

# Daniel E. Brown

R&D ENGINEER · RESEARCHER

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*Determined, creative and inquisitive engineer who is a very resourceful team player, always prepared to apply academic knowledge to solve real world problems. Able to visualize potential solutions virtually, armed with an abundance of hands-on and practical knowledge. New and interesting projects can't come soon enough.*

## Experience

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### Perception Engineer

Cambridge, Massachusetts

AURORA FLIGHT SCIENCES

Jul. 2018 - Present

- Developing aircraft-based perception and sensing systems for non-cooperative detect and avoid applications.

### Research Specialist - Instrumentation Engineer

Cambridge, Massachusetts

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

May. 2014 - May. 2018

- Conceived, prototyped, built and tested compact automotive data logging platform to capture sensor data via different sources including CANbus data, GPS, IMU, audio and high definition video. Hands-on instrumentation of over 28 vehicles, including 21 Tesla.
- Primary focus on automotive safety systems research using semi-autonomous driving features, data collection and analysis. Hands-on experience building and integrating intelligent systems into Tesla, Volvo, Toyota, Jaguar Land Rover, Mercedes, Ford and GM vehicles.
- Assisted subject data collection in laboratory, simulation, field, and naturalistic experiments. Performed data analysis using Python, OpenCV, and R on large scale data sets stored as flat file and SQL databases. Created technical documentation for instrumentation installations. Formed and executed test plans, and assisting with the development of experimental protocols.

### Undergraduate Research, Metallurgy Lab

Amherst, MA

UNIVERSITY OF MASSACHUSETTS – AMHERST

Dec. 2012 - May. 2013

- Conducted research in laboratory of Professor Joseph Goldstein, performing metallurgical experiments to form the Tetrataenite phase of Iron-Nickel found in meteorites
- Set up, calibrated, measured output from heat furnaces. Gained knowledge of grinding, polishing and etching techniques for use in optical microscopy and spectroscopy.

### NeoGraft Technologies, Inc.

Taunton, Massachusetts

INTERN

Jul. 2012 - Sept. 2012

- Performed experiments collecting and evaluating data using scanning electron microscopy (SEM) and force testers on electrospun polycaprolactone biodegradable polymer coatings on large animal model veins for coronary bypass surgery.
- Assisted senior engineers in conceiving designs and building specialty electrical and electromechanical assemblies to add functionality, value and analytical capability to process instruments.

## Education

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### University of Massachusetts Amherst

Amherst, Massachusetts

B.S. IN MECHANICAL ENGINEERING

Graduated May 2013

- SAE Supermileage Vehicle Competition
- Metallurgy Lab Technician/Research Assistant

## Projects

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### MIT \$100K Business Plan Competition

Cambridge, Massachusetts

VELOAI

Jan. 2016 - May. 2016

- Computer vision based bicycle safety system (ABAS)
- Using 2 cameras, GPS, IMU and other sensors, VeloAI detects threats such as potholes, opening car doors, turning vehicles, pedestrians, dangerous intersections and warns the rider.
- Advanced to the semi-final round of 15 other startups. Awarded \$1000 in project funding.

## Society of Automotive Engineers Supermileage Vehicle Competition

Amherst, Massachusetts

SUB-GROUP CAPTAIN-"OLD" BODY TEAM

Sept. 2012 - May. 2013

- Leading team of 5 students to improve upon the previous years' car design of body, power transmission.
- Searched areas for which losses are present, lessening losses at wheel bearings, aerodynamic profile for increased fuel mileage.
- Placed 4<sup>th</sup> of 28 universities with 1010mpg, a almost 20% increase from the prior years' fuel mileage.

## Skills

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**Programming/Software** Python, R, Linux, LaTeX, Solidworks, Matlab, MathCAD, ANSYS, EagleCAD

**Other** Electronics, CANbus, Force testers, SEM, Lean Yellow Belt

## Publications

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MIT AUTONOMOUS VEHICLE TECHNOLOGY STUDY: LARGE-SCALE DEEP LEARNING BASED ANALYSIS OF DRIVER BEHAVIOR AND INTERACTION WITH AUTOMATION

Fridman, Brown, Glazer, Angell, Dodd, Jenik, et al.. Under Review, 2018

ROAD CURVATURE WITH TESLA AUTOPILOT: DIFFERENCE IN APPROACH BETWEEN HUMAN AND MACHINE

Brown, Fridman, Kindelsberger, Glazer, Reimer Under Review, 2018

COMPARING NEAR-INFRARED AND VISIBLE LIGHT FOR GAZE ESTIMATION IN THE WILD

Brown, Fridman, Angell, Reimer. In preparation, 2017

OBSERVED DIFFERENCES IN LANE DEPARTURE WARNING RESPONSES DURING SINGLE-TASK AND DUAL-TASK DRIVING: A SECONDARY ANALYSIS OF FIELD DRIVING DATA

McWilliams, Brown, Reimer, Mehler, Dobres. SAE Technical Papers, 2016

DETECTING ROAD SURFACE WETNESS FROM AUDIO: A DEEP LEARNING APPROACH

Abdić, Fridman, Marchi, Brown, Angell, Reimer, Schuller. In IEEE Signal Processing, 2016

AUTOMATED SYNCHRONIZATION OF DRIVING DATA USING VIBRATION AND STEERING EVENTS

Fridman, Brown, Angell, Abdić, Reimer, Young Noh. In Pattern Recognition Letters, 2016

AN ON-ROAD STUDY INVOLVING TWO VEHICLES: OBSERVED DIFFERENCES BETWEEN AN AUDITORY AND HAPTIC LANE DEPARTURE WARNING SYSTEM

Brown, Reimer, Mehler, Dobres. 2015 International Conference on Automotive User Interfaces and Interactive Vehicular Applications, Nottingham, UK 2015

## Interests and Activities

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- Teaching assistant for the MIT IAP course 6.S094 Deep Learning for Self-Driving Cars and 6.S099 Artificial General Intelligence
- Licensed amateur "HAM" radio operator, Technician class
- Participated in SAE-Supermileage Vehicle competition, placed 4<sup>th</sup> with 1010MPG, Member of UMass Motorsport Club, active in Hillel House organization and charitable fund raising.
- Executed major repairs to automotive systems of various brands, and many electro-mechanical systems.
- Built NIXIE tube clock with components from Cold War era international sources.
- Member of open source community for ECU development and exploration.