

Statistical Learning Theory and Applications

9.520/6.860 in Fall 2016

Class Times:

Monday and Wednesday 1pm-2:30pm in 46-3310 Units: 3-0-9 H,G

Web site: <http://www.mit.edu/~9.520/>

Email Contact :

9.520@mit.edu

Instructors: Tomaso Poggio, Lorenzo Rosasco

Guest lectures: Charlie Frogner, Carlo Ciliberto, Alessandro Verri

TAs: Hongyi Zhang, Max Kleiman-Weiner, Brando Miranda, Georgios Evangelopoulos

Web: <http://www.mit.edu/~9.520/>

Office Hours: Friday 2-3 pm, 46-5156 (Poggio Lab lounge)

Further Info: 9.520/6.860 is currently NOT using the Stellar system.

Registration: Fill online registration form.

Mailing list: Registered students will be added in the course mailing list (9520students)

Class

<http://www.mit.edu/~9.520/>

Class 2: Mathcamps

- Functional analysis (~45mins)

Linear Algebra

Basic notion and definitions: matrix and vectors norms, positive, symmetric, invertible matrices, linear systems, condition number.

Functional Analysis:

Linear and Euclidean spaces
scalar product, orthogonality
orthonormal bases, norms and semi-norms,
Cauchy sequence and complete spaces
Hilbert spaces, function spaces
and linear functional, Riesz representation
theorem, convex functions, functional calculus.

- Probability (~45mins)

Probability Theory:

Random Variables (and related
concepts), Law of Large Numbers,
Probabilistic Convergence,
Concentration Inequalities.

9.520: Statistical Learning Theory and Applications

- Course focuses on regularization techniques for supervised learning.
- Support Vector Machines, manifold learning, sparsity, batch and online supervised learning, feature selection, structured prediction, multitask learning.
- Optimization theory critical for machine learning (first order methods, proximal/splitting techniques).
- In the final part focus on emerging deep learning theory

The goal of this class is to provide the theoretical knowledge and the basic intuitions needed to use and develop effective machine learning solutions to a variety of problems.

Class

<http://www.mit.edu/~9.520/>

Rules of the game:

- Problem sets: 4
- Final project: 2 weeks effort, you have to give us title + abstract before November 23
- Participation: check-in/sign in every class
- Grading: Psets (60%) + Final Project (30%) + Participation (10.0%)

Slides on the Web site (most classes on blackboard)

Staff mailing list is 9.520@mit.edu

Student list will be 9.520students@mit.edu

[Please fill form \(independent of MIT/Harvard registration\)!!](#)

send email to us if you want to be added
to mailing list

Class

<http://www.mit.edu/~9.520/>

Material:

Most classes on blackboard.

Book draft:

Rosasco and T. Poggio, Machine Learning: a Regularization Approach, MIT-9.520 Lectures Notes, Manuscript, Dec. 2015 (chapters will be provided).

Office hours: Friday 2-3 pm in 46-5156, Poggio Lab lounge

Tentative dates

Problem Sets (due dates will be 11 days)

Problem Set 1: 26 Sep. (due: 10/05)

Problem Set 2: 12 Oct. (due: 10/24)

Problem Set 3: 26 Oct. (due: 11/07)

Problem Set 4: 14 Nov. (due: 11/23)

Final projects:

Announcement/projects are open: Nov. 16

Deadline to suggest/pick suggestions (title/abstract): Nov. 23

Submission: Dec. xx

Final Project

The course project can be:

- **Research project** (suggested by you): Review, theory and/or application (~4 page report in NIPS format).
 - **Wikipedia articles** (suggested list by us): Editing or creating new Wikipedia entries on a topic from the course syllabus.
 - **Coding** (suggested by you or us): Implementation of one of the course algorithms and integration on the open-source library GURLS (Grand Unified Regularized Least Squares) <https://github.com/LCSL/GURLS>
-
- Research project reports will be archived online (on a dedicated page on our web)
 - Wikipedia entries links will be archived (on a dedicated page on our web), <https://docs.google.com/document/d/1RpLDfy1yMBNaSGqsdnl7w1GgzgN4Ib-wPaLwRJJ44mA/edit>

Class <http://www.mit.edu/~9.520/>: big picture

- Classes 3-9 are the core: foundations + regularization
- Classes 10-22 are state-of-the-art topics for research in — and applications of — ML
- Classes 23-25 are partly unpublished theory on multilayer networks (DCLNs)

Class

<http://www.mit.edu/~9.520/>

- Today is big picture day...
- Be ready for quite a bit of material
- If you need a complete renovation of your Fourier analysis or linear algebra background...you should not be in this class.

Summary of today's overview

- Motivations for this course: a golden age for new AI, the key role of Machine Learning, CBMM
- A bit of history: Statistical Learning Theory, Neuroscience
- A bit of history: applications
- Now:
 - why depth works
 - why is neuroscience important
 - the challenge of sampling complexity

The problem of intelligence: how it arises in the brain and how to replicate it in machines

The problem of (human) intelligence is one of the great problems in science, probably the greatest.

Research on intelligence:

- a great intellectual mission: understand the brain, reproduce it in machines
- will help develop intelligent machines

These advances will be critical to of our society's

- future prosperity
- education, health, security
- solve all other great problems in science



CENTER FOR
Brains
Minds+
Machines

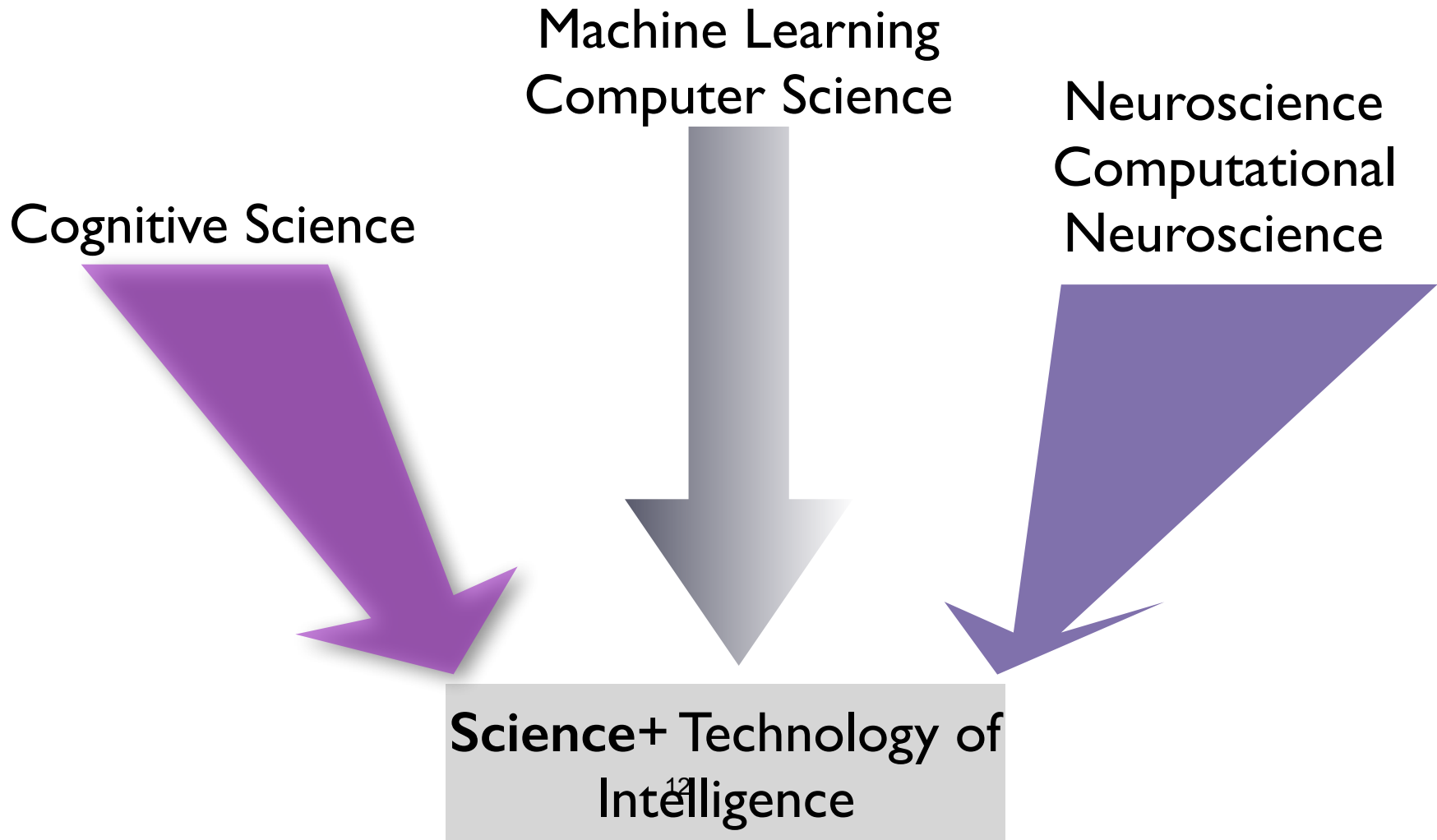
Science + Engineering of Intelligence

CBMM's main goal is to *make progress in the science of intelligence which enables better engineering of intelligence.*



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Brains
Minds+
Machines

Interdisciplinary



**Centerness:
collaborations across different disciplines and labs**

MIT

Boyden, Desimone, Kaelbling, Kanwisher,
Katz, Poggio, Sasanfar, Saxe,
Schulz, Tenenbaum, Ullman, Wilson,
Rosasco, Winston

Harvard

Blum, Kreiman, Mahadevan,
Nakayama, Sompolinsky,
Spelke, Valiant

Rockefeller

Freiwald

Allen Institute

Koch

UCLA

Yuille

Stanford

Goodman

Cornell

Hirsh

Hunter

Epstein, Sakas,
Chodorow

Wellesley

Hildreth, Conway,
Wiest

Puerto Rico

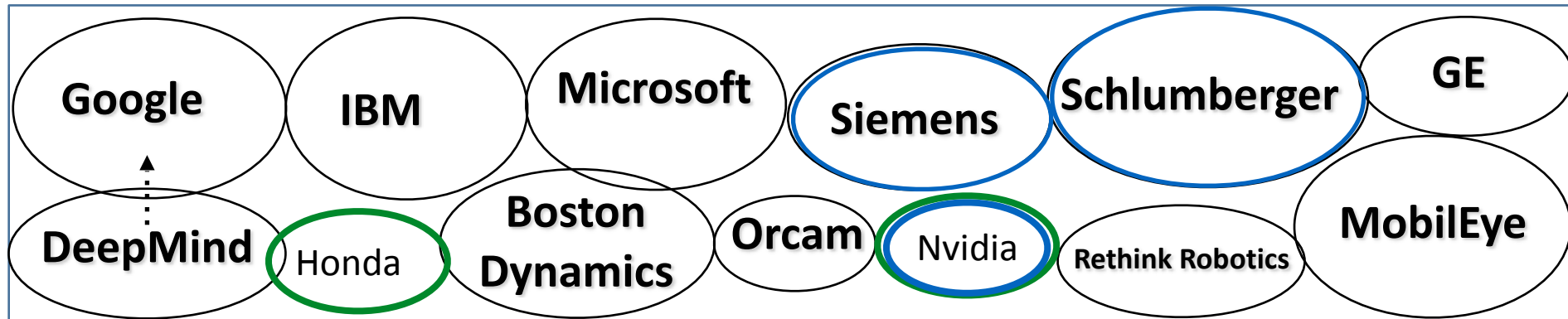
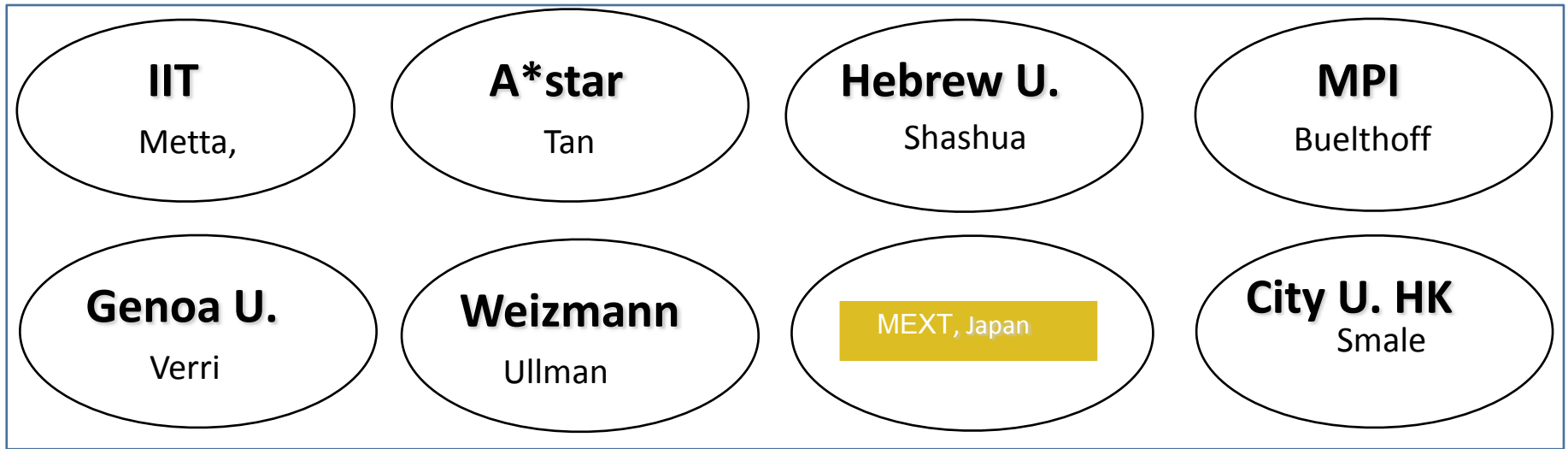
Bykhovaskaia, Ordonez,
Arce Nazario

Howard

Manaye, Chouikha,
Rwebargira



Recent Stats and Activities



Recent Stats and Activities

Summer school at Woods Hole:
Our flagship initiative, very good!

Brains, Minds & Machines Summer Course

An intensive three-week course will give advanced students a “deep end” introduction to the problem of intelligence



Intelligence in games: the beginning



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Third Annual NSF Site Visit, June 8 – 9, 2016



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Recent progress in AI

natureINSIGHT



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The 2 best examples of the success of new ML

- AlphaGo
- Mobileye





PERSON IN THE NEWS

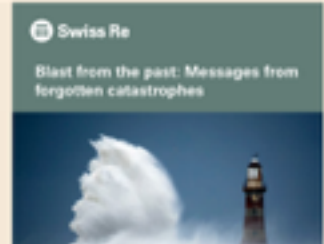
March 11, 2016 3:14 pm

Demis Hassabis, master of the new machine age

Murad Ahmed

[Share](#) [Author alerts](#) [Print](#) [Clip](#) [Comments](#)

The creator of the AI game-playing program makes all the right moves, writes Murad Ahmed



[Twitter](#) [Facebook](#) [StumbleUpon](#) [LinkedIn](#)

More

PERSON IN THE NEWS

[James Comey](#)

[Ali al-Naimi](#)

[Kylie Bass](#)

The victories have a human mastermind in [Demis Hassabis](#), co-founder and chief executive of DeepMind. He describes Mr Lee as the "Roger Federer of Go", and for some the computer program's achievement is akin to a robot taking to the lawns of Wimbledon and beating the legendary tennis champion.

"I think it is pretty huge but, ultimately, it will be for historic reasons," says Mr Hassabis, speaking at the

THE BIG READ

[EDF](#)



[TUNISIA](#)



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Real Engineering: Mobileye



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Real Engineering: Mobileye



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Third Annual NSF Site Visit, June 8 – 9, 2016

History



The Science of Intelligence

The science of intelligence was at the roots of today's engineering success

We need to make another basic effort on it

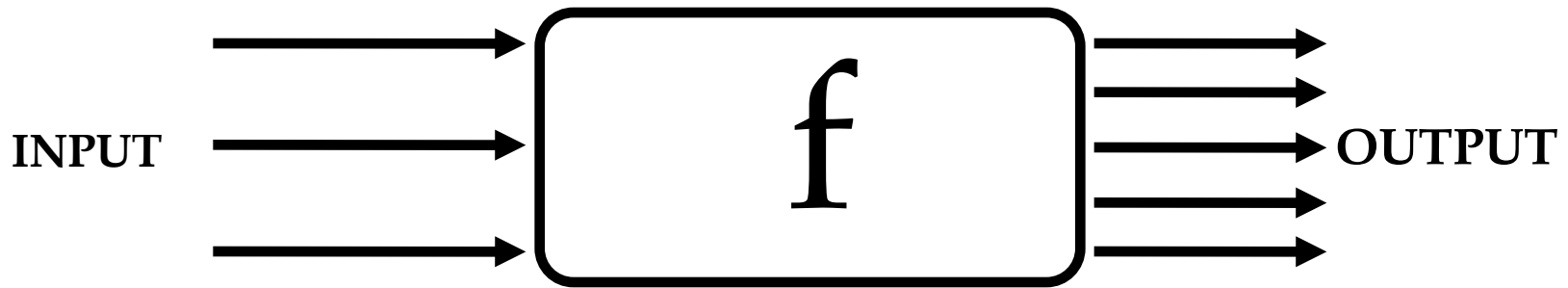
- for the sake of basic science
- for the engineering of tomorrow



Summary of today's overview

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- A bit of history: Statistical Learning Theory, Neuroscience
- A bit of history: applications
- Now:
 - why depth works
 - why is neuroscience important
 - the challenge of sampling complexity

Statistical Learning Theory: **supervised** learning (~1980-2010)



Given a set of l examples (data)

$$\{(x_1, y_1), (x_2, y_2), \dots, (x_l, y_l)\}$$

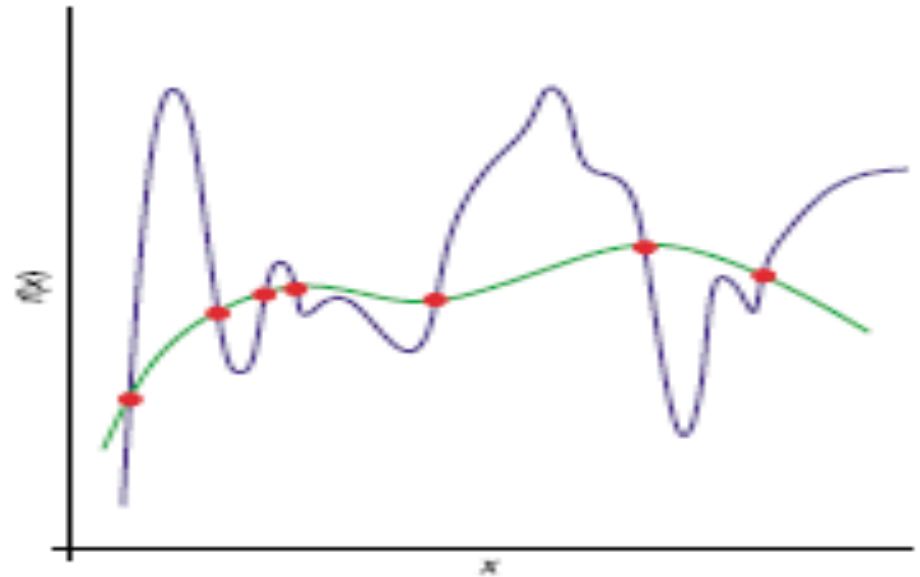
Question: find function f such that

$$f(x) = \hat{y}$$

is a **good predictor** of y for a **future** input x (fitting the data is **not** enough!)

Statistical Learning Theory: prediction, not description

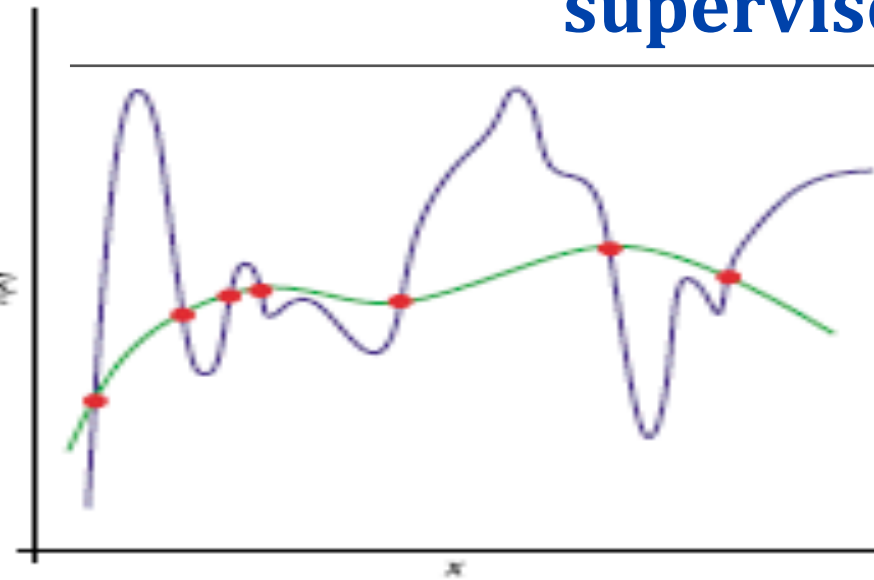
- = data from f
- = function f
- = approximation of f



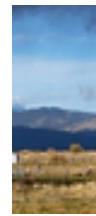
Generalization:

estimating value of function where there are no data (good generalization means predicting the function well; important is for empirical or validation error to be a good proxy of the prediction error)

Statistical Learning Theory: supervised learning



Regression



(4,24,...)



(1,13,...)



(7,33,...)

Classification



(92,10,...)



(41,11,...)



(19,3,...)



(4,71,...)

Statistical Learning Theory: part of mainstream math not just statistics (Valiant, Vapnik, Smale, Devore...)

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AMERICAN MATHEMATICAL SOCIETY
Volume 39, Number 1, Pages 1-49
S 0273-0979(01)00923-5
Article electronically published on October 5, 2001

ON THE MATHEMATICAL FOUNDATIONS OF LEARNING



FELIPE CUCKER AND STEVE SMALE

*The problem of learning is arguably at the
very core of the problem of intelligence,
both bi*

T. Poggio and C.R. Shelton

INTRODUCTION

(1) A main theme of this report is the relationship of approximation to learning and the primary role of sampling (inductive inference). We try to emphasize relations of the theory of learning to the mainstream of mathematics. In particular, there are large roles for probability theory, for algorithms such as *least squares*, and for tools and ideas from linear algebra and linear analysis. An advantage of doing this is that communication is facilitated and the power of core mathematics is more easily brought to bear.

Statistical Learning Theory: supervised learning

There is an unknown **probability distribution** on the product space $Z = X \times Y$, written $\mu(z) = \mu(x, y)$. We assume that X is a compact domain in Euclidean space and Y a bounded subset of \mathbb{R} . The **training set** $S = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\} = \{z_1, \dots, z_n\}$ consists of n samples drawn i.i.d. from μ .

\mathcal{H} is the **hypothesis space**, a space of functions $f : X \rightarrow Y$.

A **learning algorithm** is a map $L : Z^n \rightarrow \mathcal{H}$ that looks at S and selects from \mathcal{H} a function $f_S : \mathbf{x} \rightarrow y$ such that $f_S(\mathbf{x}) \approx y$ *in a predictive way*.

Statistical Learning Theory

Given a function f , a loss function V , and a probability distribution μ over Z , the **expected or true error** of f is:

$$I[f] = \mathbb{E}_Z V[f, z] = \int_Z V(f, z) d\mu(z) \quad (1)$$

which is the **expected loss** on a new example drawn at random from μ .

The **empirical error** of f is:

$$I_S[f] = \frac{1}{n} \sum V(f, z_i) \quad (2)$$

A very natural requirement for f_S is distribution independent **generalization**

$$\forall \mu, \lim_{n \rightarrow \infty} |I_S[f_S] - I[f_S]| = 0 \text{ in probability} \quad (3)$$

In other words, the training error for the solution must converge to the expected error and thus be a “proxy” for it. Otherwise the solution would not be “predictive”.

Statistical Learning Theory: generalization follows from control of complexity

The ERM problem does not have a *predictive* solution in general (just fitting the data does not work).

Choosing an appropriate hypothesis space H (for instance a compact set of continuous functions) can guarantee generalization. A necessary and sufficient condition for generalization is that H is *uGC*.

Related concept, measuring complexity of the hypothesis space, are:

VC dimension, V_γ dimension, Rademacher numbers..

Statistical Learning Theory: the learning problem should be well-posed



J. S. Hadamard, 1865-1963

A problem is well-posed if its solution
exists, unique and

is stable, eg depends continuously on the data (here
examples)

This is an example of foundational results
in learning theory...

Statistical Learning Theory: foundational theorems

Conditions for generalization in learning theory have deep, almost philosophical, implications:

they can be regarded as equivalent conditions that guarantee a theory to be predictive (that is scientific)

- ▶ theory must be chosen from a small hypothesis set
- ▶ theory should not change much with new data...most of the time (stability)

Classical algorithm: Regularization in RKHS (eg. kernel machines)

$$\min_{f \in H} \left[\frac{1}{n} \sum_{i=1}^n V(f(x_i) - y_i) + \lambda \|f\|_K^2 \right]$$

implies

$$f(\mathbf{x}) = \sum_i^n \alpha_i K(\mathbf{x}, \mathbf{x}_i)$$

Equation includes splines, Radial Basis Functions and SVMs (depending on choice of K and V).

For a review, see Poggio and Smale, 2003; see also Schoelkopf and Smola, 2002; Bousquet, O., S. Boucheron and G. Lugosi; Cucker and Smale; Zhou and Smale...

Classical algorithm: Regularization in RKHS (eg. kernel machines)

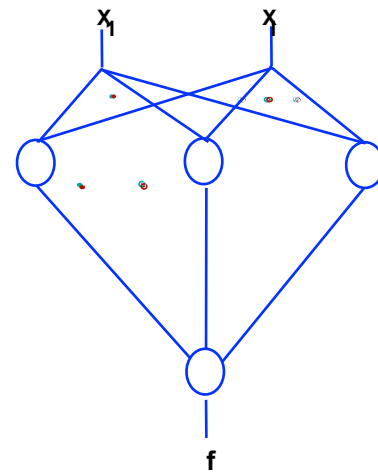
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implies

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Remark (for later use):

Classical kernel machines correspond to
shallow networks





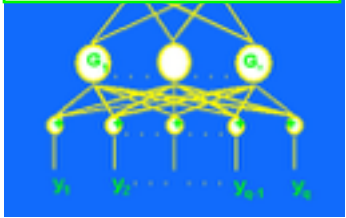
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 - why is neuroscience important
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Learning

$$\min_{f \in H} \left[\frac{1}{\ell} \sum_{i=1}^{\ell} V(y_i, f(x_i)) + \mu \|f\|_K^2 \right]$$

$$f(x) = \sum_{i=1}^{\ell} c_i K(\mathbf{x}_i, \mathbf{x})$$



**LEARNING THEORY
+
ALGORITHMS**

Theorems on foundations of learning
Predictive algorithms



Sung & Poggio 1995, also Kanade & Baluja....

**COMPUTATIONAL
NEUROSCIENCE:
models+experiments**

How visual cortex works

Engineering of Learning

$$\min_{f \in H} \left[\frac{1}{\ell} \sum_{i=1}^{\ell} V(y_i, f(x_i)) + \mu \|f\|_K^2 \right]$$

$$f(x) = \sum_{i=1}^{\ell} c_i K(\mathbf{x}_i, \mathbf{x})$$



**LEARNING THEORY
+
ALGORITHMS**

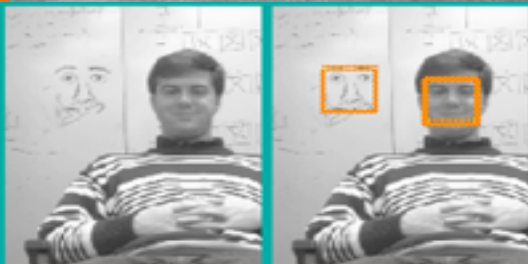
Theorems on foundations of learning
Predictive algorithms



Sung & Poggio 1995

**COMPUTATIONAL
NEUROSCIENCE:
models+experiments**

How visual cortex works



Image

Output



Engineering of Learning

$$\min_{f \in H} \left[\frac{1}{\ell} \sum_{i=1}^{\ell} V(y_i, f(x_i)) + \mu \|f\|_K^2 \right]$$

$$f(x) = \sum_{i=1}^{\ell} c_i K(\mathbf{x}_i, \mathbf{x})$$



**LEARNING THEORY
+
ALGORITHMS**

Theorems on foundations of learning
Predictive algorithms



Face detection has been available in digital cameras for a few years now

**COMPUTATIONAL
NEUROSCIENCE:
models+experiments**

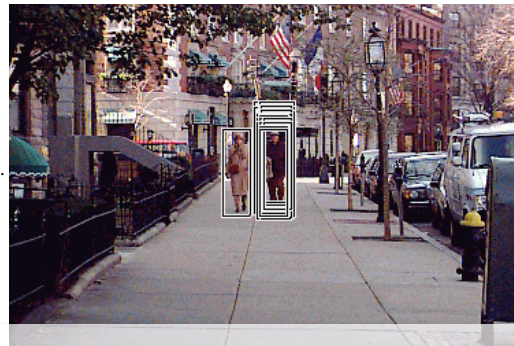
How visual cortex works

Engineering of Learning



LEARNING THEORY
+
ALGORITHMS

Theorems on foundations of learning
Predictive algorithms



People detection

Papageorgiou&Poggio, 1997, 2000
also Kanade&Scheiderman



COMPUTATIONAL
NEUROSCIENCE:
models+experiments

How visual cortex works



Engineering of Learning



LEARNING THEORY
+
ALGORITHMS

Theorems on foundations of learning
Predictive algorithms



Pedestrian detection

Papageorgiou&Poggio, 1997, 2000
also Kanade&Scheiderman

COMPUTATIONAL
NEUROSCIENCE:
models+experiments

How visual cortex works

Some other examples of past ML applications from my lab

Computer Vision

- Face detection
- Pedestrian detection
- Scene understanding
- Video categorization
- Video compression
- Pose estimation

Graphics

Speech recognition

Speech synthesis

Decoding the Neural Code

Bioinformatics

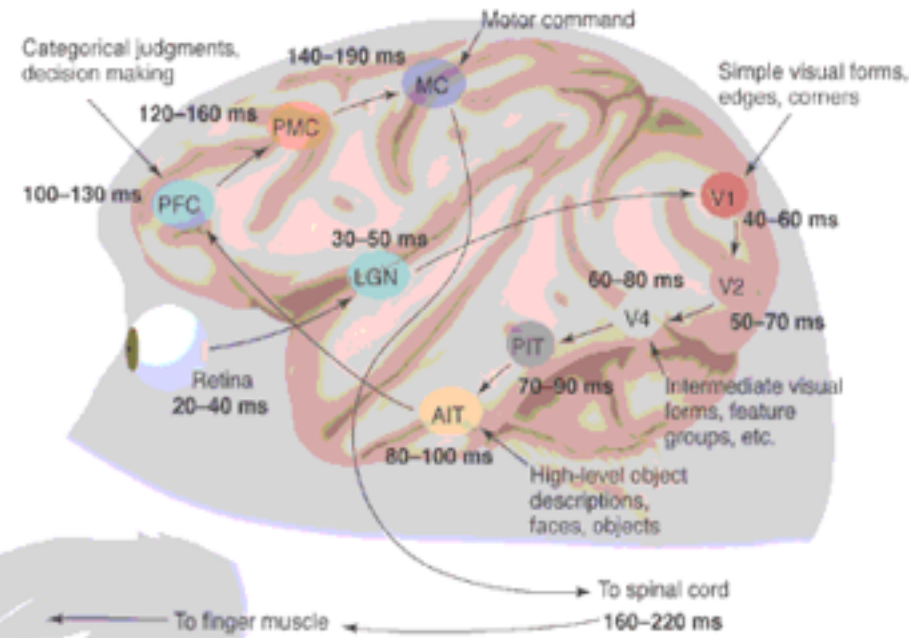
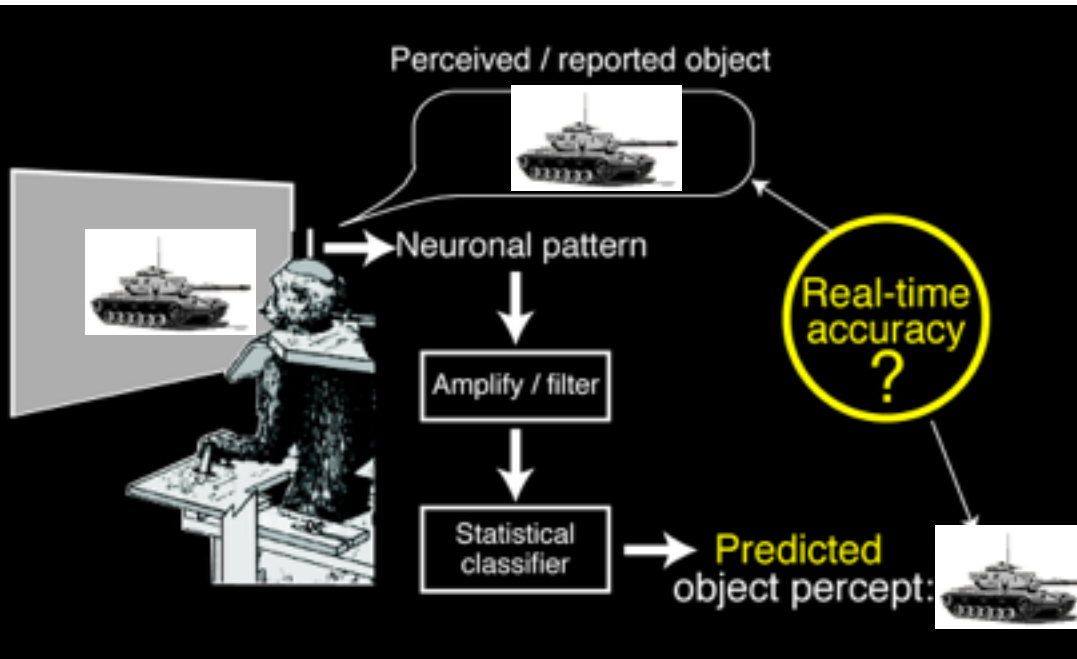
Text Classification

Artificial Markets

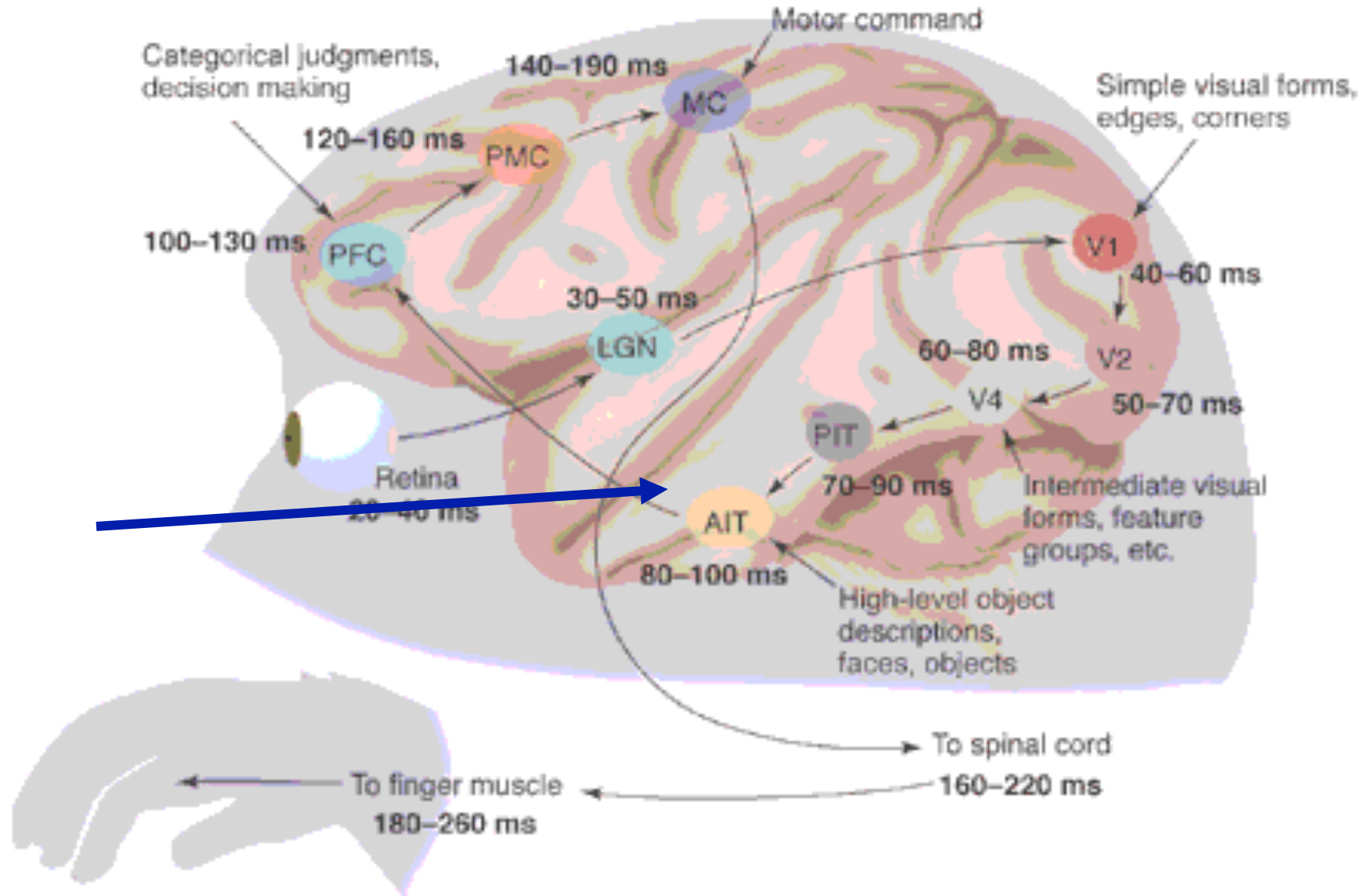
Stock option pricing

....

Decoding the neural code: Matrix-like read-out from the brain

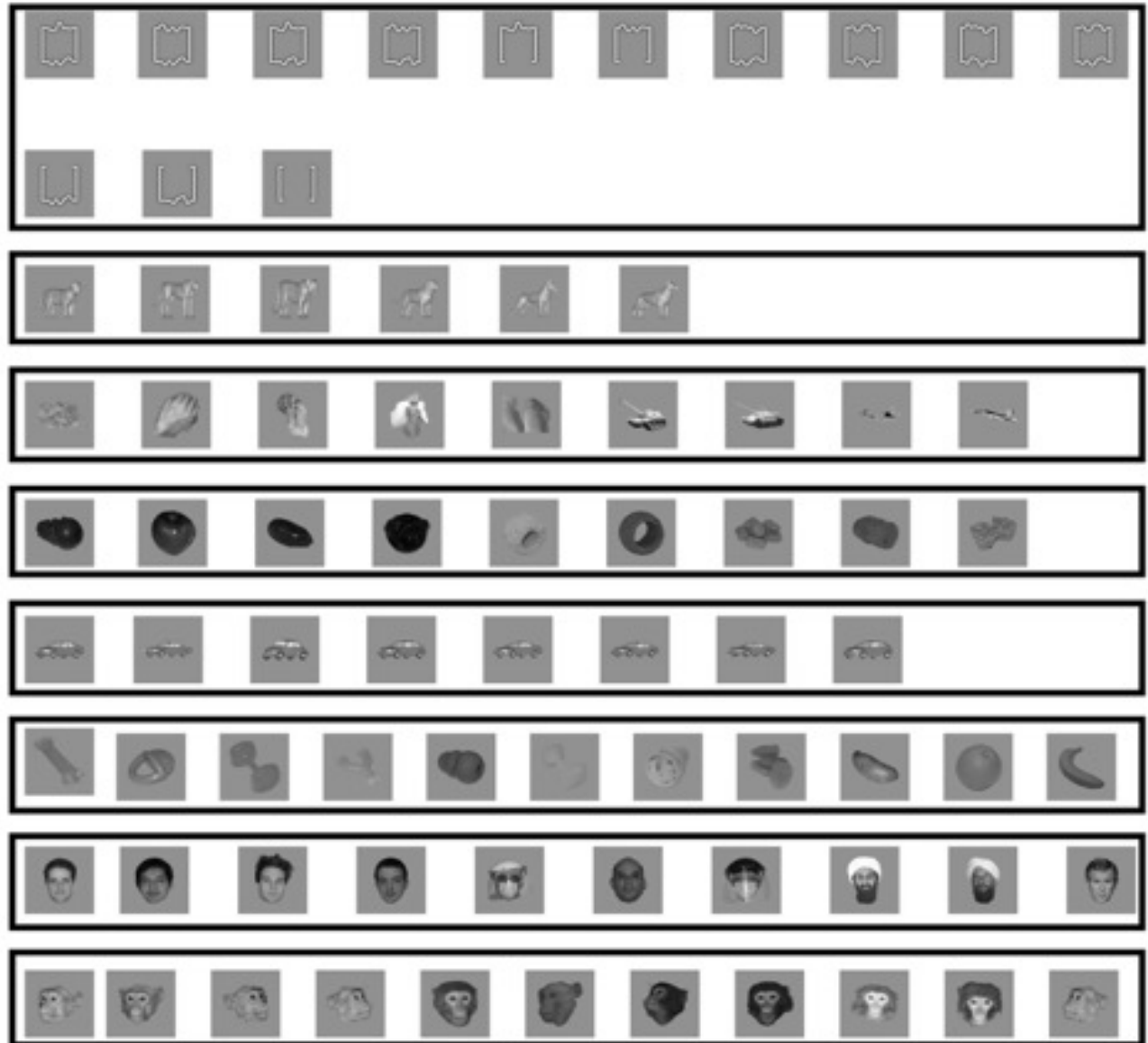


The end station of the ventral stream in visual cortex is IT

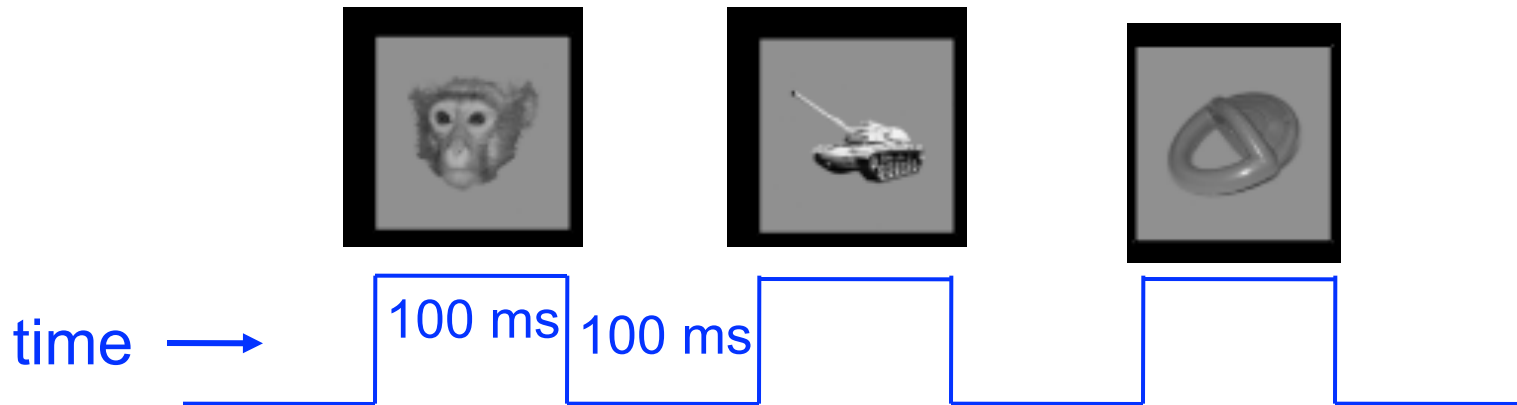


Reading-out the neural code in AIT

77 objects,
8 classes

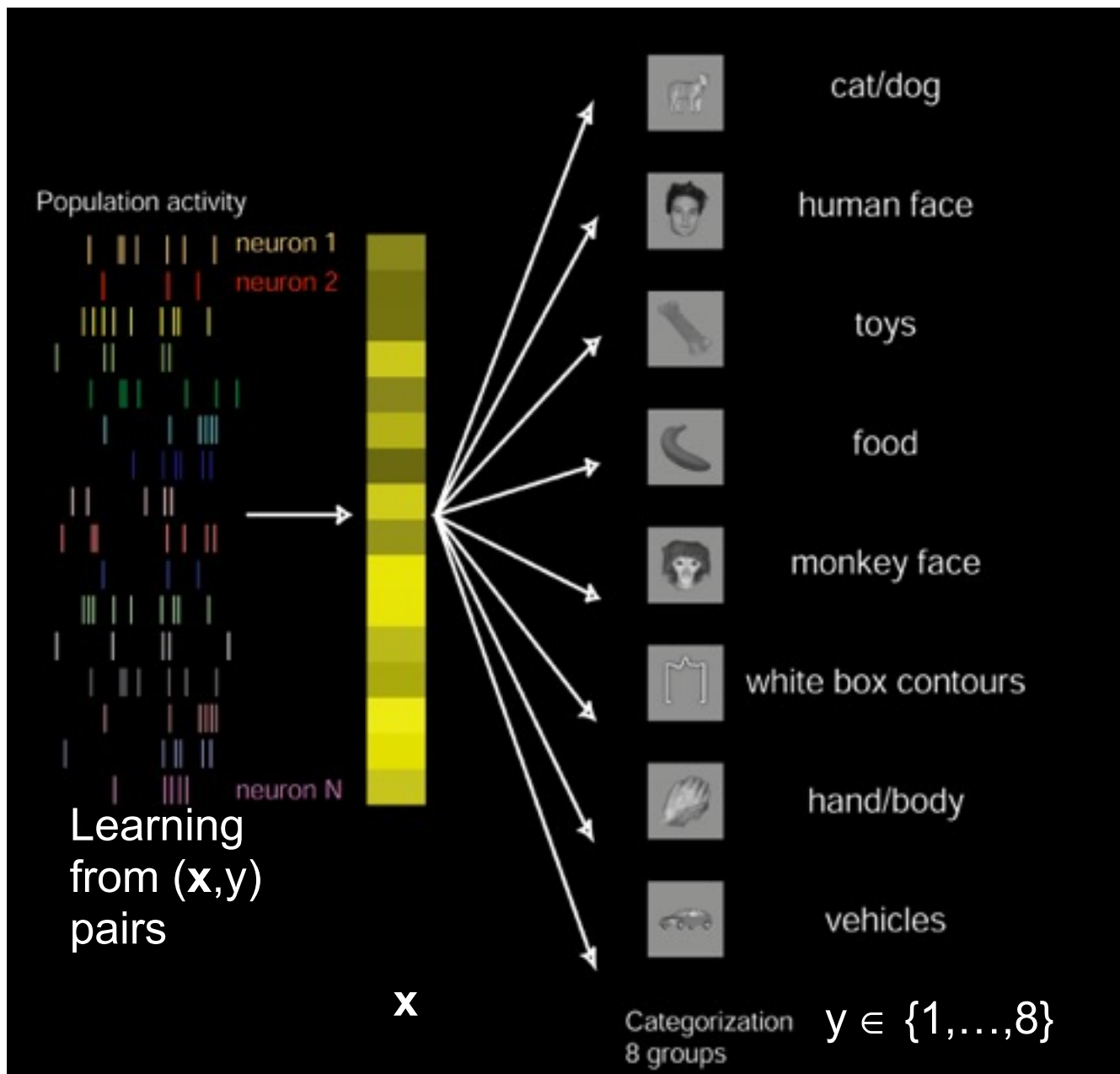


Recording at each recording site during passive viewing



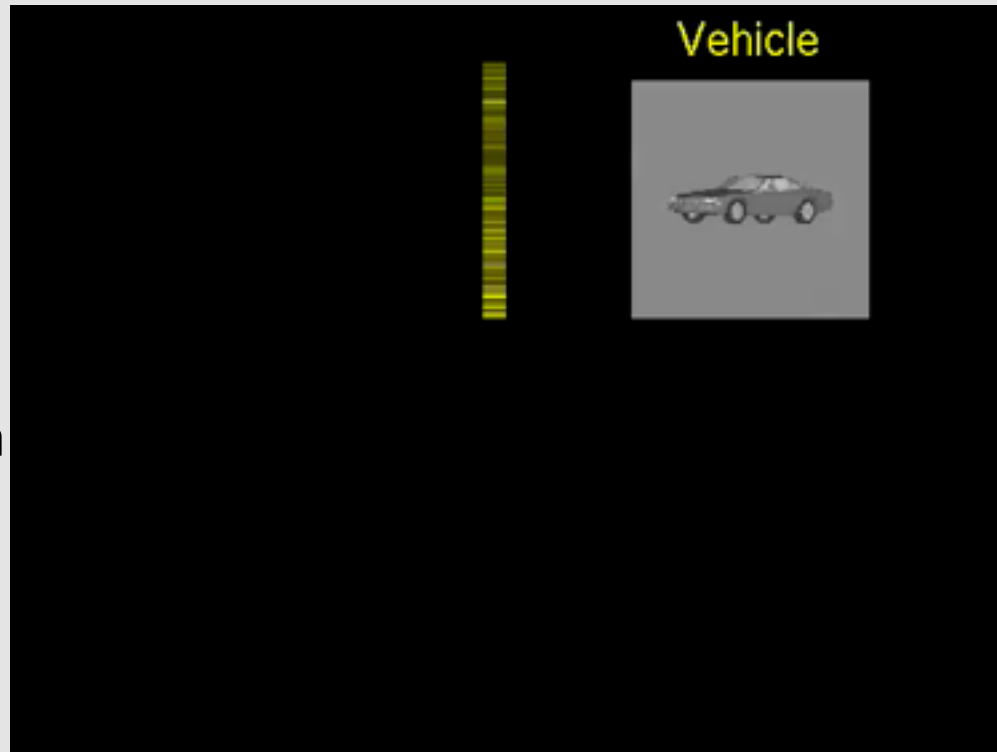
- 77 visual objects
- 10 presentation repetitions per object
- presentation order randomized and counter-balanced

Decoding the neural code ... using a classifier



We can decode the brain's code and read-out from neuronal populations: reliable object categorization (>90% correct) using ~200 arbitrary AIT "neurons"

Categorization



Toy

Body

Human Face

Monkey Face

Vehicle

Food

Box

Cat/Dog

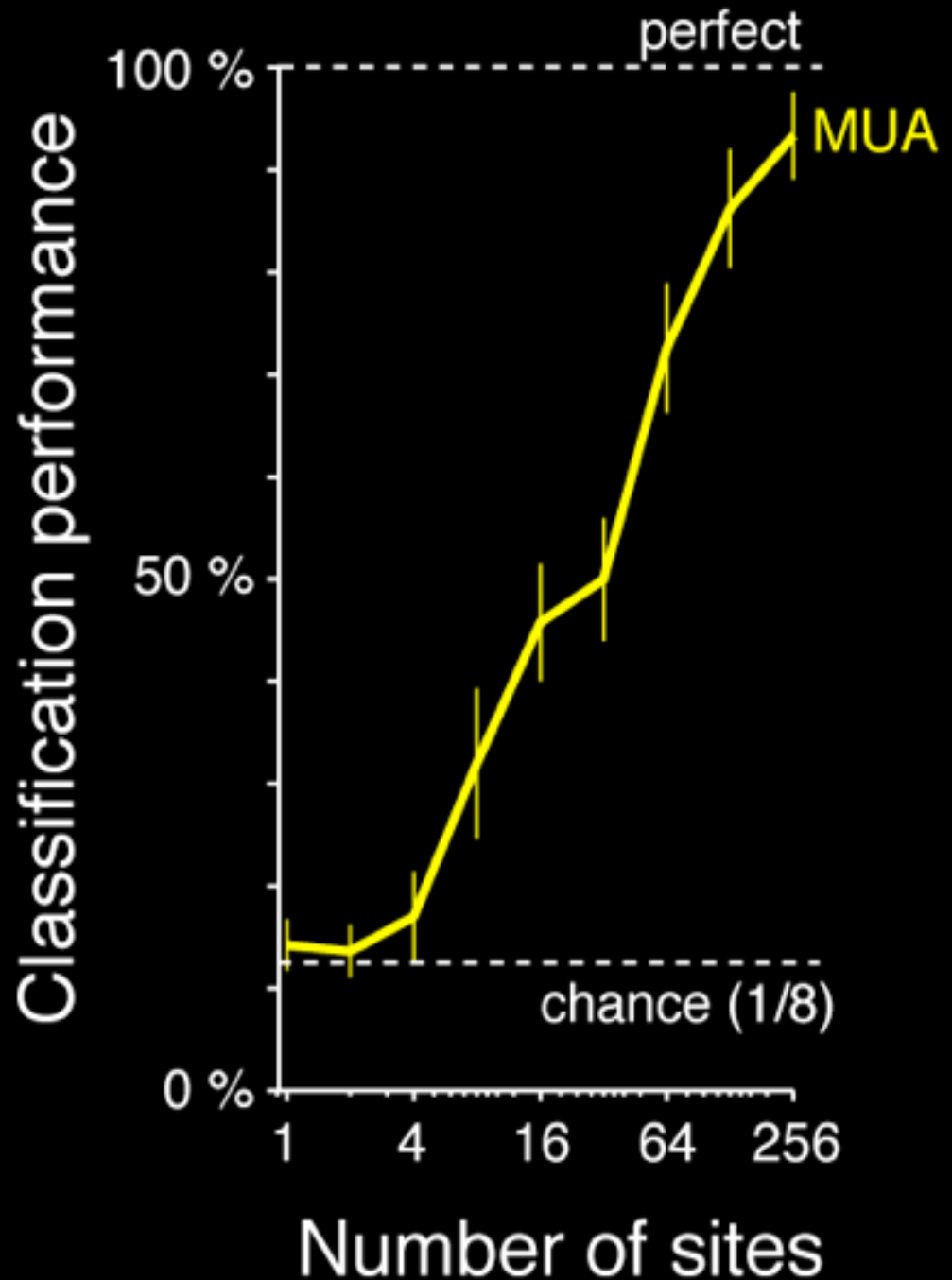
Video speed: 1
frame/sec

Actual presentation
rate: 5 objects/sec

We can decode the brain's code and read-out from neuronal populations:

reliable object categorization using ~100 arbitrary AIT sites

- [100-300 ms] interval
- 50 ms bin size



Learning: image analysis



⇒ **Bear (0° view)**



⇒ **Bear (45° view)**

Learning: image synthesis

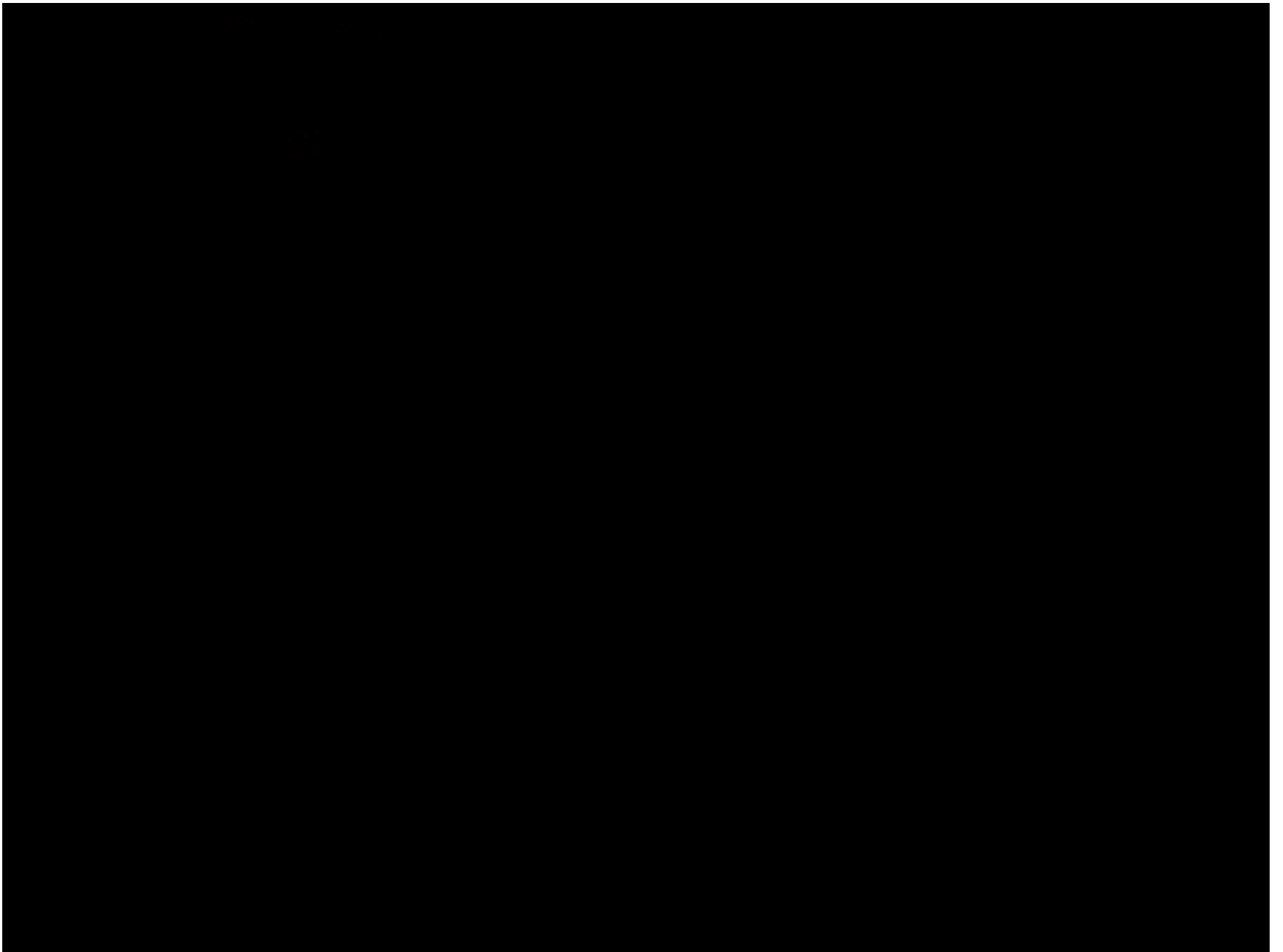
UNCONVENTIONAL GRAPHICS

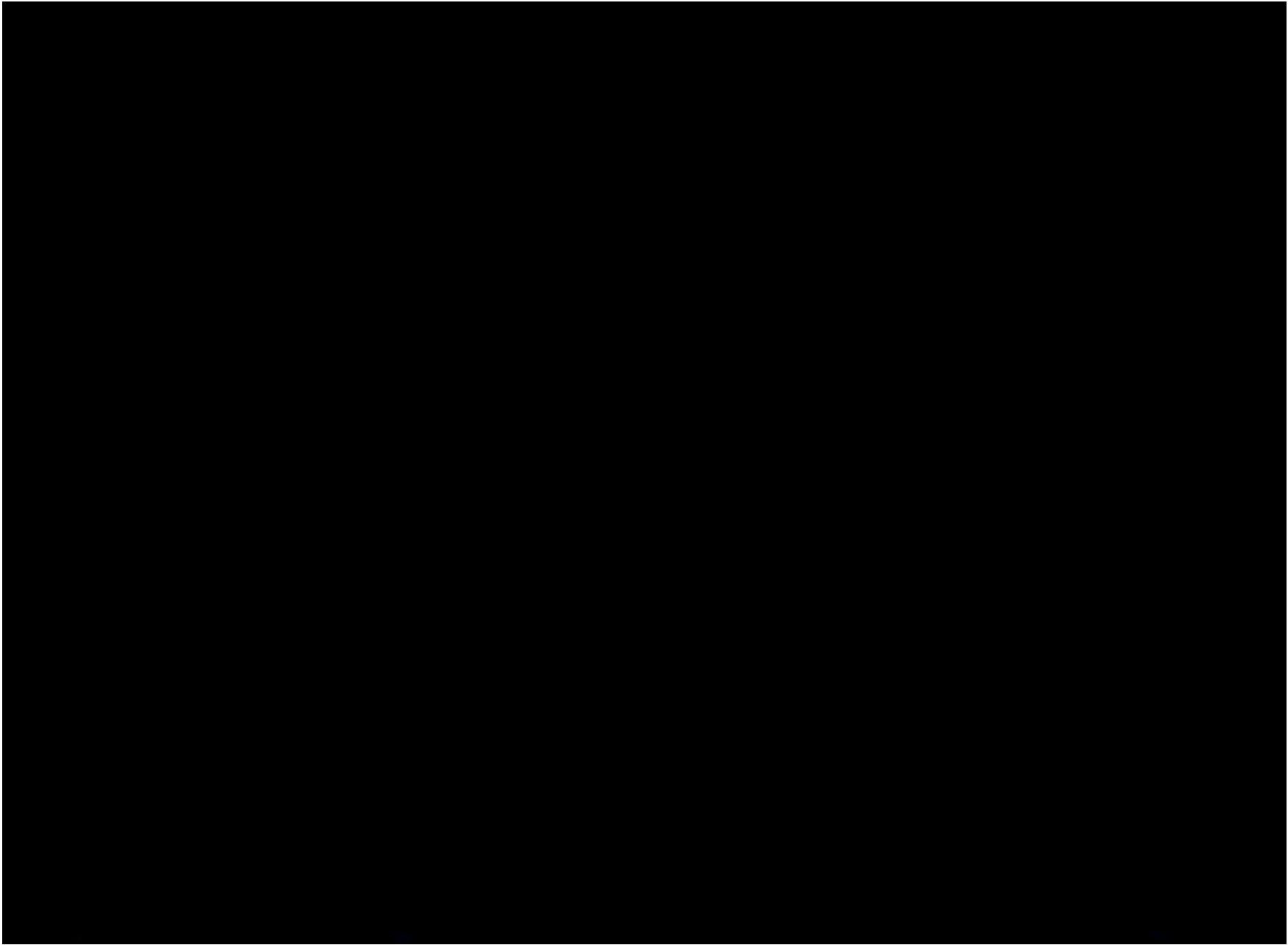
$\Theta = 0^\circ$ view \Rightarrow



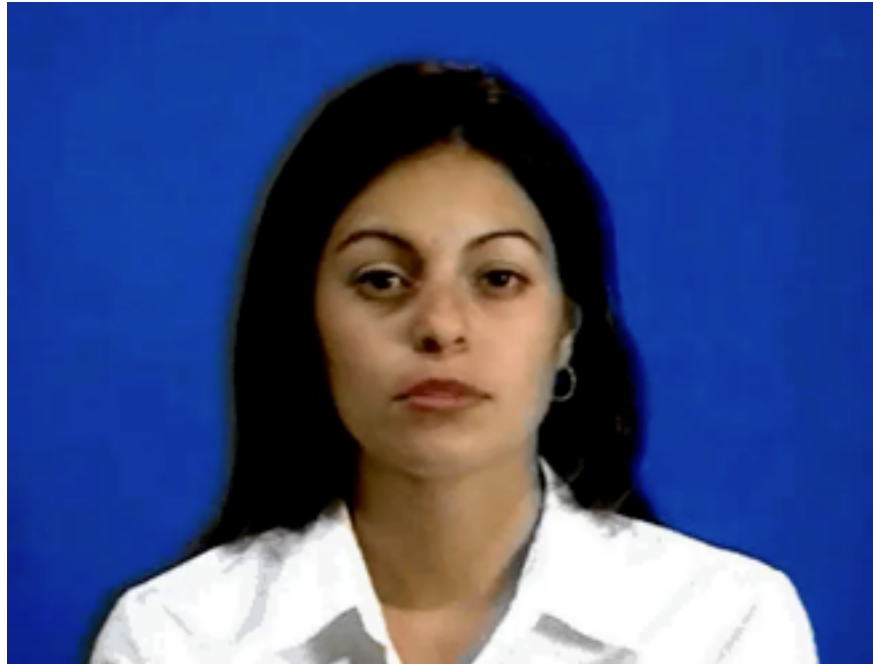
$\Theta = 45^\circ$ view \Rightarrow







Mary101



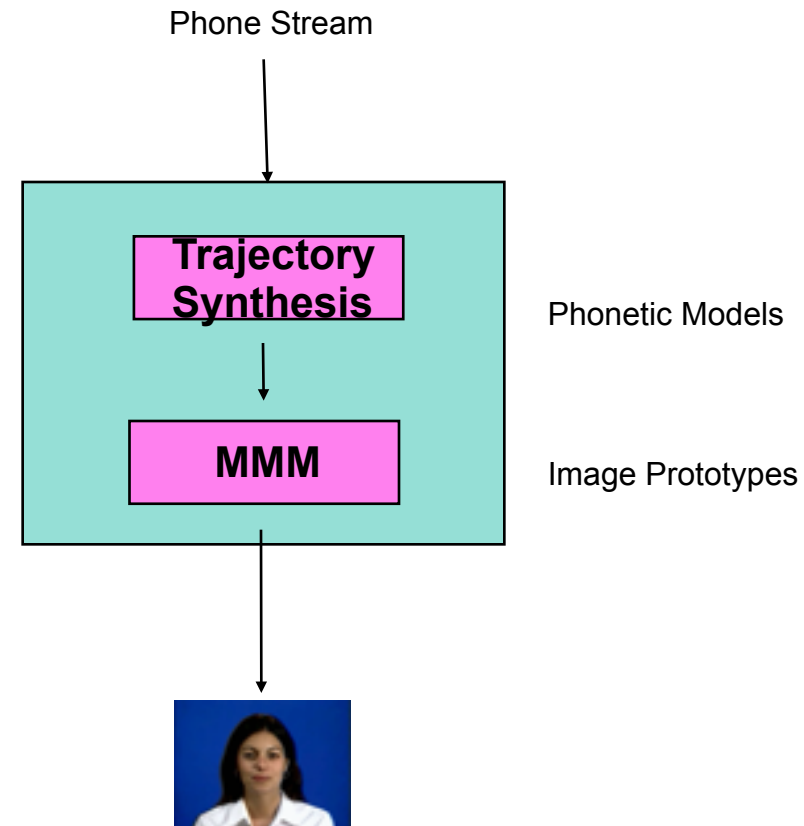
A- more in a moment

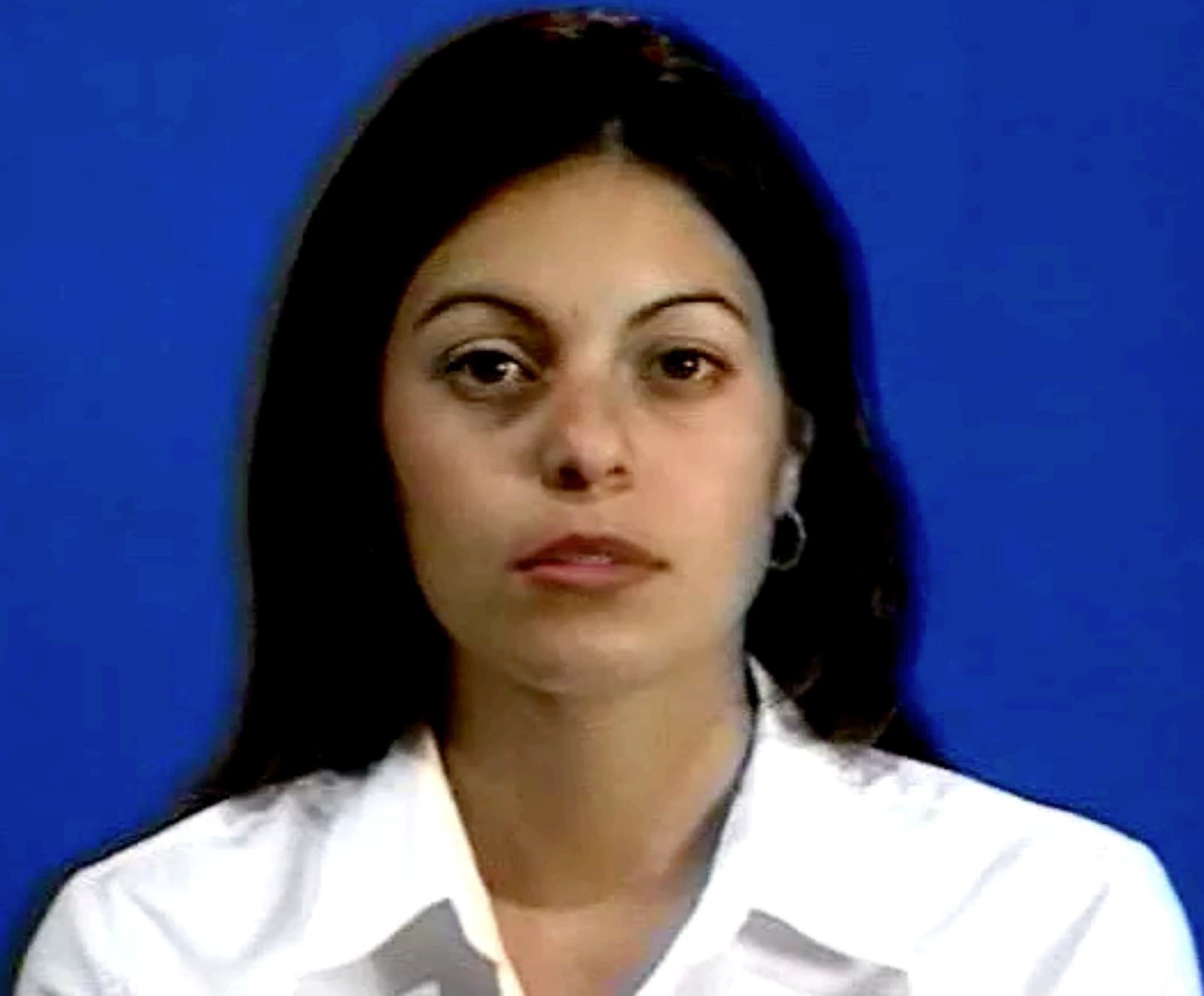
1. Learning

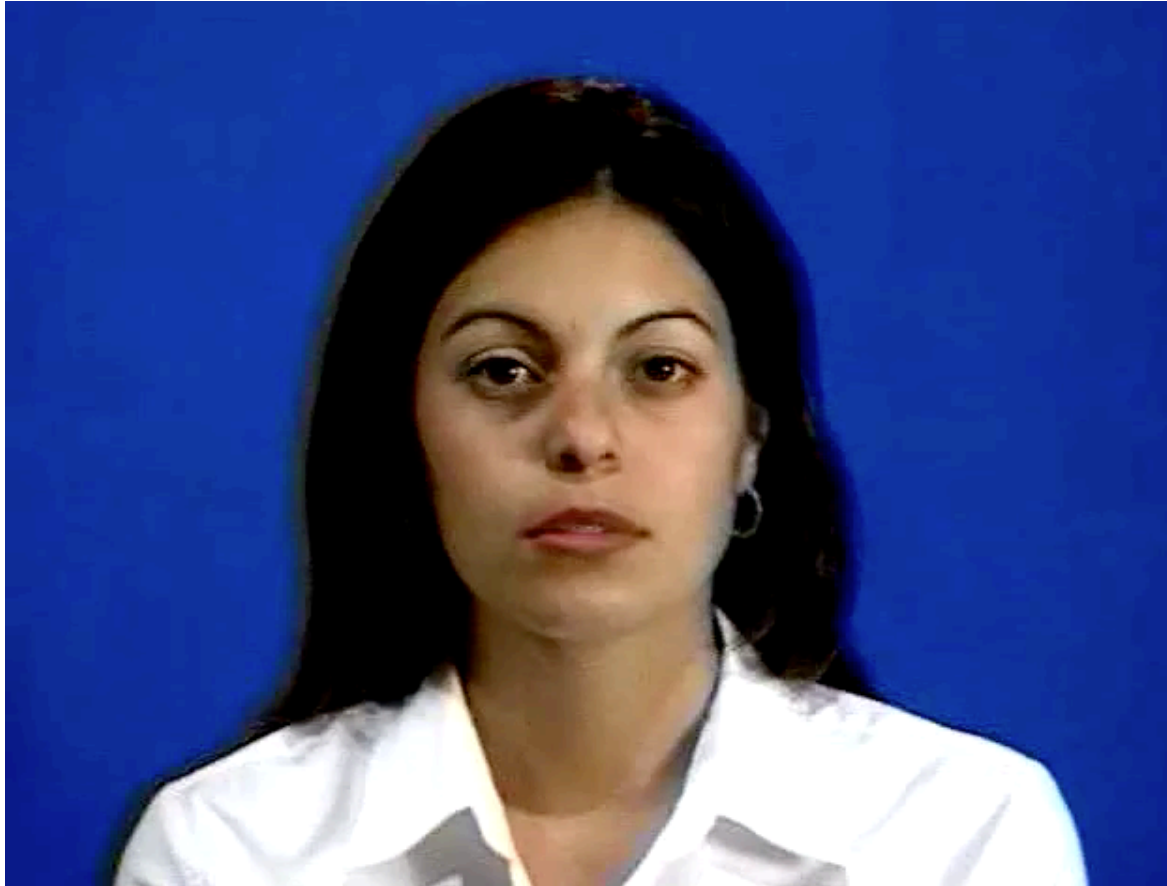
System learns from 4 mins of video face appearance (Morphable Model) and speech dynamics of the person

2. Run Time

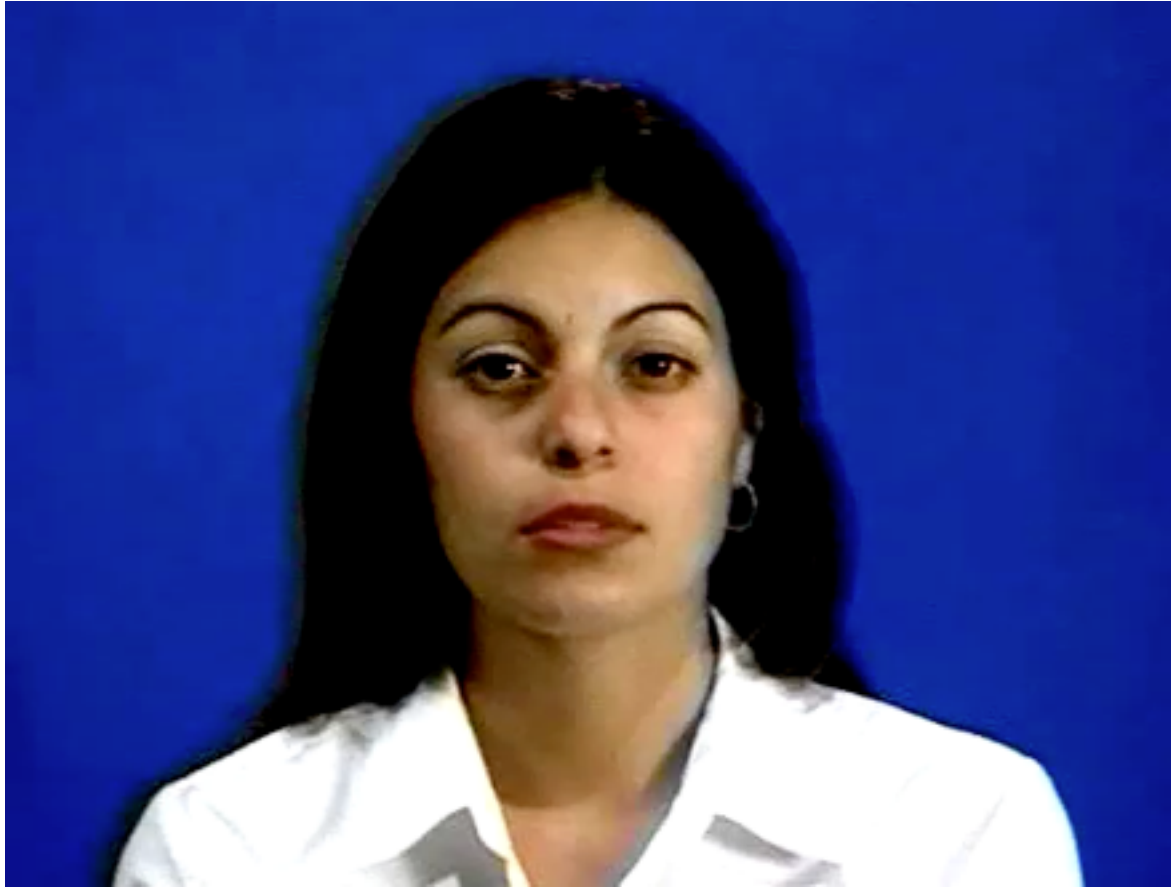
For any speech input the system provides as output a synthetic video stream



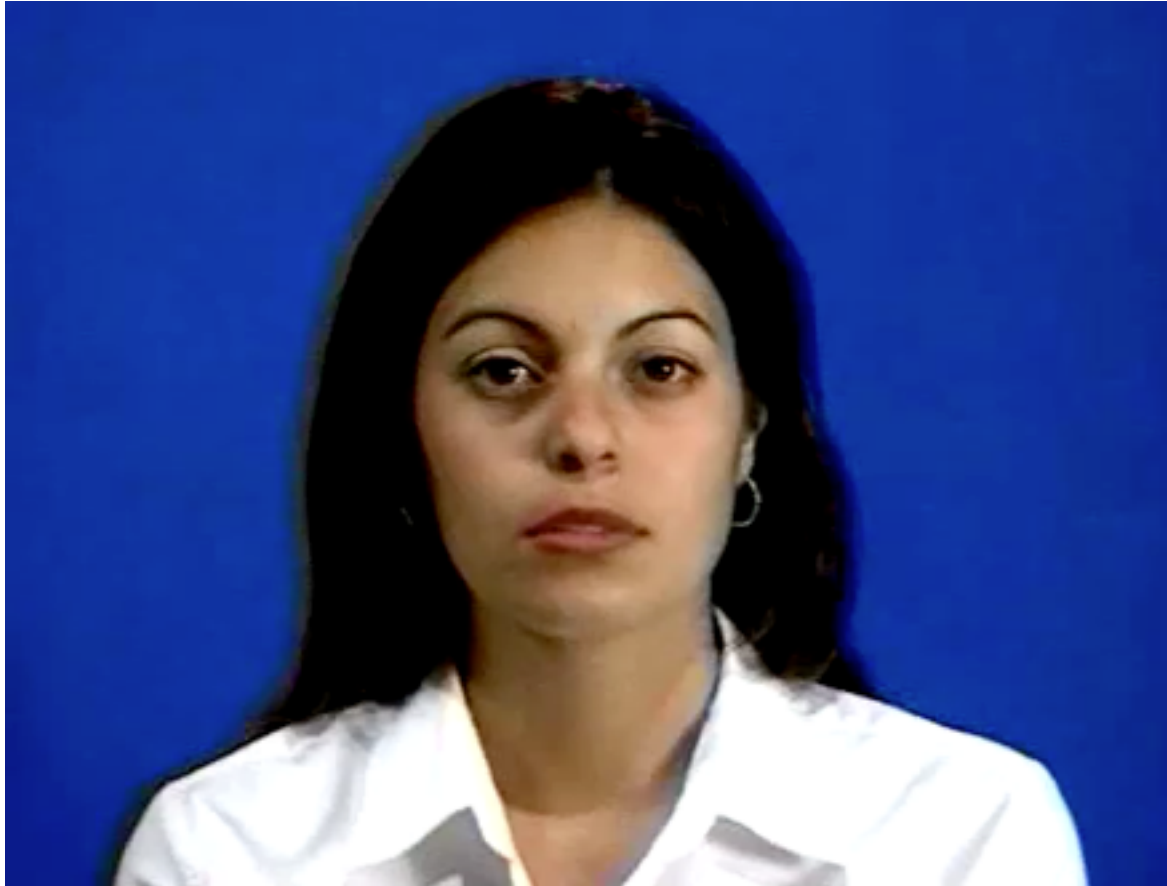




B-Dido



C-Hikaru



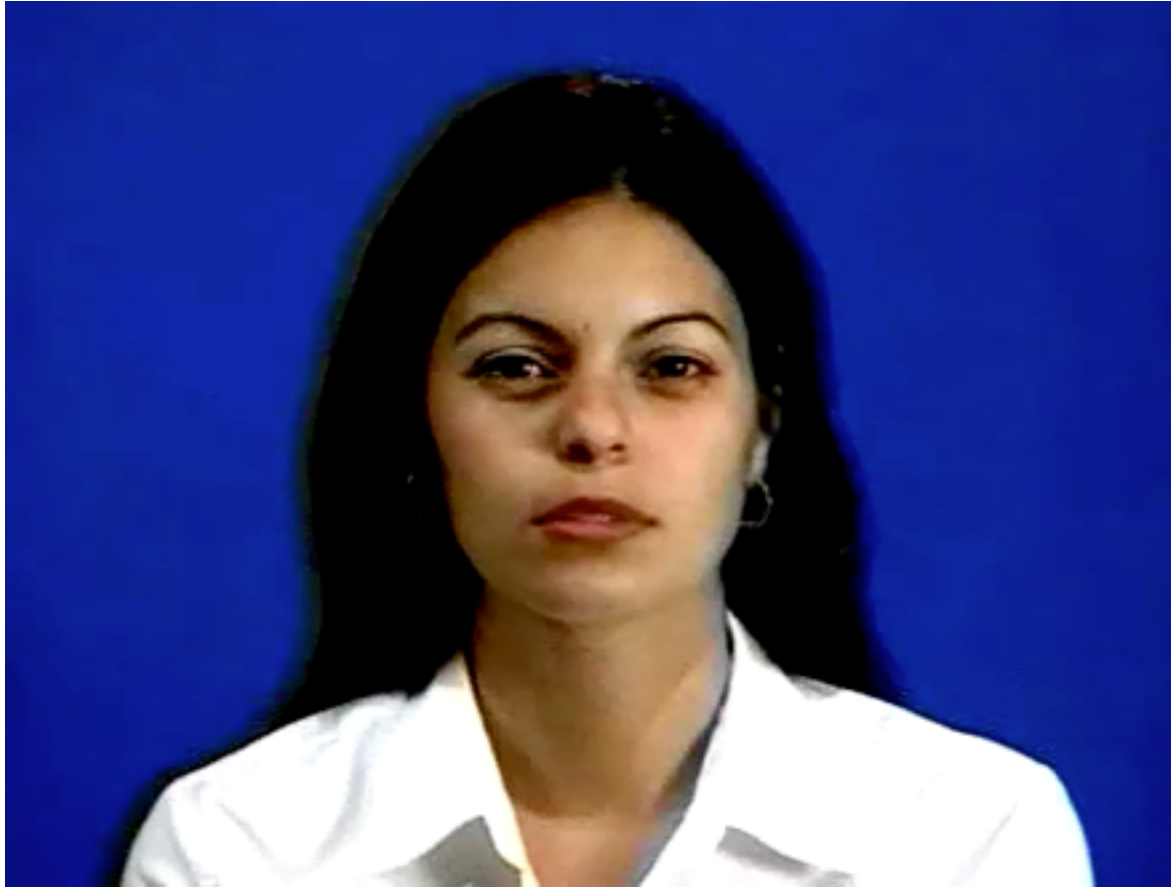
D-Denglijun



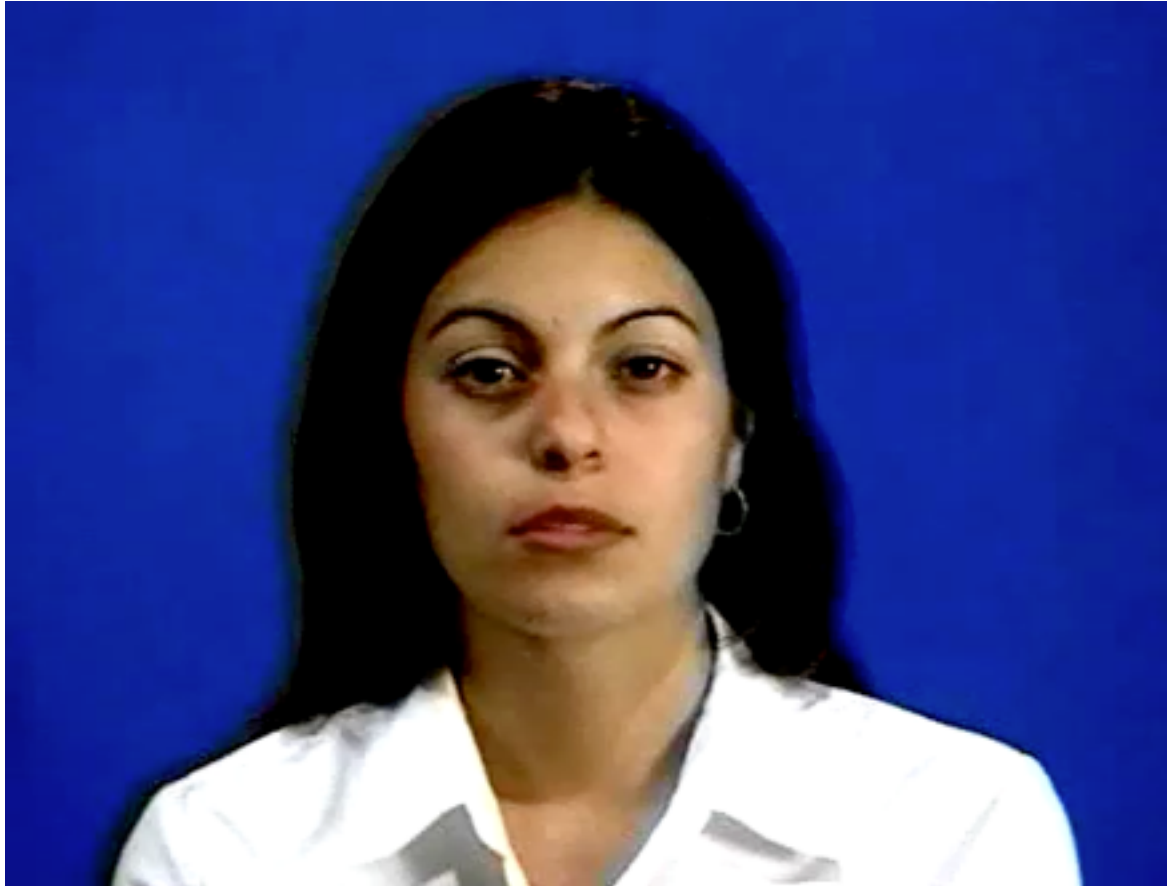
E-Marylin



F-Katie Couric



G-Katie

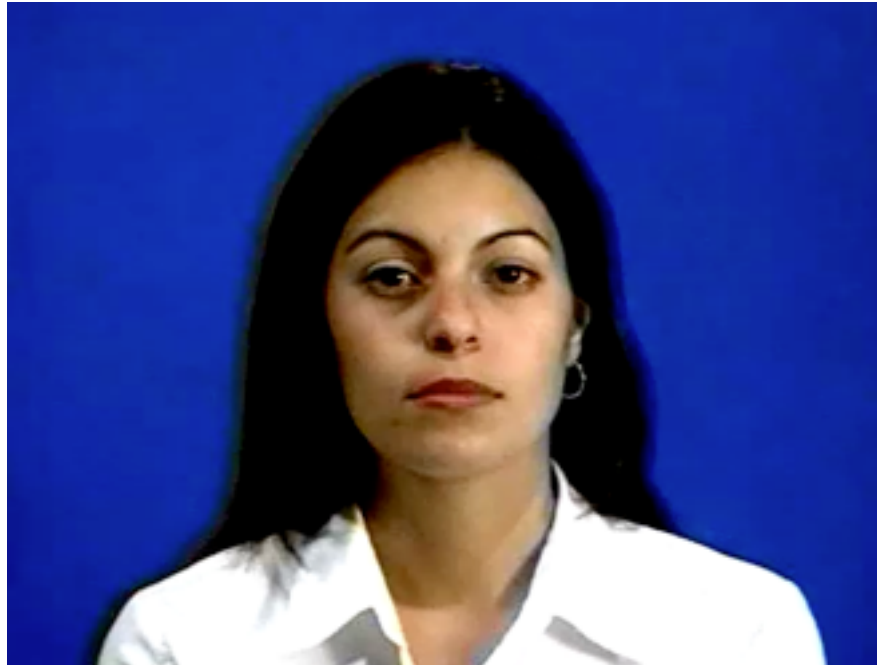


H-Rehema



I-Rehemax

A Turing test: what is real and what is synthetic?



L-real-synth

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Classical learning algorithms: “high” sample complexity and shallow architectures

How do the learning machines described by classical learning theory -- such as kernel machines -- compare with brains?

❑ One of the most obvious differences is the ability of people and animals to learn from very few examples (“poverty of stimulus” problem).

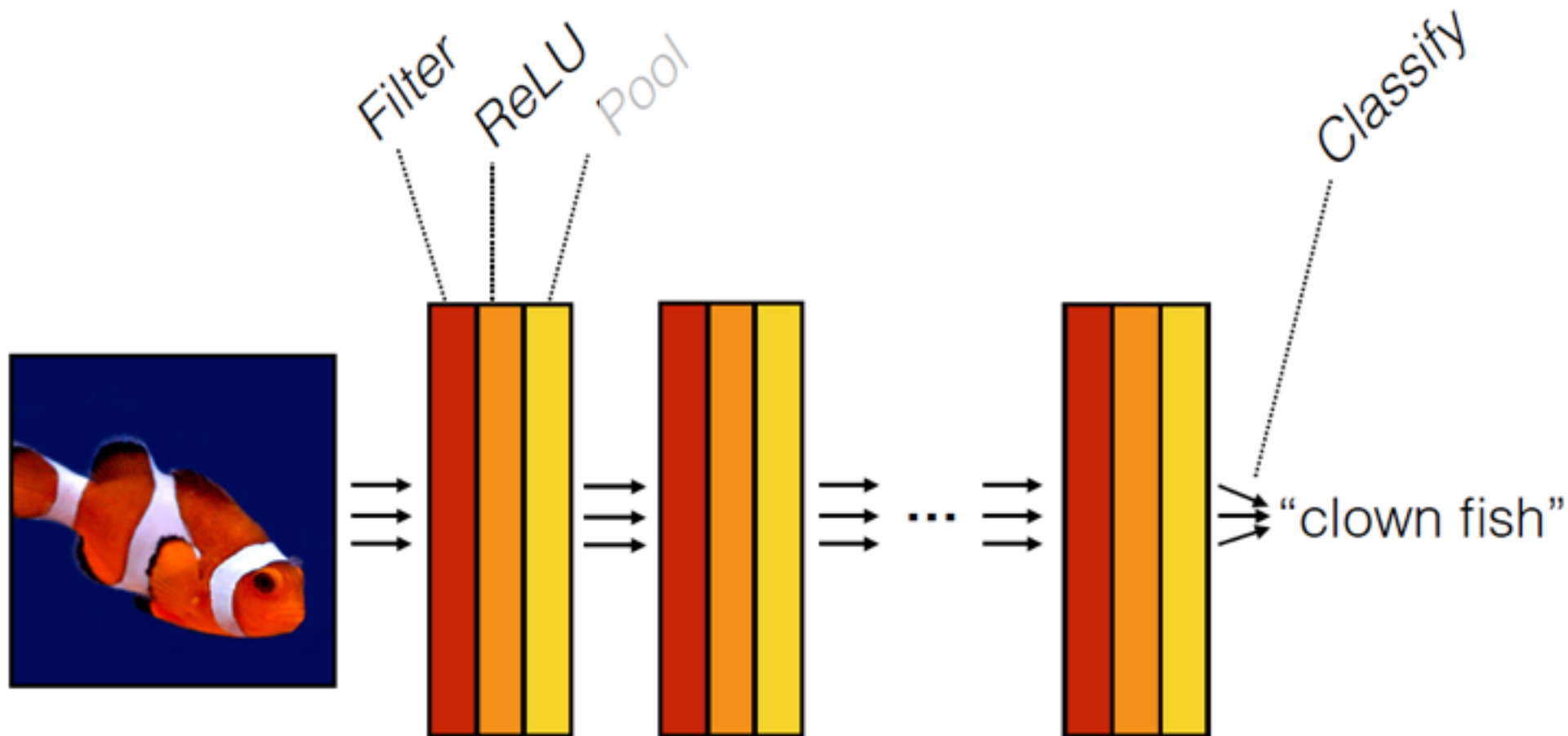
❑ A comparison with real brains offers another, related, challenge to learning theory. Classical “learning algorithms” correspond to one-layer architectures. The cortex suggests a hierarchical architecture.

Thus...are hierarchical architectures with more layers important perhaps for the sample complexity issue?

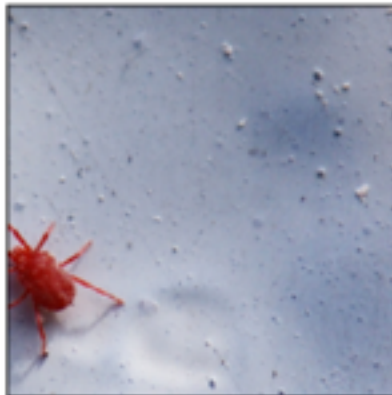
Notices of the American Mathematical Society (AMS), Vol. 50, No. 5, 537-544, 2003.

The Mathematics of Learning: Dealing with Data
Tomaso Poggio and Steve Smale

Computation in a neural net



$$f(\mathbf{x}) = f_L(\dots f_2(f_1(\mathbf{x})))$$



mite

container ship

motor scooter

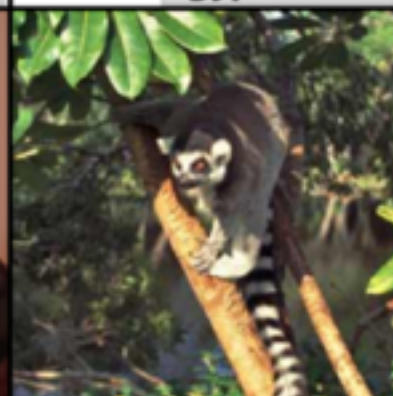
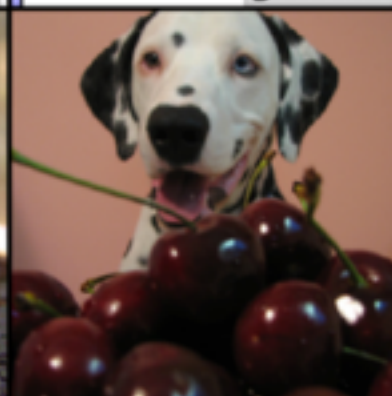
leopard

	mite
	black widow
	cockroach
	tick
	starfish

	container ship
	lifeboat
	amphibian
	fireboat
	drilling platform

	motor scooter
	go-kart
	moped
	bumper car
	golfcart

	leopard
	jaguar
	cheetah
	snow leopard
	Egyptian cat



grille

mushroom

cherry

Madagascar cat

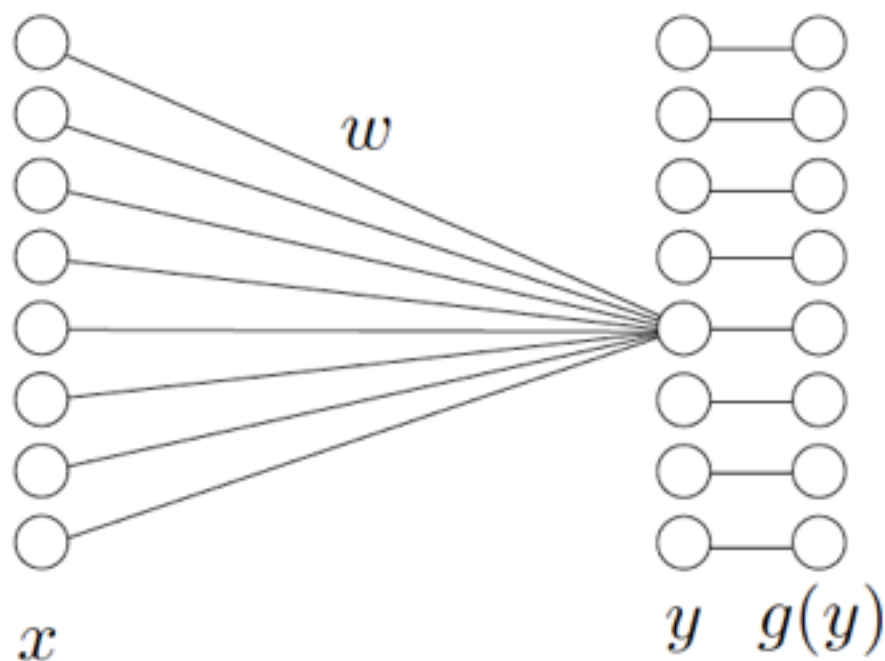
	convertible
	grille
	pickup
	beach wagon
	fire engine

	agaric
	mushroom
	jelly fungus
	gill fungus
	dead-man's-fingers

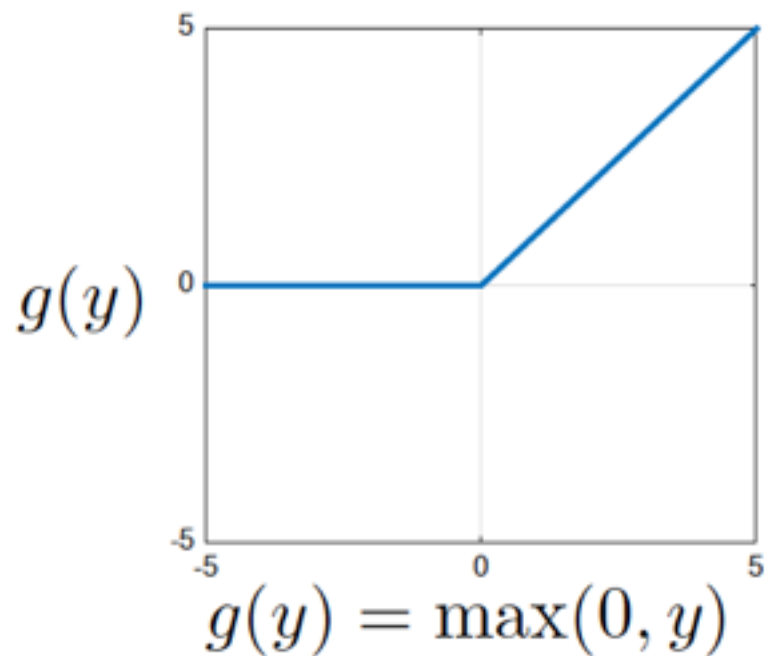
	dalmatian
	grape
	elderberry
	ffordshire bullterrier
	currant

	squirrel monkey
	spider monkey
	titi
	indri
	howler monkey

Computation in a neural net



Rectified linear unit (ReLU)

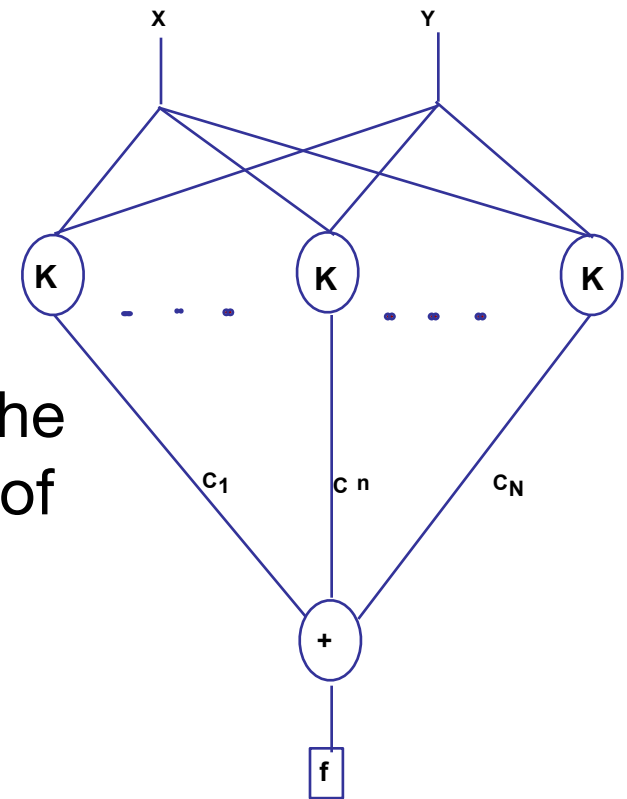


Classical kernel machines are equivalent to shallow networks

Kernel machines...

$$f(\mathbf{x}) = \sum_i^l c_i K(\mathbf{x}, \mathbf{x}_i) + b$$

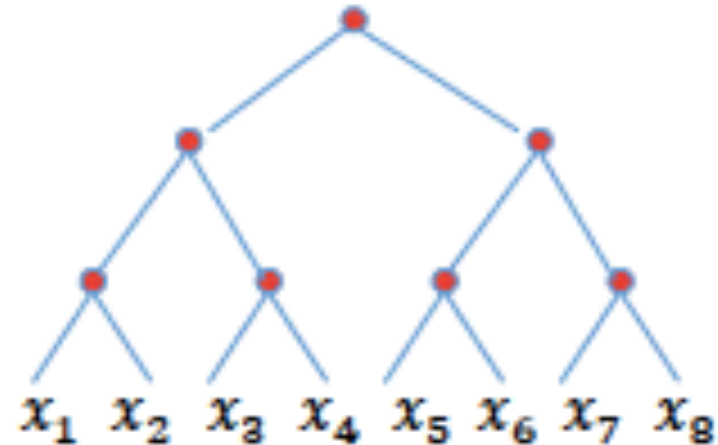
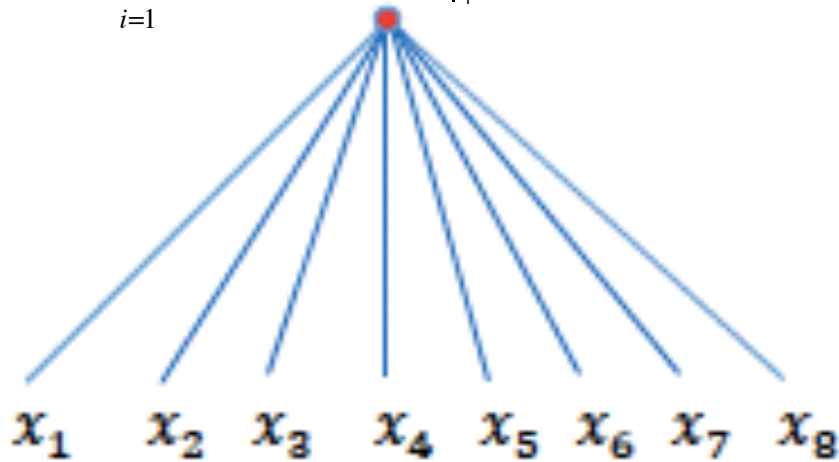
can be “written” as shallow networks: the value of K corresponds to the “activity” of the “unit” for the input and the correspond to “weights”



Deep and shallow networks: universality

Theorem Shallow, one-hidden layer networks with a nonlinear $\phi(x)$ which is not a polynomial are universal. Arbitrarily deep networks with a nonlinear $\phi(x)$ (including polynomials) are universal.

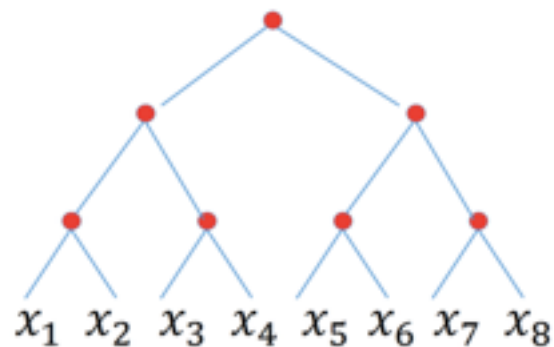
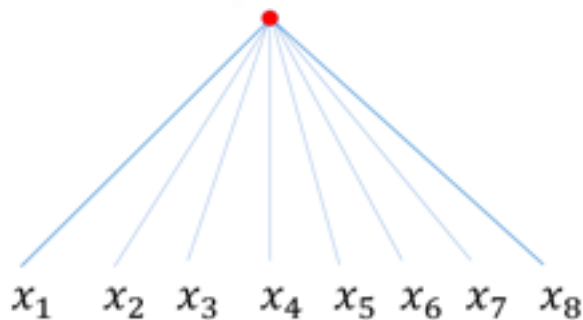
$$g(x) = \sum_{i=1}^r c_i |\langle w_i, x \rangle + b_i|_+$$



Theorem:

why and when are deep networks better than shallow network?

$$f(x_1, x_2, \dots, x_8) = g_3(g_{21}(g_{11}(x_1, x_2), g_{12}(x_3, x_4)), g_{22}(g_{11}(x_5, x_6), g_{12}(x_7, x_8)))$$



Theorem (informal statement)

Suppose that a function of d variables is compositional. Both shallow and deep network can approximate f equally well. The number of parameters of the shallow network depends exponentially on d as $O(\epsilon^{-d})$ with the dimension whereas for the deep network depends linearly on d that is $O(d\epsilon^{-2})$



The curse of dimensionality, the blessing of compositionality

For compositional functions deep networks — but not shallow ones — can avoid the curse of dimensionality, that is the exponential dependence on the dimension of the network complexity and of its sample complexity.

Summary of today's overview

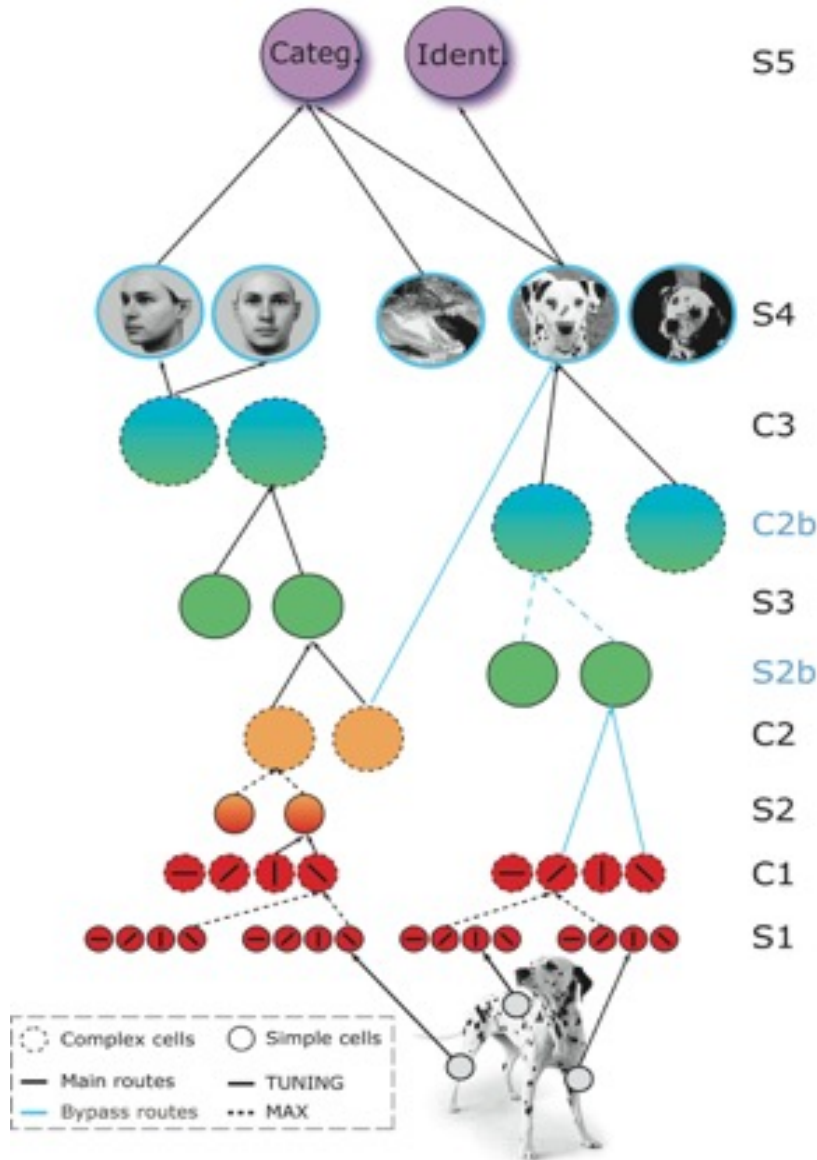
- Motivations for this course: a golden age for new AI, the key role of Machine Learning, CBMM
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CBMM: motivations

Key recent advances
in the engineering of intelligence
have their roots
in basic science of the brain



Recognition in Visual Cortex



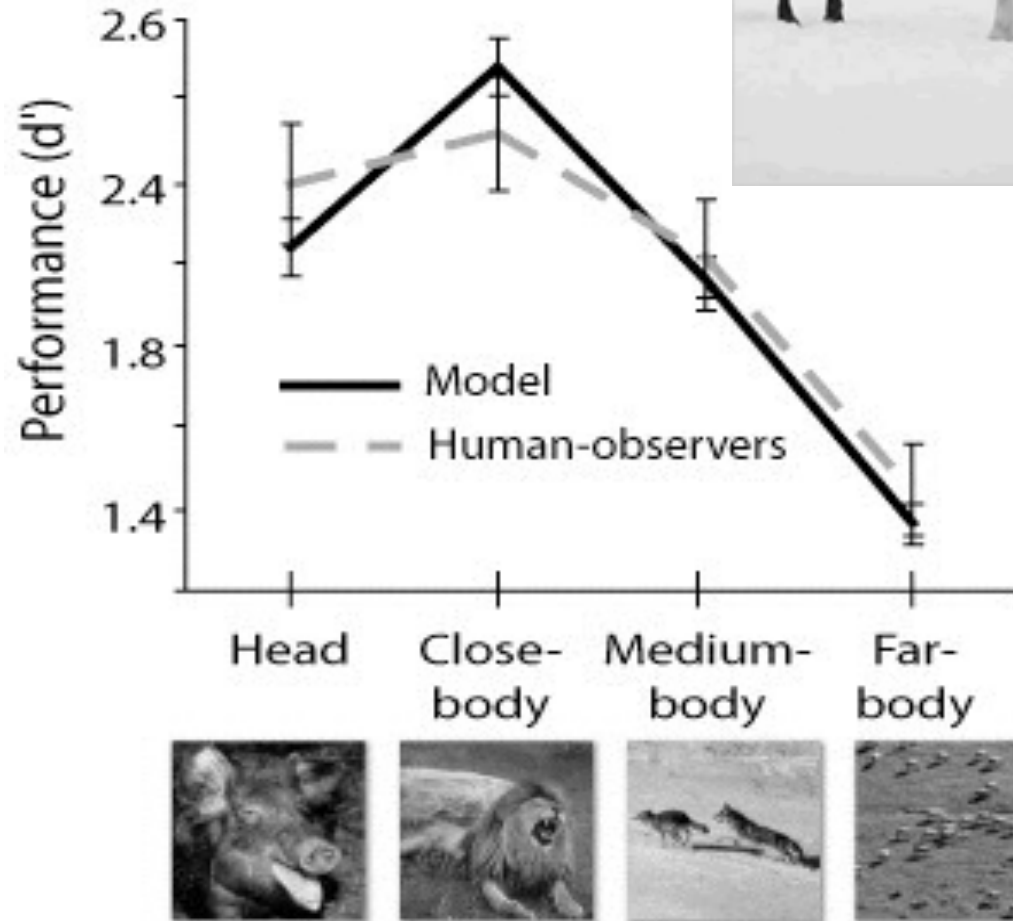
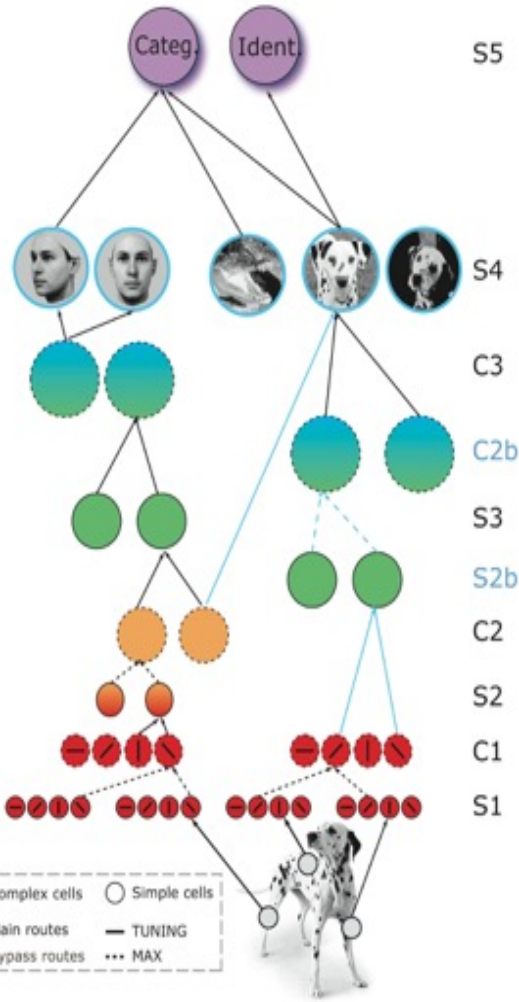
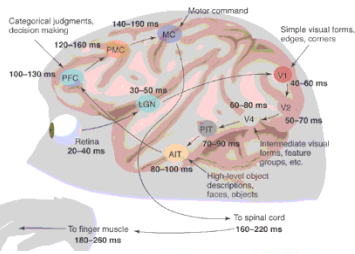
- It is in the family of “Hubel-Wiesel” models (Hubel & Wiesel, 1959: *qual.* [Fukushima](#), 1980: *quant.*; Oram & Perrett, 1993: *qual.*; Wallis & Rolls, 1997; Riesenhuber & Poggio, 1999; Thorpe, 2002; Ullman et al., 2002; Mel, 1997; Wersing and Koerner, 2003; LeCun et al 1998: *not-bio.*; Amit & Mascaro, 2003: *not-bio.*; Hinton, LeCun, Bengio *not-bio.*; Deco & Rolls 2006...)
- As a biological model of object recognition in the ventral stream – from V1 to PFC -- it is *perhaps* the most quantitatively faithful to known neuroscience data

Riesenhuber & Poggio 1999, 2000; [Serre Kouh Cadieu Knoblich Kreiman & Poggio 2005](#); [Serre Oliva Poggio 2007](#)

[software available online]

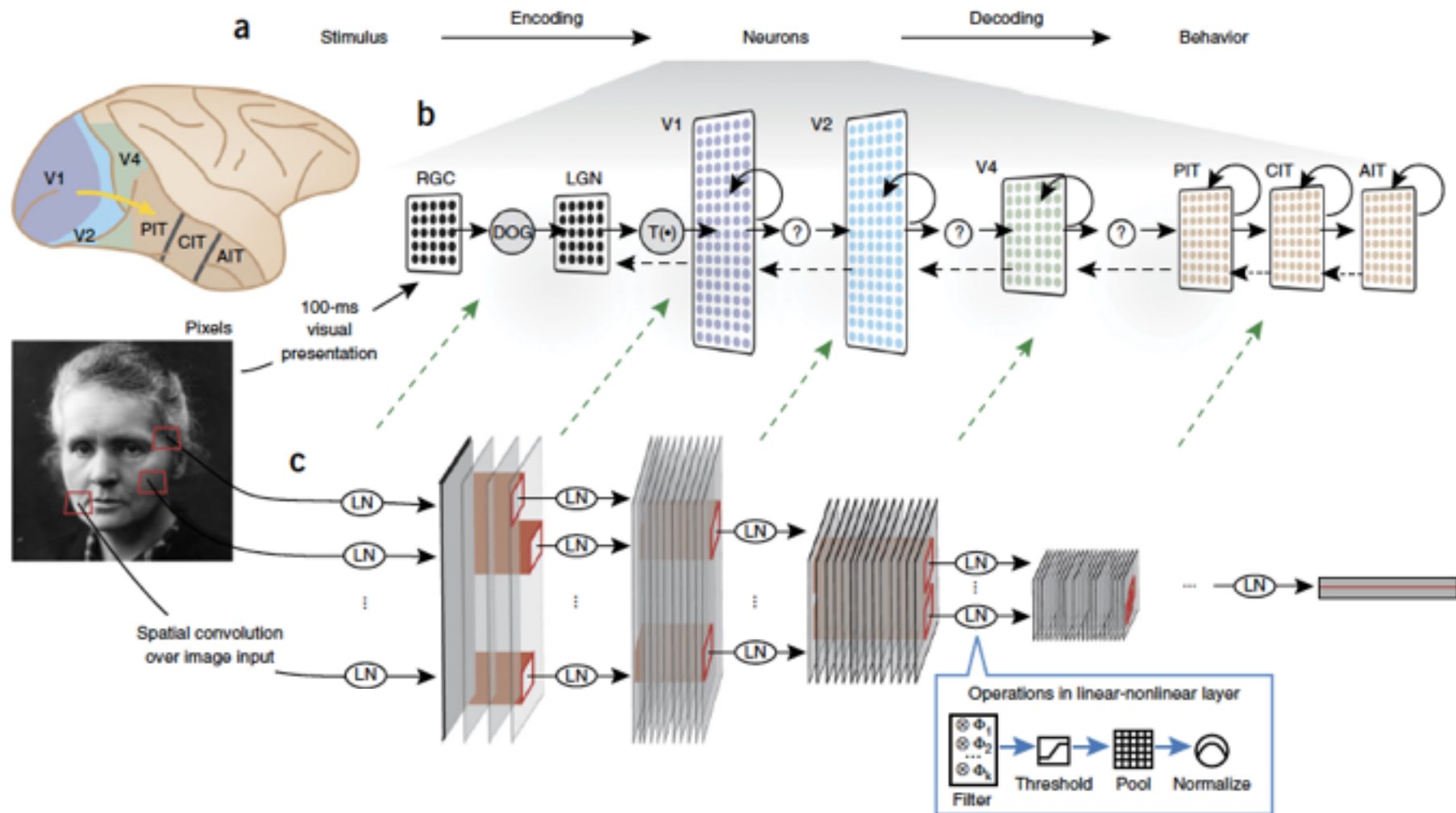
Hierarchical feedforward models of the ventral stream

do “work”



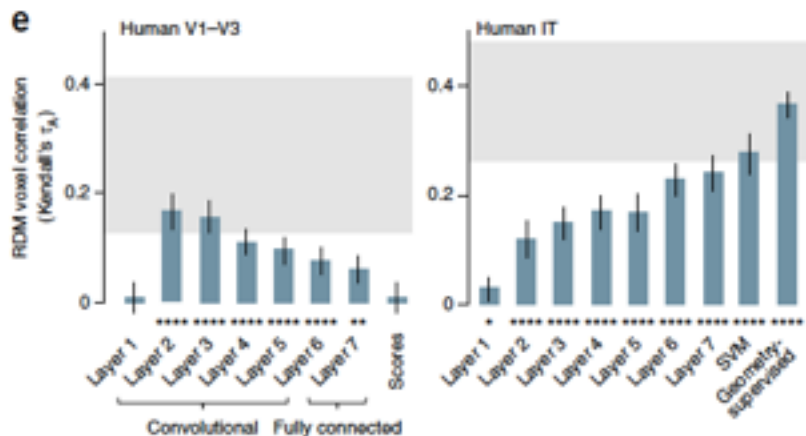
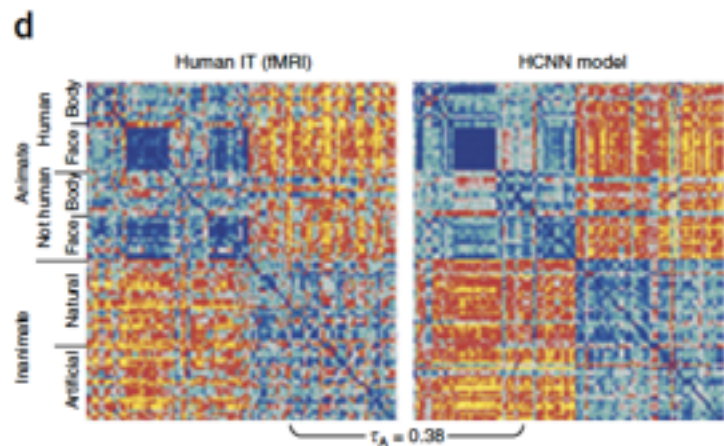
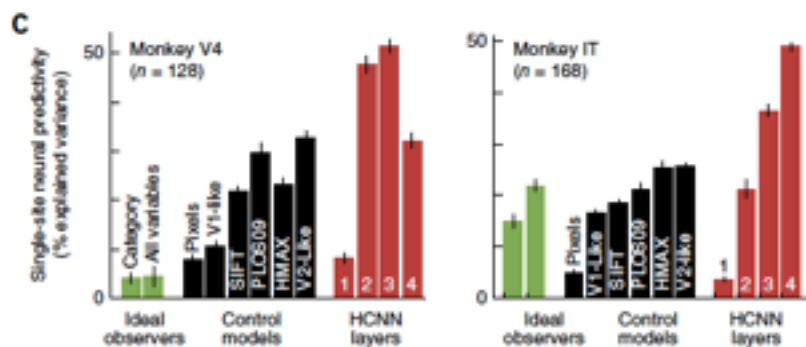
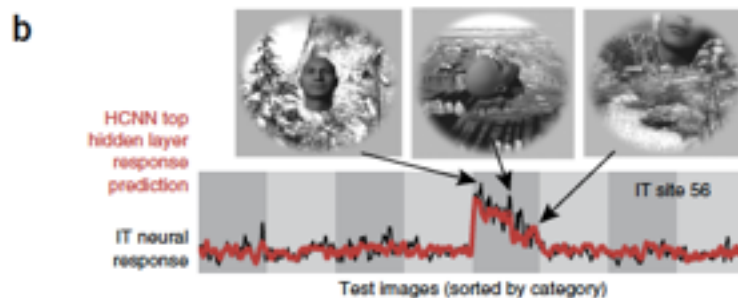
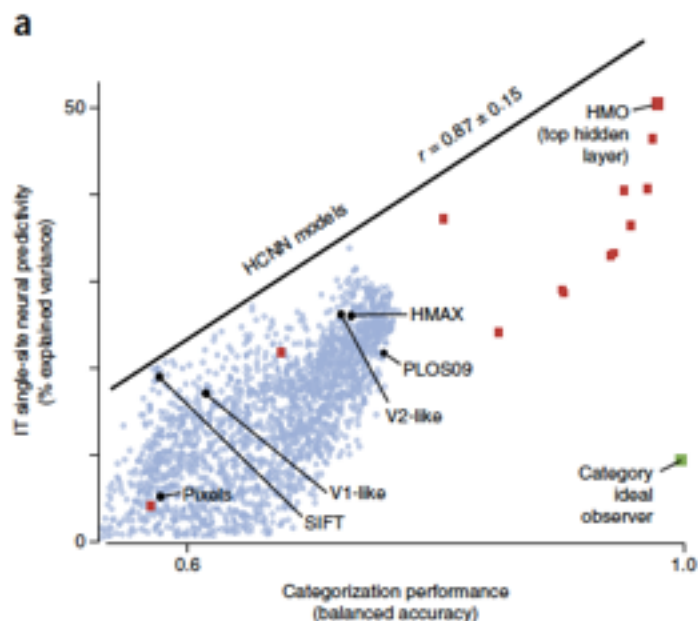
Using goal-driven deep learning models to understand sensory cortex

Daniel L K Yamins^{1,2} & James J DiCarlo^{1,2}



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Classical learning algorithms: “high” sample complexity and shallow architectures

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❑ One of the most obvious differences is the ability of people and animals to learn from very few examples (“poverty of stimulus” problem).

❑ A comparison with real brains offers another, related, challenge to learning theory. Classical “learning algorithms” correspond to one-layer architectures. The cortex suggests a hierarchical architecture.

Thus...are hierarchical architectures with more layers the answer to the sample complexity issue?

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Today's science, tomorrow's engineering: learn like children learn

The first phase (and successes) of ML:

supervised learning, big data: $n \rightarrow \infty$



from programmers...

...to labelers...

...to computers that learn like children...

The next phase of ML: implicitly supervised learning,
learning like children do, small data: $n \rightarrow 1$

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