribution illustrated in an online appendix.

3. The load factor ρ_k corresponding to party size k was calculated as $\rho_k = \bar{\lambda}_k S_{k.}/\bar{c}(k)$, where $\bar{\lambda}_k :=$ the expected rate of arrival of size k parties, $S_{k.} :=$ the expected service time of size k customers, and $\bar{c}(k) :=$ the average number of tables of size k over all three configurations.

4. The online appendix contains an illustration of the expected demand for each period and party size corresponding to each of the demand scenarios (http://or.pubs.informs.org/Pages/collect.html/).

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