

Dyson
Brownian
Motion

①

2/20/13

Sym Eig Pert Theory

Differentiate $Aq = \lambda q$

$A' = E$
with $A'' = 0$ for simplicity
 A is a "line" of Matrices

$$A(t) = A + Et$$

$$q^T q' = 0 = q^T q'' = \dots$$

der

$$1 \quad Eq + Aq' = \lambda' q + \lambda q'$$

$$2 \quad 2Eq' + Aq'' = \lambda'' q + 2\lambda' q' + \lambda q''$$

$$3 \quad 3Eq'' + Aq''' = \lambda''' q + 3\lambda'' q' + 3\lambda' q'' + \lambda q'''$$

$$q^T E q^{(k)} = \lambda^{(k)}$$

$$\lambda' = q^T E q^{(1)}$$

$$\lambda'' = q^T E q^{(2)}$$

$$Eq + Aq^{(1)} = q^T E q + \lambda q^{(1)}$$

$$(A - \lambda I)q^{(1)} = -(I - q q^T)Eq \quad \text{An equation in } q^{\perp}$$

$$q^{(1)} = -(A - \lambda I)^{\perp} Eq$$

$$\lambda' = -2q^T E (A - \lambda I)^{\perp} Eq$$

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Without loss of generality assume
 $A = \text{diagonal} = (\lambda_1, \dots, \lambda_n)$

$$\lambda_i' = E_{ii}$$

$$\lambda_i'' = - \sum_{j \neq i} \frac{E_{ij}^2}{\lambda_j - \lambda_i}$$

Add a little GOE matrix

$$c \cdot \sqrt{h} \cdot \begin{bmatrix} a & a/\sqrt{2} & & \\ a/\sqrt{2} & & & \\ & & \ddots & \\ & & & \ddots \end{bmatrix}$$

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$$d\lambda_i = c \cdot \sqrt{h} (G_{ii})$$

$$c \cdot dW - \frac{1}{2} h c^2 \sum_{j \neq i} \frac{h^2}{\lambda_j - \lambda_i}$$

↙
do use case
this is 1

$$d\lambda_i = c dW_i - dt \frac{c^2}{2} \sum_{j \neq i} \frac{1}{\lambda_j - \lambda_i}$$

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Eigenvectors as a change of variables

$$S = \begin{bmatrix} p & s \\ s & r \end{bmatrix} = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

$$p, r, s \longleftrightarrow \lambda_1, \lambda_2, \theta$$

$$\text{Jacobian Matrix} = \begin{vmatrix} dp/d\theta & dp/d\lambda_1 & dp/d\lambda_2 \\ dr/d\theta & dr/d\lambda_1 & dr/d\lambda_2 \\ ds/d\theta & ds/d\lambda_1 & ds/d\lambda_2 \end{vmatrix}$$

$$p = \lambda_1 \cos^2 \theta + \lambda_2 \sin^2 \theta$$

$$r = \lambda_2 \cos^2 \theta + \lambda_1 \sin^2 \theta$$

etc

$$\det J = \lambda_1 - \lambda_2$$

$$\frac{1}{\sqrt{2\pi}} \frac{1}{\sqrt{\pi}} \frac{1}{\sqrt{\pi}} e^{-\frac{1}{2}(p^2 + r^2 + s^2)} dp dr ds = \frac{1}{\sqrt{2\pi}^3} |\lambda_1 - \lambda_2| e^{-\frac{1}{2}(\lambda_1^2 + \lambda_2^2)} d\lambda_1 d\lambda_2 d\theta$$

can integrate out $d\theta$

$$\frac{1}{\sqrt{2\pi}^3} |\lambda_1 - \lambda_2| e^{-\frac{1}{2}(\lambda_1^2 + \lambda_2^2)}$$

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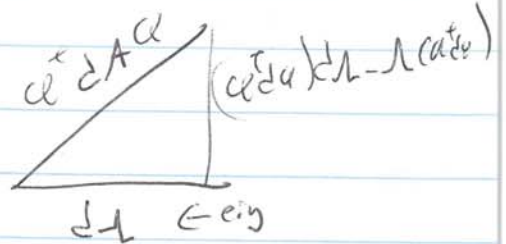
$$Q = \begin{bmatrix} \cos \sigma & -\sin \sigma \\ \sin \sigma & \cos \sigma \end{bmatrix}$$



$$dQ = \begin{bmatrix} -\sin \sigma & -\cos \sigma \\ \cos \sigma & -\sin \sigma \end{bmatrix} d\sigma$$

$$Q^T dQ = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} d\sigma$$

$$Q^T Q = I$$



$$dQ^T Q + Q^T dQ = 0$$

$$Q^T dQ = -(Q^T dQ)^T$$

Wielant-Hoffmann
 $\|dA\|_F = \pi \left\| \frac{dL}{d\sigma} \right\|_F$

$$A = Q^T L Q$$

$$dA = dQ^T L Q + Q^T dL Q + Q^T L dQ^T$$

$$Q^T dA Q = dL + Q^T dQ L - L Q^T dQ$$

$$d\text{diag} = d\lambda_i$$

$$\text{off-diag} = \frac{Q_{ij}^T dL_j}{\lambda_j} (\lambda_j - \lambda_i)$$

$$\prod_{i \neq j} |\lambda_i - \lambda_j|$$

$$\frac{\partial (Q^T dA Q)}{\partial \lambda_i} = 1$$

$$\frac{\partial (Q^T dA Q)}{\partial (Q^T dQ)_{ij}} = \lambda_j - \lambda_i$$