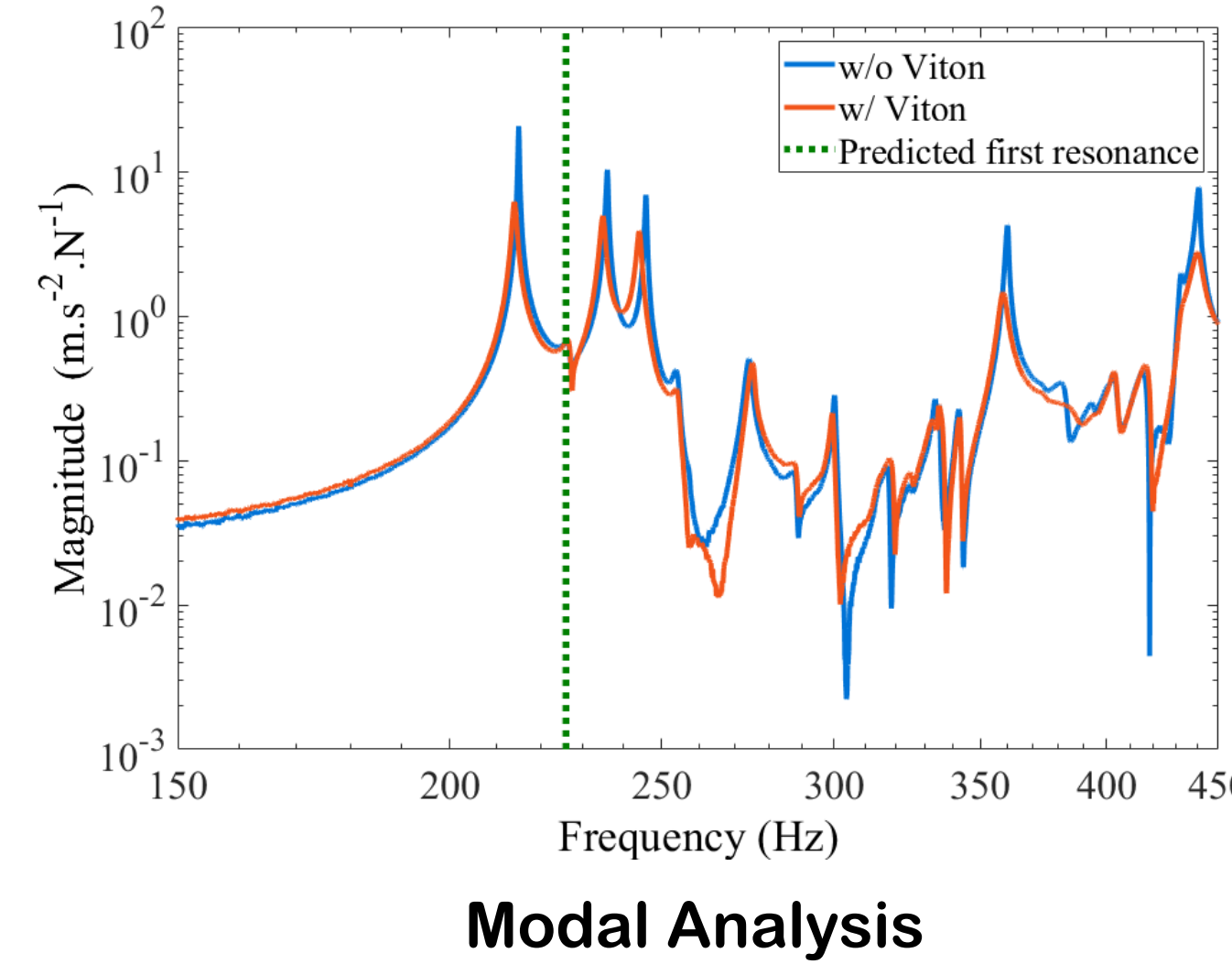
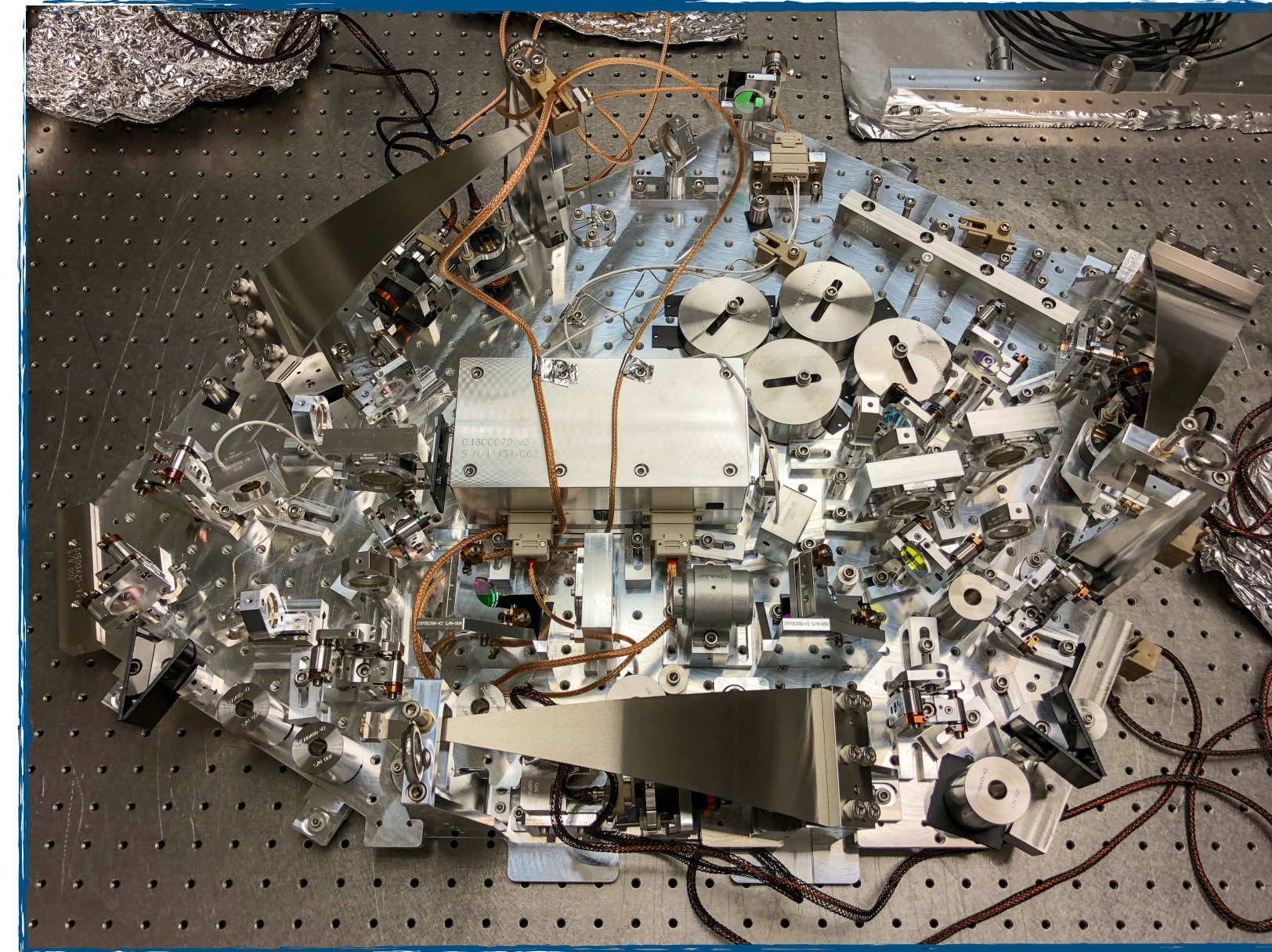


# Overview of a Tabletop Active Vibration Isolation System for Ultra-High Vacuum Optical Experiments

Álvaro Fernández Galiana\*, Fabrice Matichard and the LIGO squeezing team

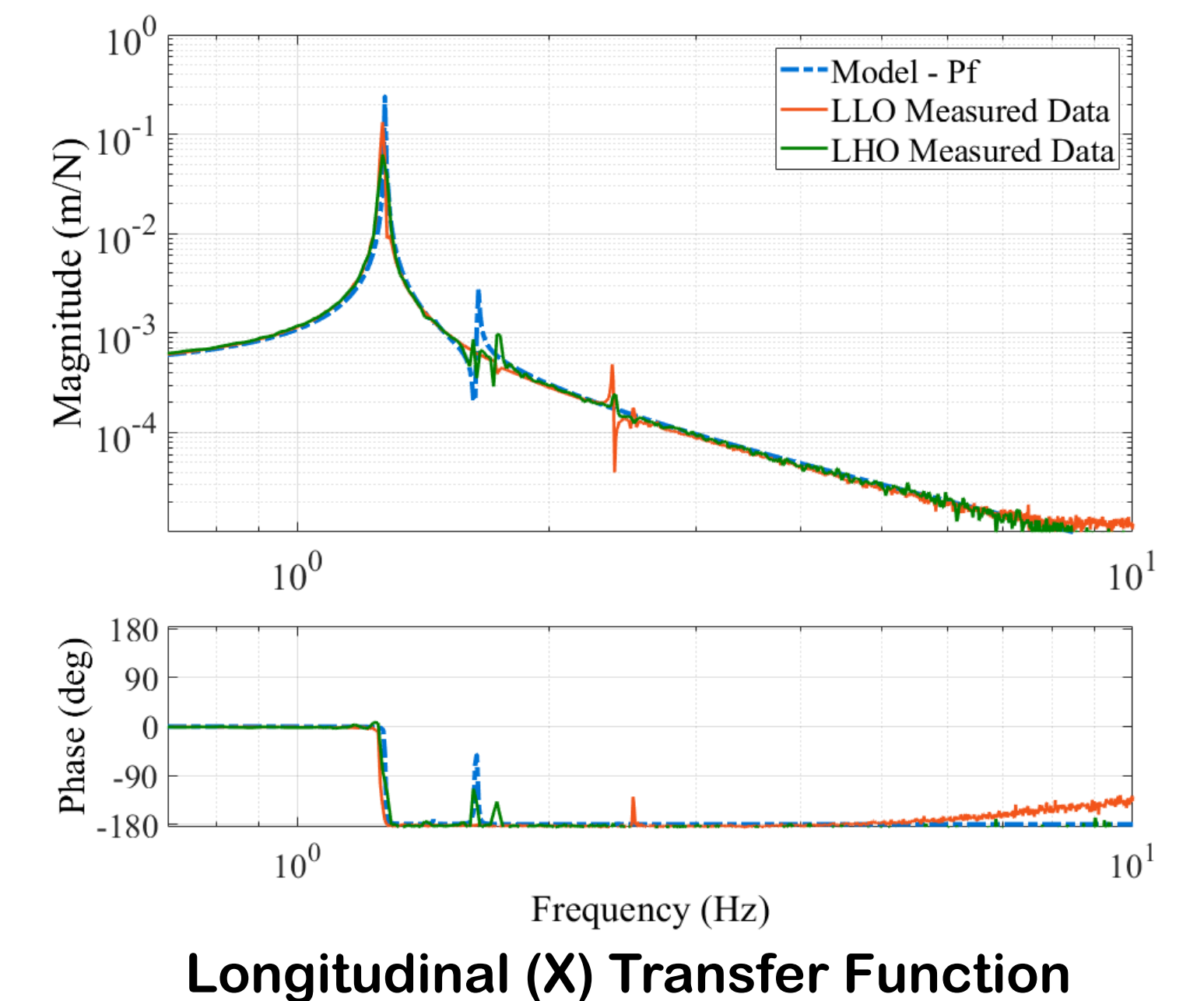
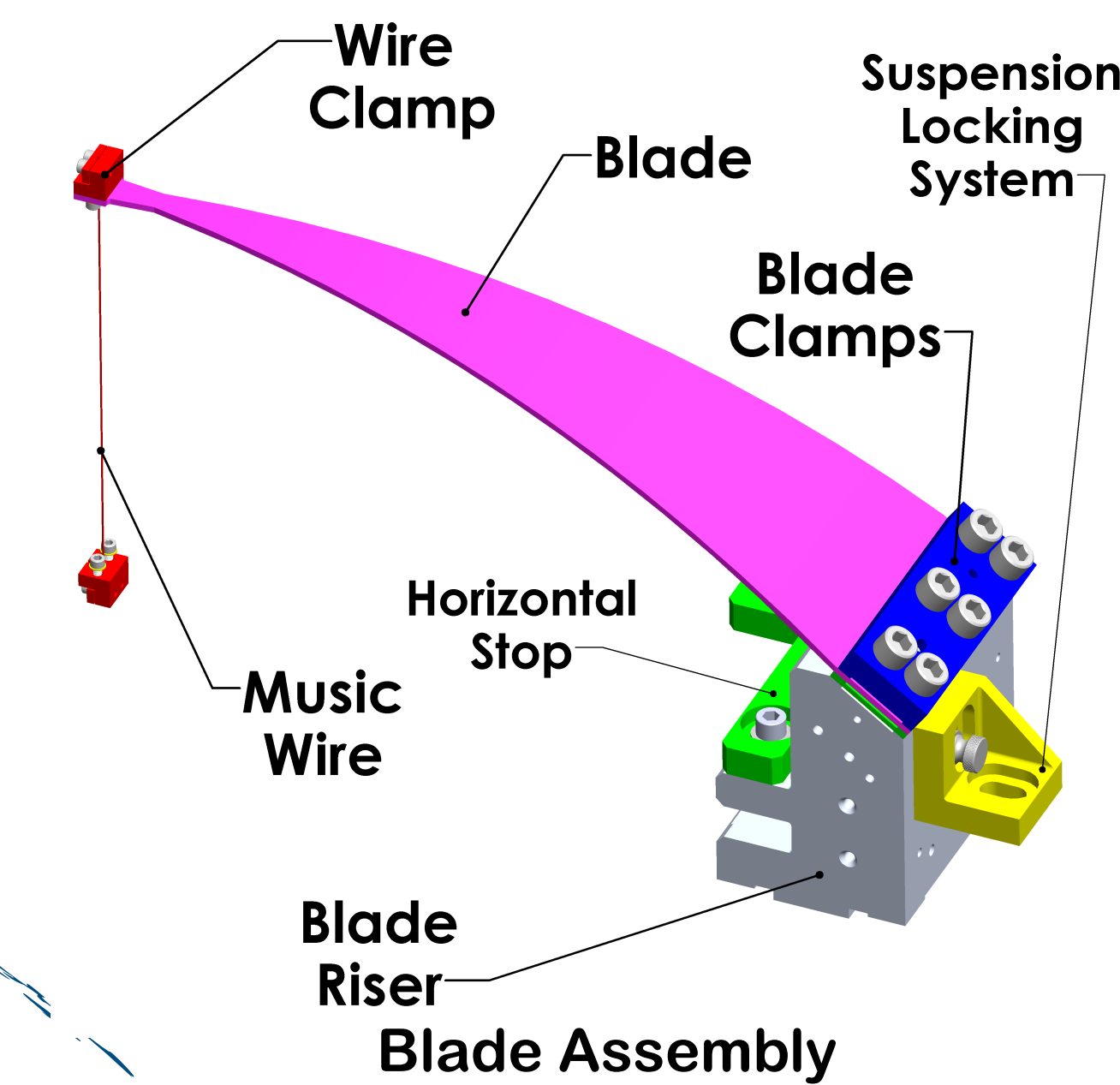
\*alvarofg@mit.edu

Massachusetts Institute of Technology, Cambridge, MA, USA



- >50dB @ 100Hz
- Large isolation bandwidth

- $f^2$  isolation
- Highly accurate model



- ▶ Total mass: 48 kg
  - Suspended: 36 kg
  - Payload: 8-14 kg
- ▶ Dimensions: 27x37x8 in [94x67x21 cm]
- ▶ Suspended stage:
  - Surface: 540 in<sup>2</sup> [0.34 m<sup>2</sup>]
  - Height: 1.5 in [3.8 cm]
- ▶ Resonance Q-factors:
  - 20 (damped) / 300 (undamped)
- ▶ UHV compatible

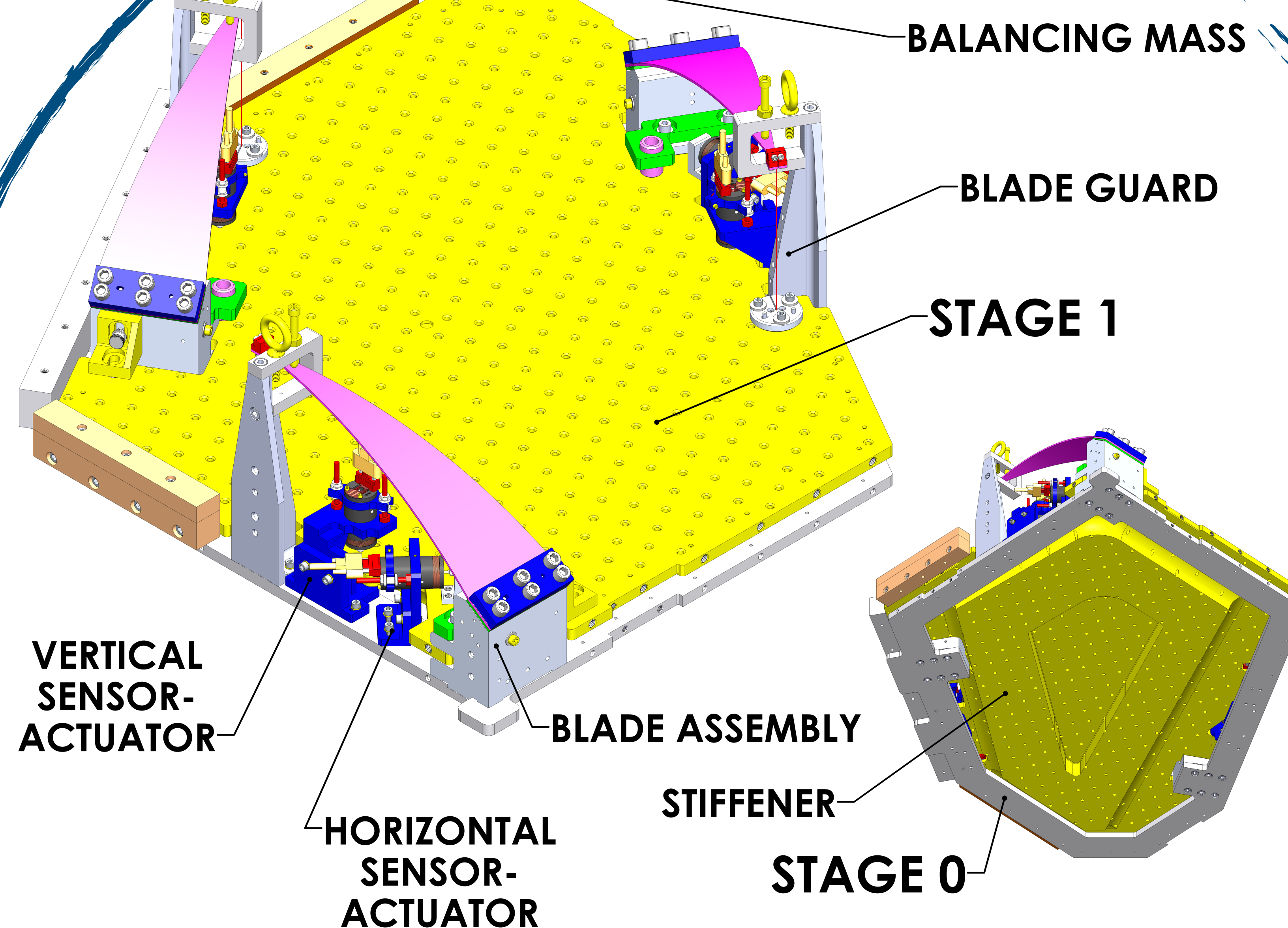
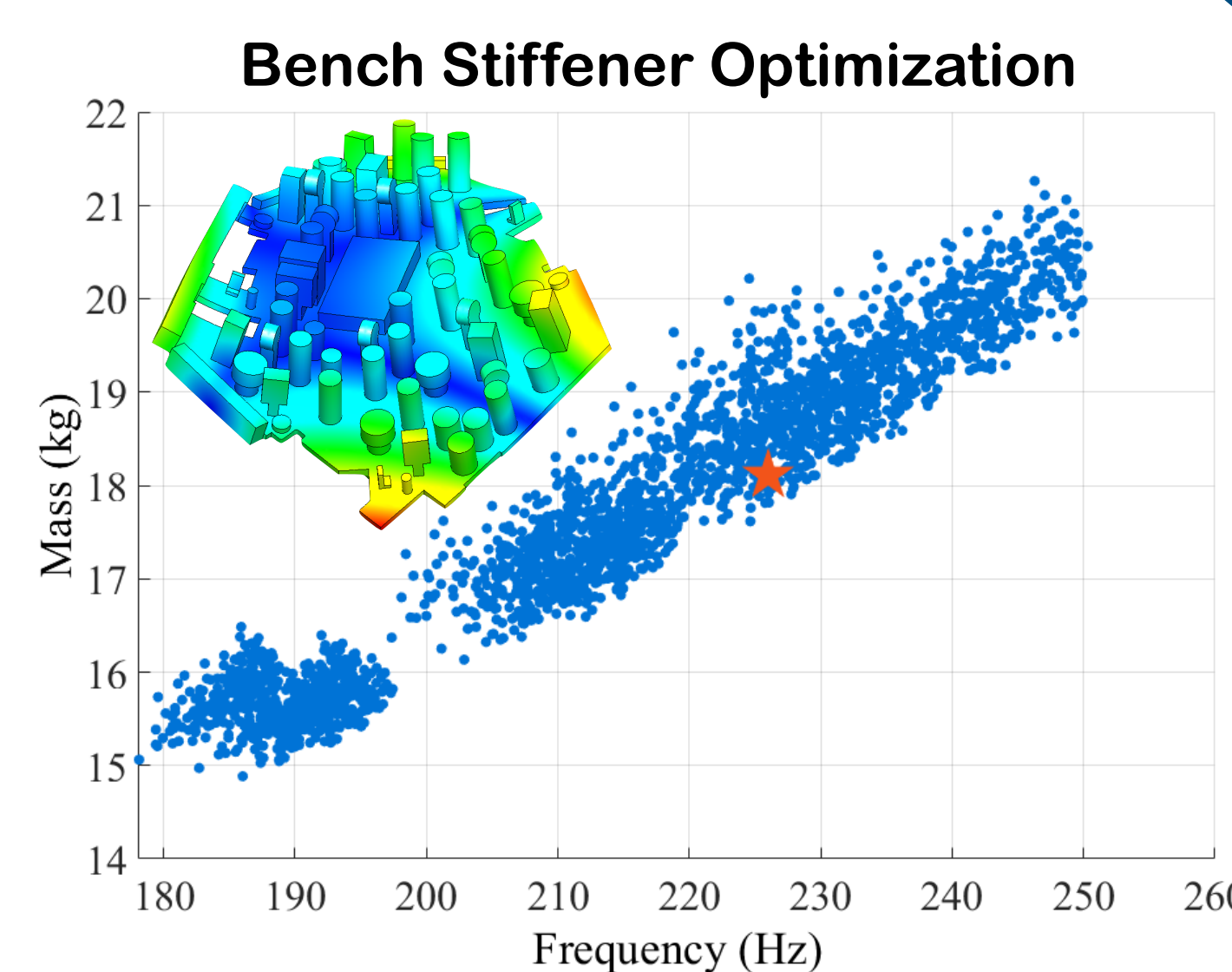
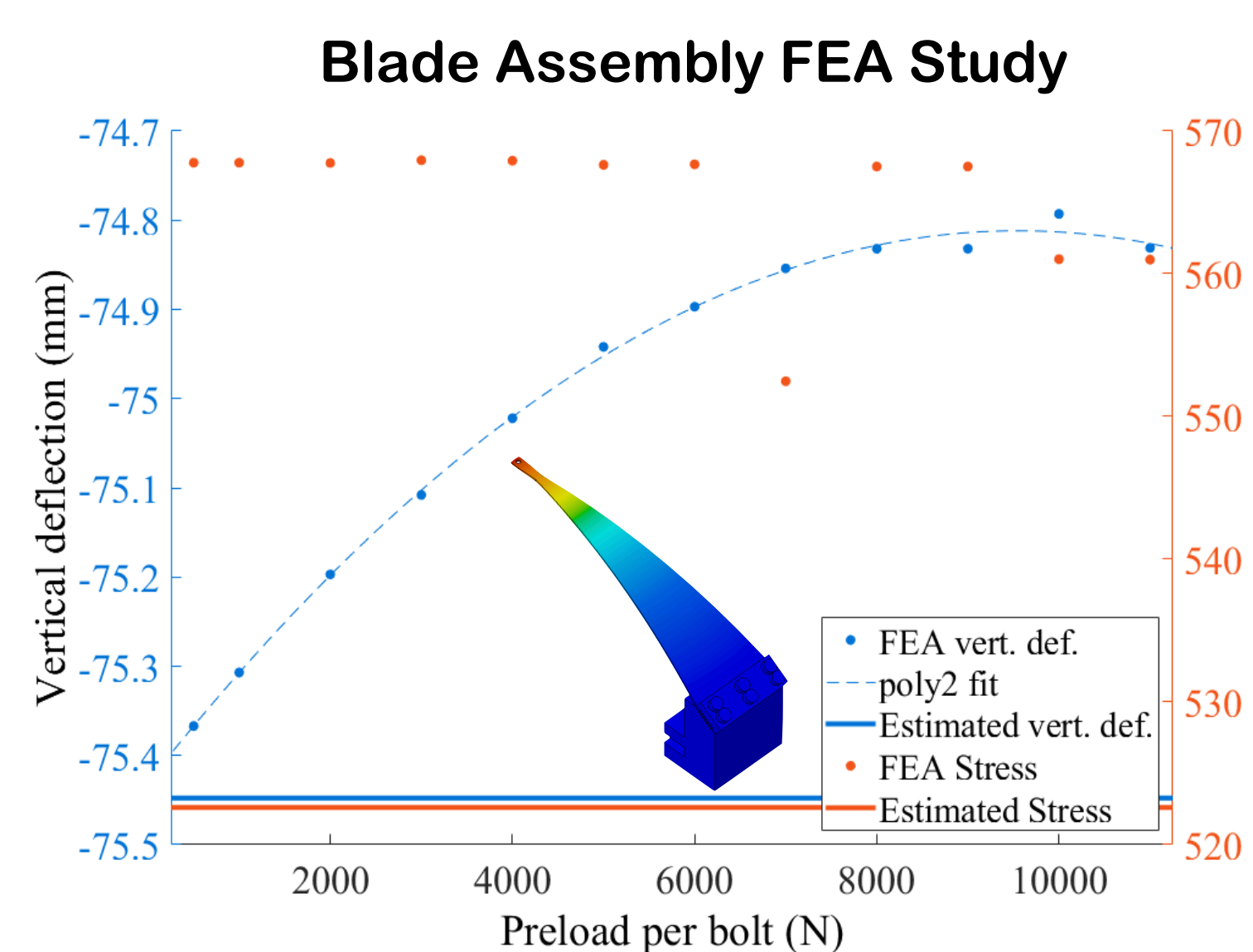
## PERFORMANCE

## DESIGN FEATURES

- ▶ Compact: lighter and stiffer
- ▶ Bolted joints, no UHV soldering
- ▶ Adaptive shape and effective footprint



- ▶ Optical table: Optimized underneath stiffener
- ▶ Blades: Material, Machining and FEA contact study



SUSPENSION MODES (Hz)		
	Model	Measured
X-Longitudinal	1.29	1.28
Y-Transversal	1.29	1.28
Z-Vertical	1.64	1.75
RX-Roll	2.22	2.40
RY-Pitch	1.63	1.64
RZ-Yaw	1.49	1.45

- Simplicity and adaptability
- Suspended mass error < .2%

- Q damped < 30
- RMS motion reduction (10x)

- ▶ Vertical isolation: cantilevered blade spring

$$f_z \approx \frac{1}{2\pi} \sqrt{\frac{Eah^3}{6l^3m}}$$

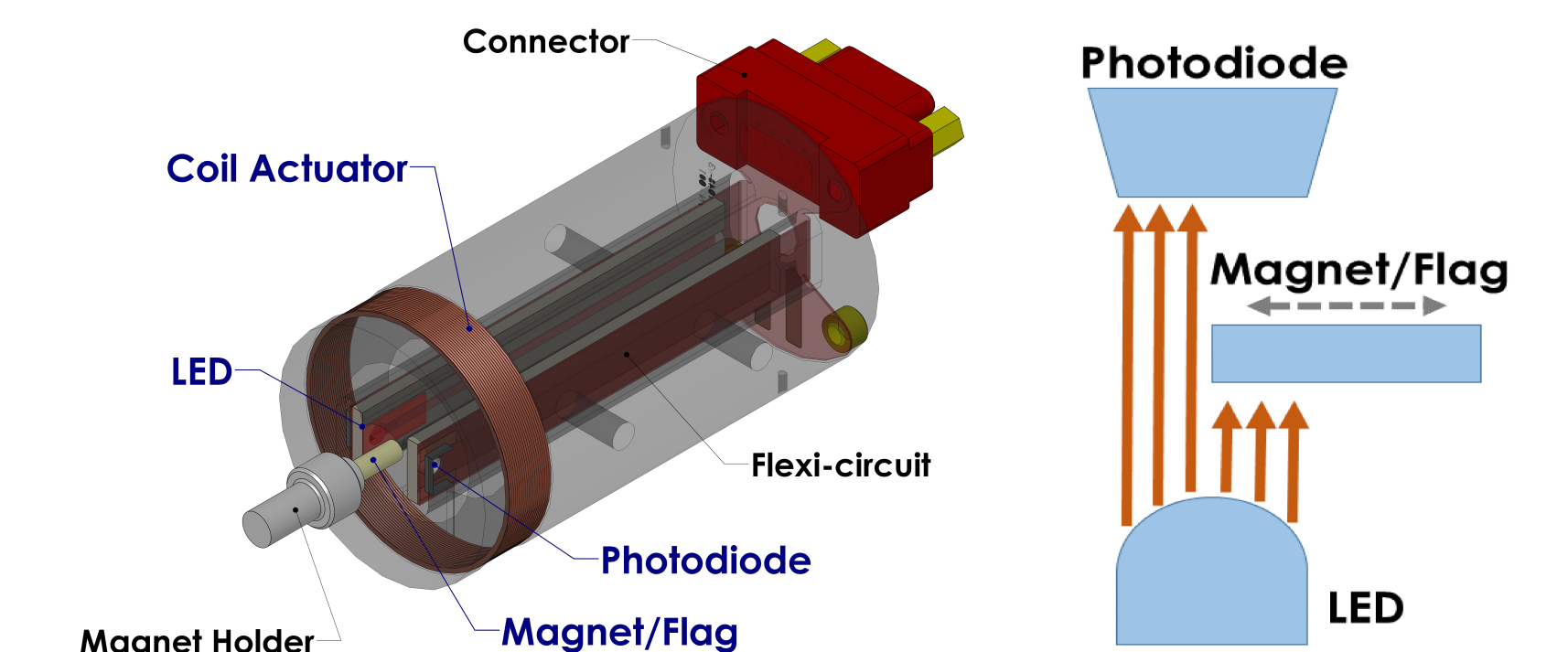
- ▶ Horizontal isolation: pendulum

$$f_{xx}(\approx f_{yy}) \approx \frac{1}{2\pi} \sqrt{\frac{g}{l_{eff}}}$$

## PASSIVE ISOLATION

## ACTIVE DAMPING

- ▶ Sensor-actuator (AOSEM)



- ▶ Feedback digital damping control
  - Band-pass filter (1 zero DC, 2 poles)
- ▶ Control noise: sensor, DAC and ADC

