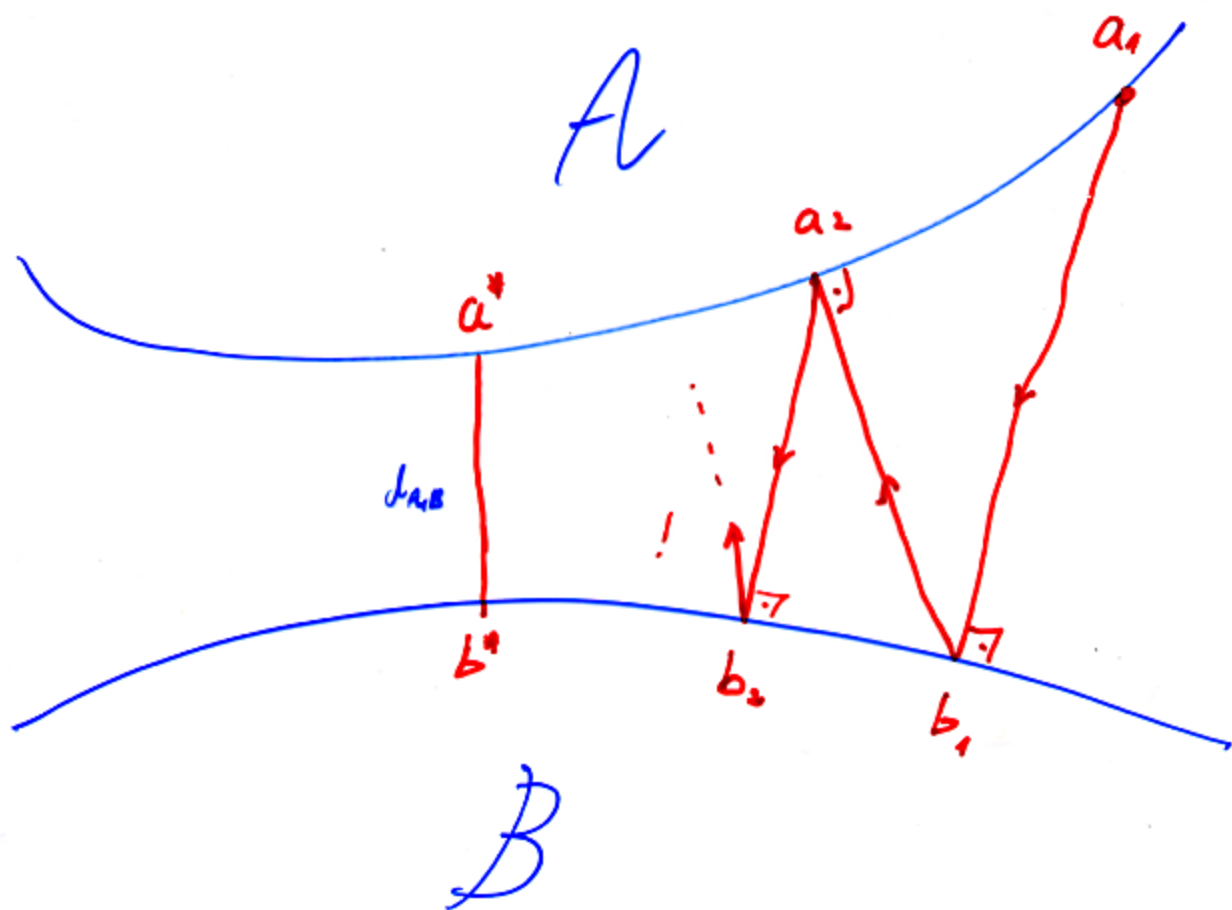


alternating Projections



at

$$a^*, b^* = \arg \min_{\substack{a \in A \\ b \in B}} \|a - b\| \quad \text{achieve } d_{A,B}$$

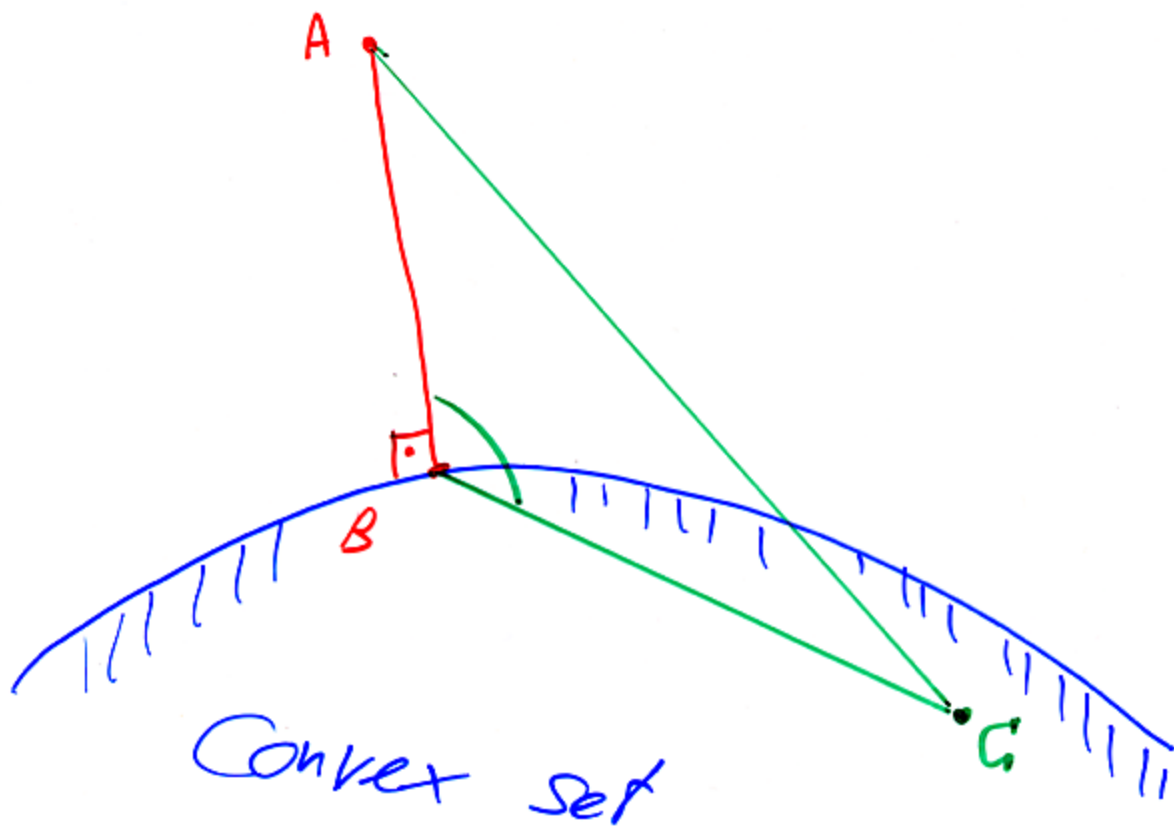
If A and B are convex, then

$$a_1 \rightarrow b_1 \rightarrow a_2 \rightarrow b_2 \rightarrow \dots \quad \begin{aligned} a_{i+1} &= \arg \min_{a \in A} \|a - b_i\| \\ b_i &= \arg \min_{b \in B} \|a_i - b\| \end{aligned}$$

Then

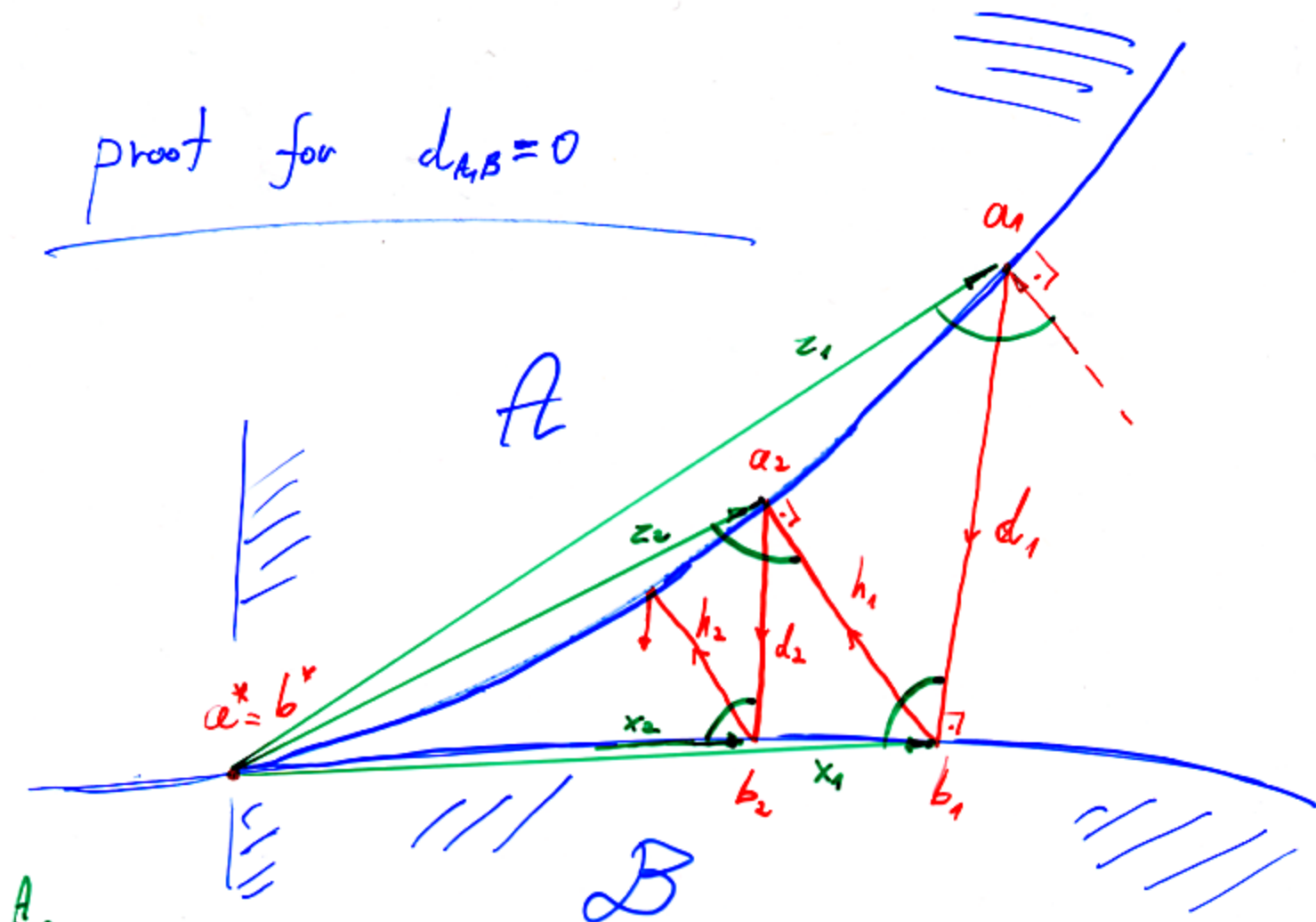
$$a_i \rightarrow a^* \quad b_i \rightarrow b^*$$

* Pythagoras Inequality *



$$\angle > 90^\circ \Rightarrow AB^2 + BC^2 \leq AC^2$$

proof for $d_{AB} = 0$



convexity of sets $\Rightarrow \angle > 90^\circ$

$$\Rightarrow AC^2 > AB^2 + BC^2$$

"Pythagoras Inequality"

$\therefore$

$$z_1^2 \geq d_1^2 + x_1^2$$

$$x_1^2 \geq h_1^2 + z_2^2$$

$$z_2^2 \geq d_2^2 + x_2^2$$

$\vdots$

$$\therefore z_1^2 \geq z_{i+1}^2 + d_i^2 + h_i^2 + d_{i+1}^2 + \dots + h_n^2 + d_n^2 \quad \forall i$$

$$\therefore \sum_{i=1}^{\infty} h_i^2 + d_i^2 \leq z_1^2$$

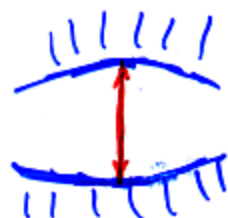
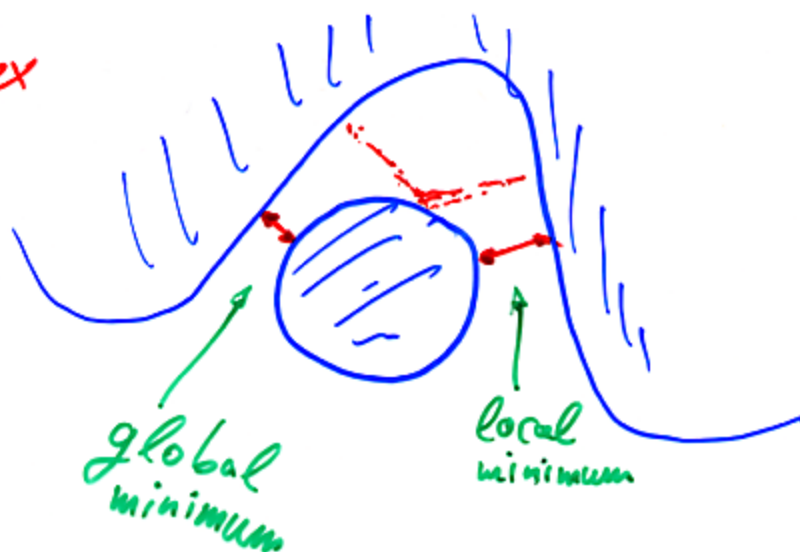
$$\therefore (\text{non-negative series}) \quad h_i, d_i \rightarrow 0$$

$$\Rightarrow \begin{matrix} \text{(unique minimum)} \\ a_i \rightarrow a^*, b_i \rightarrow b^*, z_i \rightarrow 0 \end{matrix}$$

assume $z_1 < \infty$

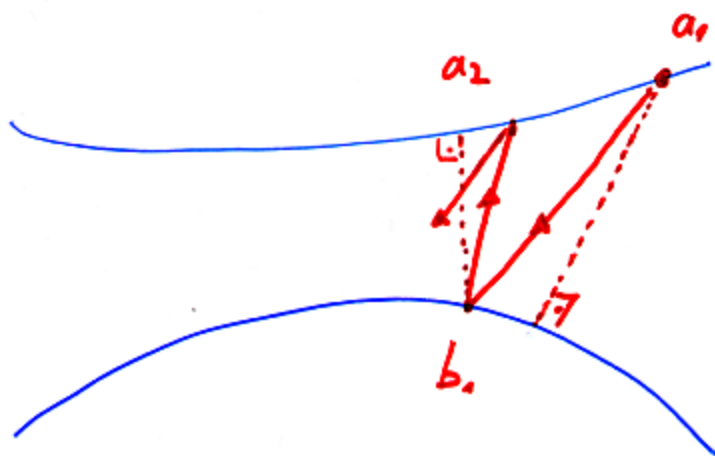
Bad Cases ...

1) non convex sets

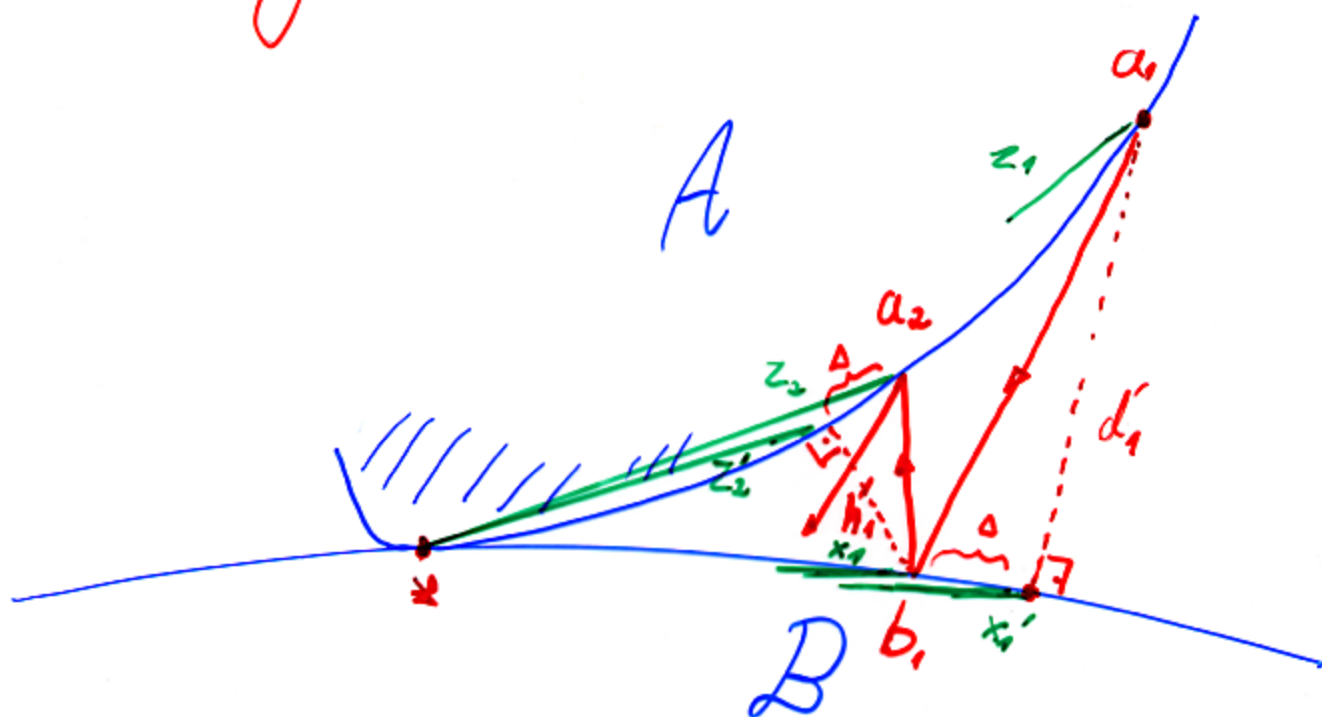


non-stable
fixed
point

2) non accurate
projections



Noisy (non accurate) Projections



$d_i', h_i' = \text{true projection distance}$ (ideal)
 $z_i, x_i = \text{actual distance from optimum}$
 $z_i', x_i' = \text{distance of true projection}$ " " "

Suppose $|x_i^2 - x_i'^2| < \Delta^2$, $|z_i^2 - z_i'^2| < \Delta^2$

$$\Rightarrow z_i^2 \geq \sum_{i=1}^m (d_i'^2 + h_i'^2 - \Delta^2) \quad \forall m$$

$$\Rightarrow \liminf_i [d_i'^2 + h_i'^2 - \Delta^2] \leq 0$$

gradient descent
in L.M.S.

[2] "Black Hole" : $A_\infty(\Delta)$: $a_i \in A_\infty(\Delta) \Rightarrow a_{i+1} \in A_\infty(\Delta)$

Aspects to think about....

* desired optimum $\stackrel{?}{=}$ fixed point
 $\stackrel{?}{=}$ stable point (stability region)
 $\stackrel{?}{=}$ unique fixed point

* projection rule (metric) vrs. true optimality criterion

* physical meaning of intermediate quantities:

$$a_1 \rightarrow b_1 \rightarrow a_2 \rightarrow b_2 = ?$$

$$z_i, x_i, h_i, d_i = ?$$

Divergence "Pythagoras Theorem"

If E = closed and convex set of probability distributions

$$Q \notin E$$

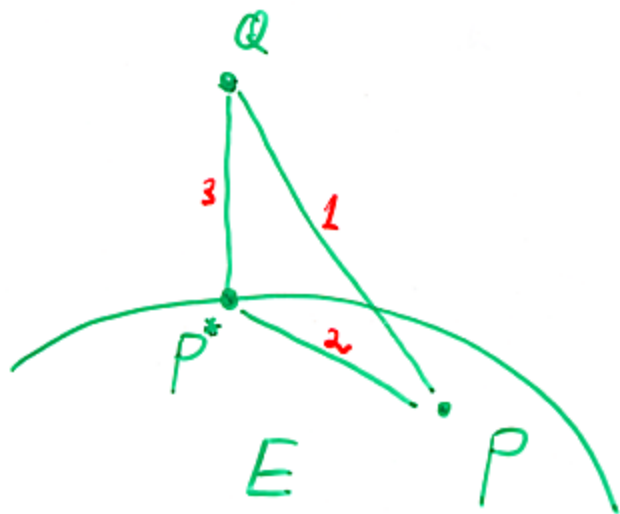
$p^* \in E$ is closest to Q in divergence sense

$$D(p^* \| Q) = \min_{p \in E} D(p \| Q)$$

Then for any $p \in E$

$$D(p \| Q) \geq D(p \| p^*) + D(p^* \| Q)$$

1 2 3



Recall that for $p \geq 0, q \geq 0$

$$D(p||q) \triangleq \sum_x p(x) \log \frac{p(x)}{q(x)}$$

— If p, q are prob. measures* ($\sum p = \sum q = 1$) $\rightarrow$
 $D(p||q) \geq 0$ with eq. iff $p = q$

— not a metric!

$$* D(p||q) \neq D(q||p)$$

not symmetric

* no triangle inequality

— $D(p||q) \leq \log \frac{1}{q_{\min}} \Rightarrow$ bounded if $q_{(x)} > 0 \forall x$

* if $\sum p \neq 1, \sum q \neq 1$ Then "modified pythagoras" hold.

Csiszar - Tusnady Theorem

$\mathcal{P}, \mathcal{Q}$ ^{closed} convex sets of measures
(not necessarily of unit sum)
 $Q_0(x) > 0 \quad \forall x \in \mathcal{X} \quad |\mathcal{X}| < \infty$

$$P_n = \arg \min_{P \in \mathcal{P}} D(P \| Q_{n-1}) \quad n=1, 2, \dots$$

$$Q_n = \arg \min_{Q \in \mathcal{Q}} D(P_n \| Q) \quad n=1, 2, \dots$$

i.e., $Q_0 \rightarrow P_1 \rightarrow Q_1 \rightarrow P_2 \rightarrow \dots$
sequence of alternating minimizations

Then

$$\lim_{n \rightarrow \infty} D(P_n \| Q_n) = D(P \| Q) \triangleq \min_{P \in \mathcal{P} \quad Q \in \mathcal{Q}} D(P \| Q) \\ \triangleq D(P^* \| Q^*)$$

a minimizing pair

~~Furthermore~~ $P_n \rightarrow P^*, \quad Q_n \rightarrow Q^*$

E.M.

$$\max_{\theta} f(\underline{y} | \theta) \quad \text{given } \underline{y} = y_1 \dots y_n$$

$$f(\underline{y} | \theta) = \int q(x, \underline{y} | \theta) dx$$

$$\iff \max_{p(\underline{x})} \max_{\theta} \int p(\underline{x}) \log \frac{q(\underline{x}, \underline{y} | \theta)}{p(\underline{x})} dx$$

marginalizing $p(\cdot)$

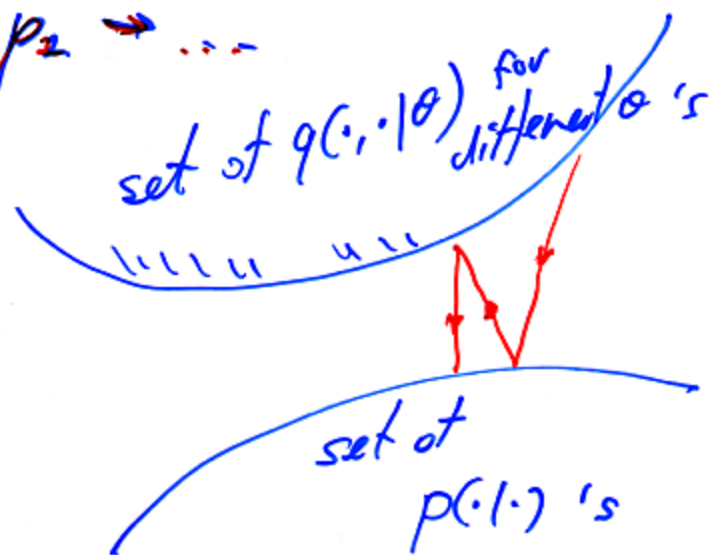
can only
increase
likelihood

$$\iff \max_{p(\underline{x} | \underline{y})} \max_{\theta} -E_{\underline{y}(\underline{y})} D(p(\cdot | \underline{y}) \| q(\cdot, \underline{y} | \theta))$$

empirical
measure of $\underline{y}$

$$\theta_0 \rightarrow p_1 \rightarrow \theta_1 \rightarrow p_2 \rightarrow \dots$$

converges if $q(\cdot, \cdot | \theta)$
is convex set w.r.t. θ .



R-D = computation

$$R(D) = \min I(p, w)$$

$$w: E_{p,w} d(x, y) \leq D$$

$$p = p(x)$$

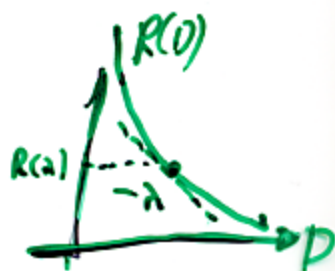
$$w = w(y|x)$$

= the minimum rate is compressing a source $X \sim p$ with distortion $\leq D$ w.r.t. distortion measure $d(\cdot, \cdot)$

$R(D) = I(p, w^*)$: $Q^* = [p \circ w]_y$ is the optimum reproduction = codebook distribution

unconstrained version

$$R(\lambda) \triangleq \min_w [I(p, w) + \lambda \cdot \underbrace{d(p, w)}_{E_{p,w} d(x, y)}]$$



$$D(p \circ w \parallel p_x \underbrace{[p \circ w]_y}_{Q(y)} \cdot \underbrace{e^{-\lambda d(x, y)}}_{Q^*(x|y)})$$

Blahut A for $R(\lambda)$

$$\iff \min_w \min_Q D(p \circ w_{(x,y)} \parallel p_x \times Q_{(y)} \cdot e^{-\lambda d(x,y)})$$

$$Q_0 \rightarrow \underbrace{w_1}_{\text{easy}} \rightarrow Q_1 \rightarrow \underbrace{w_2}_{\text{easy}} \rightarrow Q_2 \rightarrow \dots$$



Physical meaning

constrained problem:

$$R(D) = \min_{w: d(p, w) \leq D} \min_Q D(p \circ w \parallel p \times Q)$$

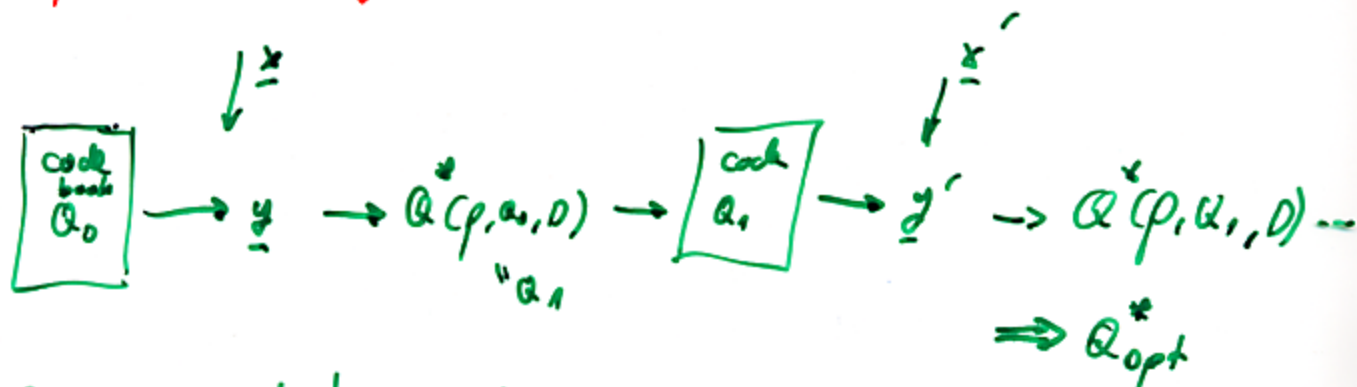
Define $R(p, Q, D) = \min_{w: d(p, w) \leq D} D(p \circ w \parallel p \times Q)$

$$Q^*(p, Q, D) = [p \circ w^*]_2$$



$R(p, Q, D)$ = rate of mismatched codebook

$Q^*(p, Q, D)$ = limiting ^{w.p. 1} empirical distribution of D -matching codeword.



* practical implementation using parametric codebook...

C - computation

$$C = \max_P I(p, w)$$

= maximum rate in transmission over channel in w .

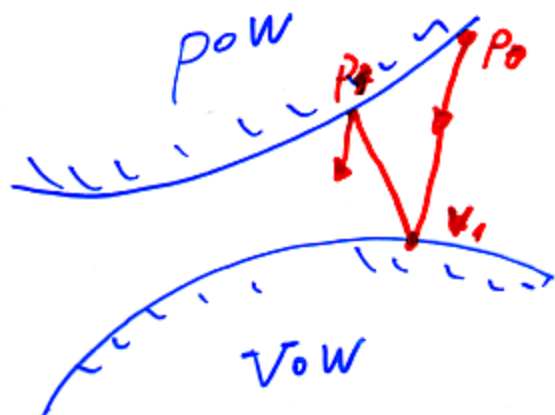
$C = I(p^*, w)$: p^* is the optimum ^{input =} codebook distribution.

Arimoto - Blahut for C :

$$\Leftrightarrow C = \max_P D(p \circ w \parallel \underbrace{p \times [p \circ w]_y}_{Q(y)})$$

$$= \max_P \underbrace{\max_V D(p \circ w \parallel V \circ w)}_{\max = I(p, w)} \quad V(x|y)$$

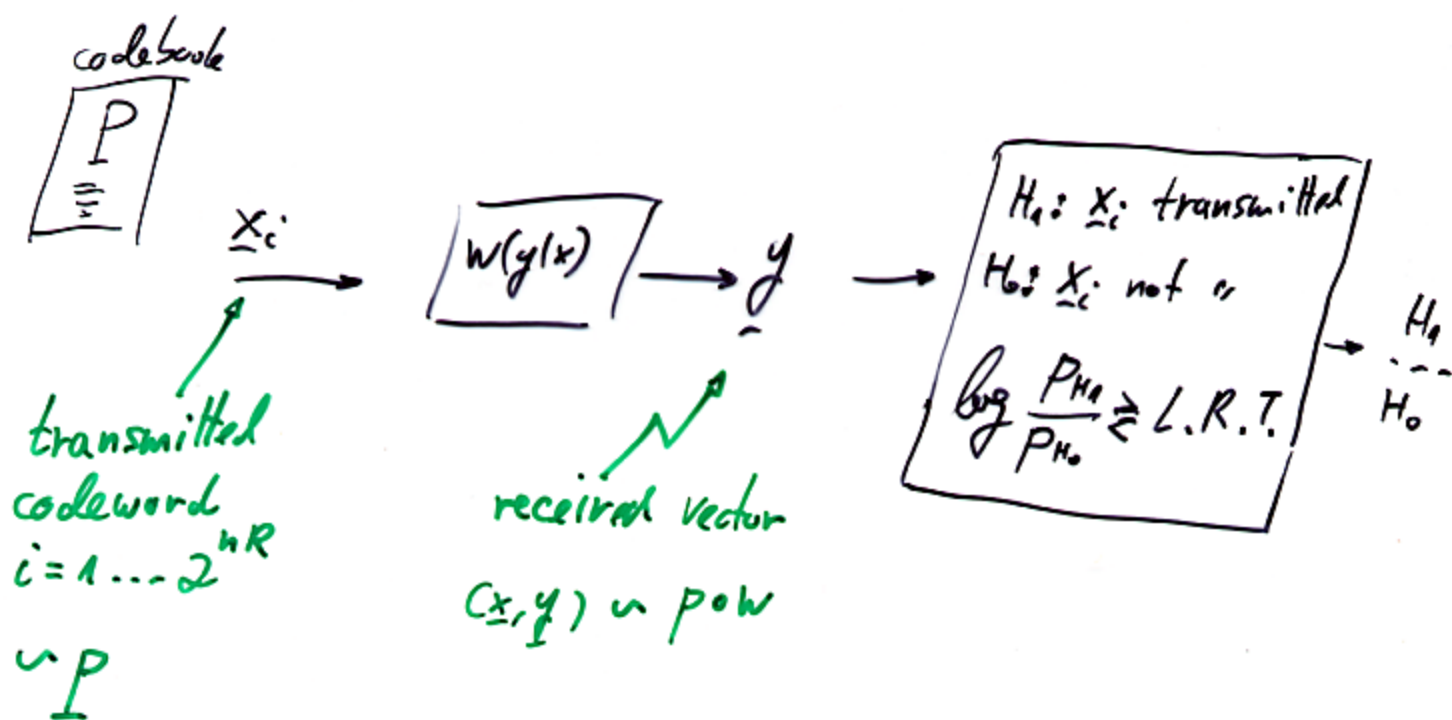
$P_0 \rightarrow V_1 \rightarrow P_1 \rightarrow V_2 \rightarrow \dots$
 (easy induced backward) easy



Physical Meaning?

Q: Does $-D(p_{ow} \| v_{ow})$ represent an empirically measurable quantity?

$$\sum_x \sum_y p(x) w(y|x) \log \frac{V(x|y)}{p(x)}$$



* suppose receiver estimates backward channel as $V(x|y)$

$$\Rightarrow \text{L.R.} = \frac{1}{n} \sum_{j=1}^n \log \frac{V(x_j | y_j)}{p(x_j)} \approx \sum_x \sum_y p(x) w(y|x) \log \frac{V(x|y)}{p(x)}$$

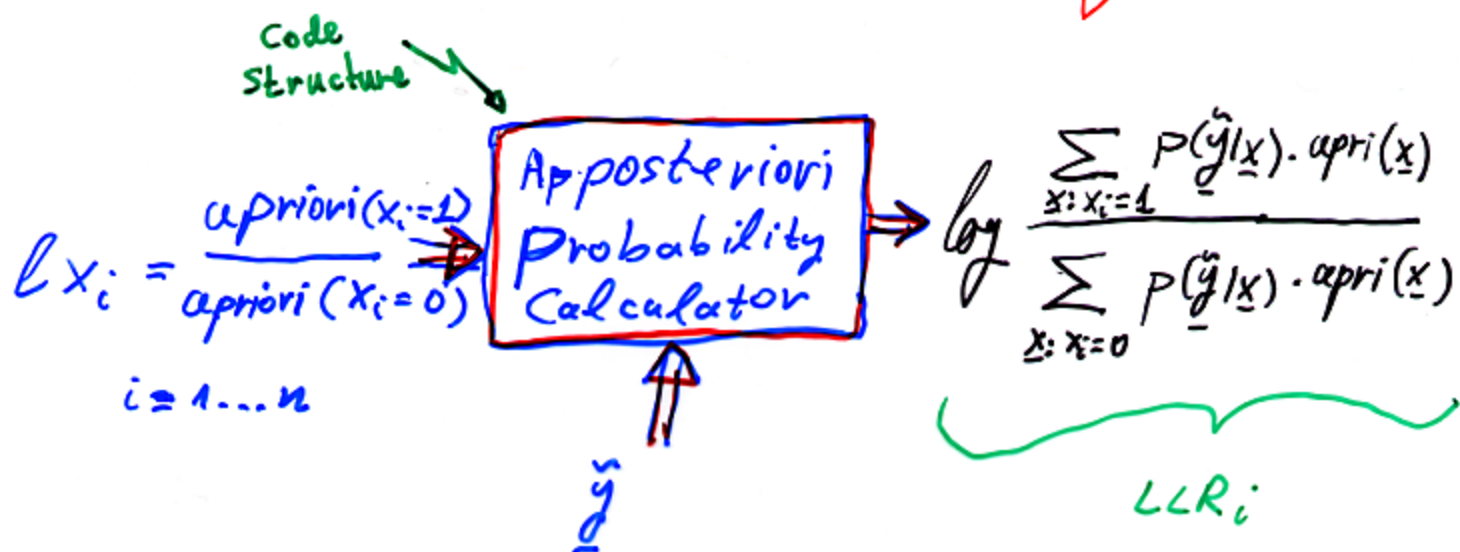
with high prob.

Can we realize/simulate $p_0 \rightarrow v_1 \rightarrow p_1 \rightarrow v_2 \rightarrow \dots$?

alternating optimizations :

geometric meaning	physical meaning	
✓	✓	EM
✓	✓	R-D
✓	?	G
?	✓	turbo-leading

* Turbo Decoding *



Define : $\underline{LLR} = D(\underline{l}_x, \underline{\tilde{y}})$

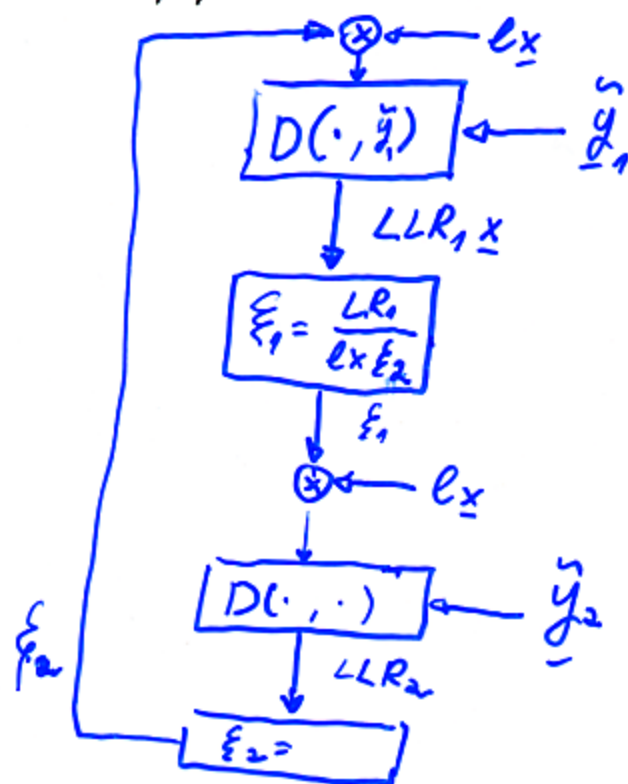
Iterative decoding (recursive LLR computation):

$$LLR_{1i}^{(k)} = D(\underline{l}_x \xi_{2i}^{(k-1)}, \underline{\tilde{y}}_1) \triangleq l_{x_i} \cdot \xi_{1i}^{(k)} \cdot \xi_{2i}^{(k-1)}$$

$$LLR_{2i}^{(k)} = D(\underline{l}_x \xi_{1i}^{(k)}, \underline{\tilde{y}}_2) \triangleq l_{x_i} \cdot \xi_{1i}^{(k)} \cdot \xi_{2i}^{(k)}$$

$i=1 \dots n \quad k=1, 2, 3, \dots$

$\xi_1^{(0)} = 1$

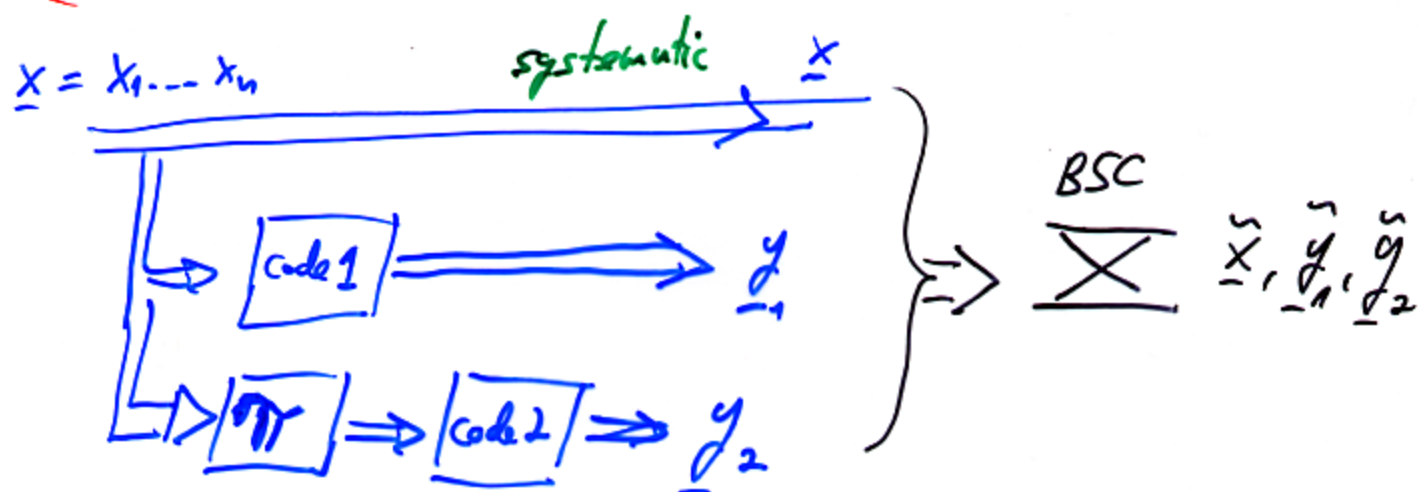


extrinsic info for next iteration ("LLR amplification")

steady state (fixed point)

$LLR_1 = LLR_2 = \text{constant}$

Turbo Code



$$P(\underline{\tilde{x}}, \underline{\tilde{y}}_1, \underline{\tilde{y}}_2 | \underline{x}) = P(\underline{\tilde{x}} | \underline{x}) \cdot P(\underline{\tilde{y}}_1 | \underline{x}) \cdot P(\underline{\tilde{y}}_2 | \underline{x})$$

memoryless $\Rightarrow \underline{\tilde{y}}_i = \text{func}(\underline{x})$

optimal decoding:

1) sequence-wise: $\hat{\underline{x}}_{\text{M.L.}} = \arg \max_{\underline{x}} P(\underline{\tilde{x}}, \underline{\tilde{y}}_1, \underline{\tilde{y}}_2 | \underline{x})$

2) bit-wise: $\hat{x}_{i \text{ M.L.}} = \arg \max_{x_i} P(\underline{\tilde{x}}, \underline{\tilde{y}}_1, \underline{\tilde{y}}_2 | x_i) \text{ for } i = 1, \dots, n$

$$\Leftrightarrow \log \frac{\sum_{\underline{x}: x_i=1} P(\underline{\tilde{x}}, \underline{\tilde{y}}_1, \underline{\tilde{y}}_2 | \underline{x})}{\sum_{\underline{x}: x_i=0} P(\underline{\tilde{x}}, \underline{\tilde{y}}_1, \underline{\tilde{y}}_2 | \underline{x})} \begin{matrix} \hat{x}_i=1 \\ > 0 \\ < 0 \\ \hat{x}_i=0 \end{matrix}$$

L.L.R._i

Q: when $\hat{x}_{i \text{ M.L.}} \neq (\hat{\underline{x}}_{\text{M.L.}})_i$? ... ☺

Abstraction: Projections on Product Measures

n -length real vector $\rightarrow p_0(\underline{x}) \triangleq \sum_{i=1}^n \log p(\tilde{x}_i | x_i) = \text{"product measure"}$

2^{n-1} length real vectors $\rightarrow p_1(\underline{x}) \triangleq \log p(\tilde{y}_1 | \underline{x})$ (non product)

$\rightarrow p_2(\underline{x}) \triangleq \log p(\tilde{y}_2 | \underline{x})$ (non product)

* marginalization:

$$\pi(p(\underline{x})) \triangleq \sum_{\substack{x_1, x_2, \dots, x_n \\ \underbrace{\quad}_{p(\underline{x}_i)}}} \log \sum_{x_i} \exp p(\underline{x}) = \text{the induced product ("memoryless") measure}$$

M.L.:

$$\Rightarrow \hat{x}_{M.L.i} = \arg \max_{x \in \{0,1\}} \pi(p_0 + p_1 + p_2)_i(x)$$

Turbo:

$Q_1(\underline{x}), Q_2(\underline{x}) = \text{"log-likelihood amplification"} = \text{product measures} \quad \left(\xi_{1i} = \frac{\exp Q_{1i}(1)}{\exp Q_{1i}(0)} \right)$

$$Q_2^{(0)} \equiv 1$$

$$Q_1^{(k)} = \pi(p_0 + Q_2^{(k-1)} + p_1) - (p_0 + Q_2^{(k-1)})$$

$$Q_2^{(k)} = \pi(p_0 + Q_1^{(k)} + p_2) - (p_0 + Q_1^{(k)})$$

$$k = 1, 2, 3, \dots$$

$$LLR^{(k)} = \pi(p_0 + Q_2^{(k+1)} + p_1) \text{ or } \pi(p_0 + Q_1^{(k)} + p_2)$$

Fixed point of Turbo iteration

Given P_0, P_1, P_2 ($\log$ likelihood ^{measures} of x)

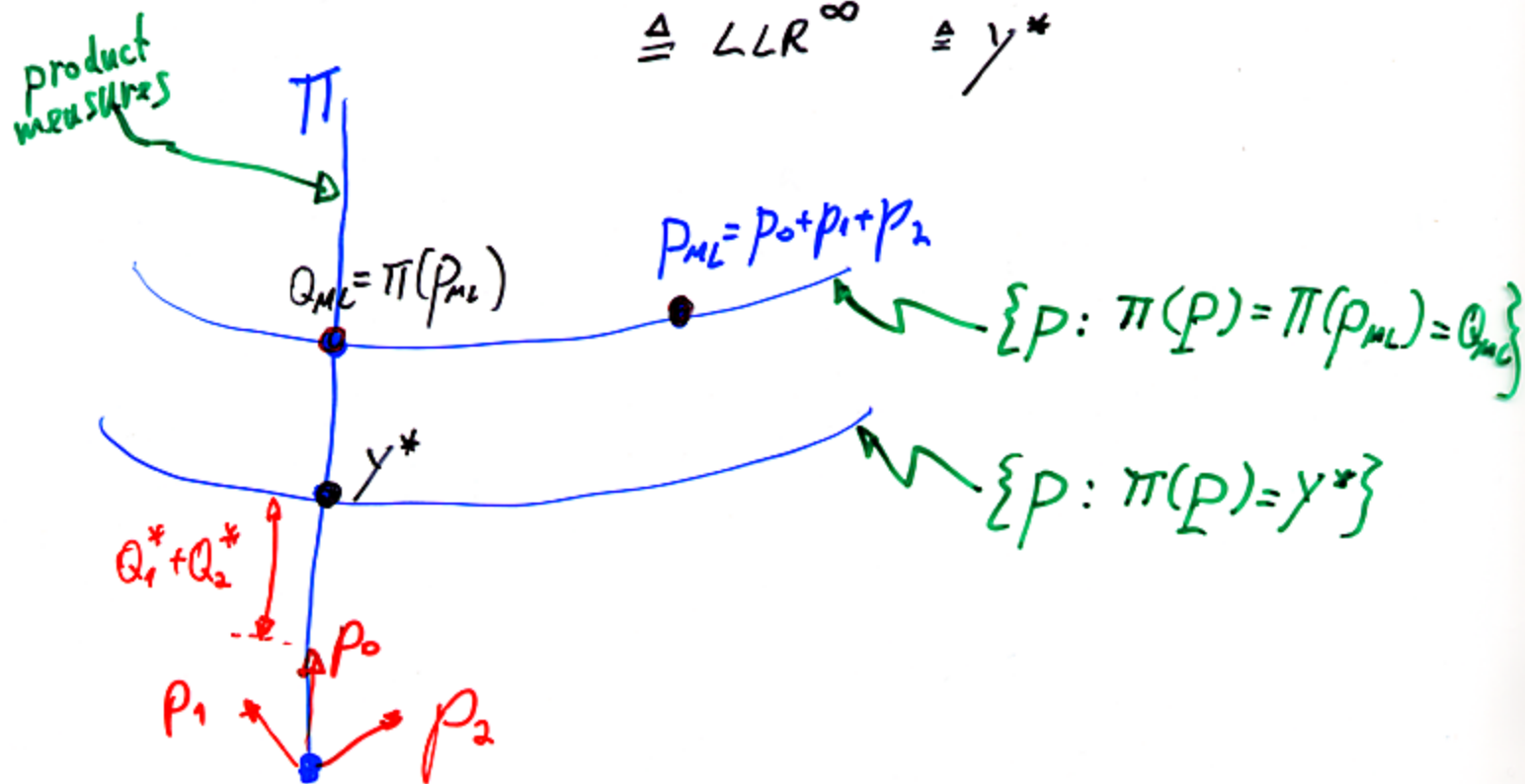
Find product measures Q_1, Q_2 ($\Rightarrow$ find two vectors in $\mathbb{R}^n$)
such that iteration does not change their values;

$$Q_1 = \pi(P_0 + Q_2 + P_1) - (P_0 + Q_2)$$

$$Q_2 = \pi(P_0 + Q_1 + P_2) - (P_0 + Q_1)$$

2n equations with 2n unknowns... $\Rightarrow Q_1^*, Q_2^*$

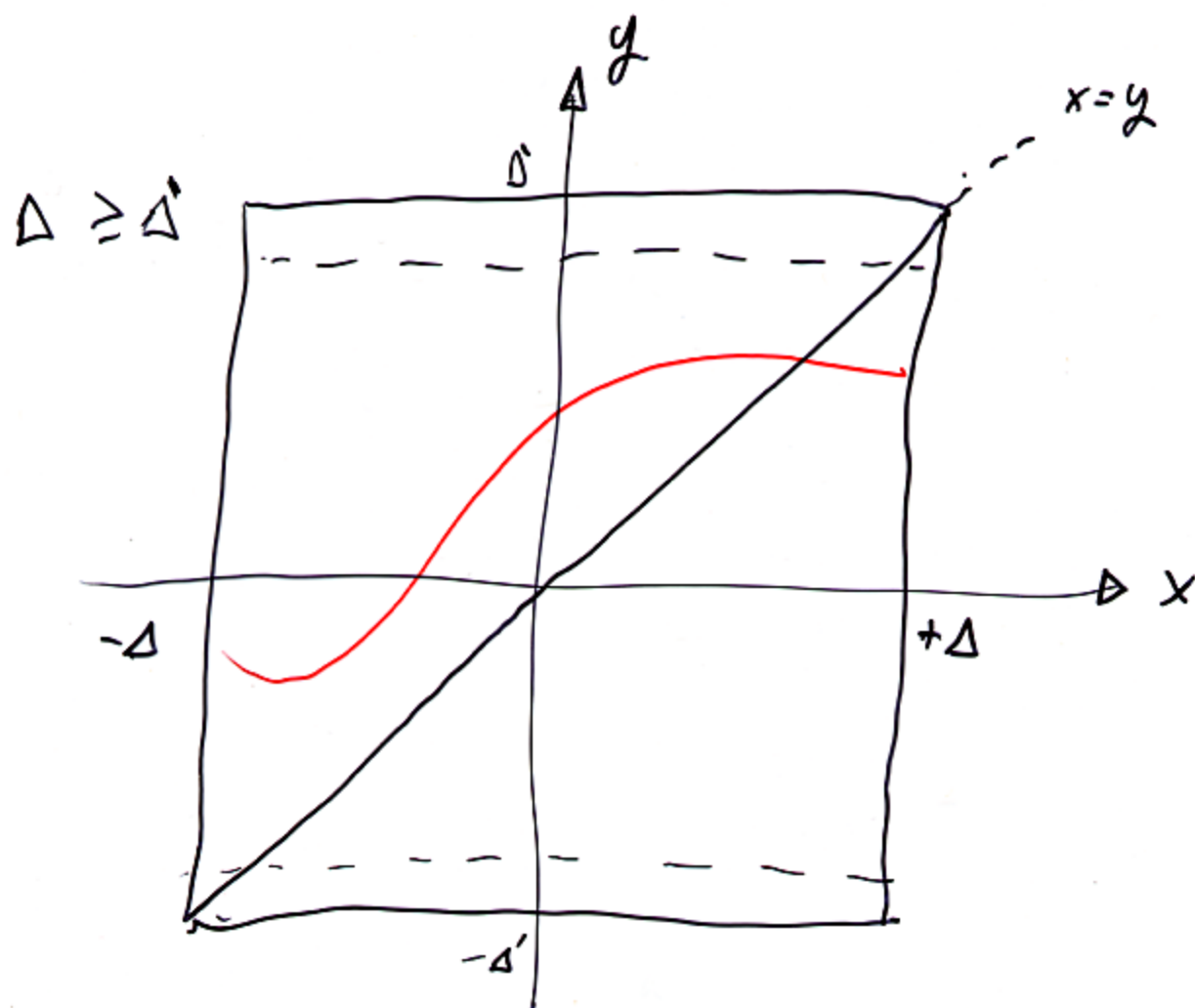
$$\Rightarrow \pi(P_0 + Q_2^* + P_1) = \pi(P_0 + Q_1^* + P_2) = P_0 + Q_1^* + Q_2^* \\ \triangleq LLR^\infty \triangleq y^*$$



How do we know that Q_1^*, Q_2^* exist?

$F: S \rightarrow S'$ continuous function

S set (ball) in $\mathbb{R}^n$; $S' \subseteq S$



Brouwer fixed point theorem: $\exists x \in S$

s.t. $F(x) = x$